This manual describes how to install and use the GNU multiple precision arithmetic library, version 6.2.0.


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Programs which are not part of the library itself, such as demonstration programs and the GMP testsuite, are licensed under the terms of the GNU General Public License version 3 (see COPYINGv3), or any later version.
1 Introduction to GNU MP

GNU MP is a portable library written in C for arbitrary precision arithmetic on integers, rational numbers, and floating-point numbers. It aims to provide the fastest possible arithmetic for all applications that need higher precision than is directly supported by the basic C types.

Many applications use just a few hundred bits of precision; but some applications may need thousands or even millions of bits. GMP is designed to give good performance for both, by choosing algorithms based on the sizes of the operands, and by carefully keeping the overhead at a minimum.

The speed of GMP is achieved by using fullwords as the basic arithmetic type, by using sophisticated algorithms, by including carefully optimized assembly code for the most common inner loops for many different CPUs, and by a general emphasis on speed (as opposed to simplicity or elegance).

There is assembly code for these CPUs: ARM Cortex-A9, Cortex-A15, and generic ARM, DEC Alpha 21064, 21164, and 21264, AMD K8 and K10 (sold under many brands, e.g. Athlon64, Phenom, Opteron) Bulldozer, and Bobcat, Intel Pentium, Pentium Pro/II/III, Pentium 4, Core2, Nehalem, Sandy bridge, Haswell, generic x86, Intel IA-64, Motorola/IBM PowerPC 32 and 64 such as POWER970, POWER5, POWER6, and POWER7, MIPS 32-bit and 64-bit, SPARC 32-bit ad 64-bit with special support for all UltraSPARC models. There is also assembly code for many obsolete CPUs.

For up-to-date information on GMP, please see the GMP web pages at

https://gmplib.org/

The latest version of the library is available at


Many sites around the world mirror ‘ftp.gnu.org’, please use a mirror near you, see https://www.gnu.org/order/ftp.html for a full list.

There are three public mailing lists of interest. One for release announcements, one for general questions and discussions about usage of the GMP library and one for bug reports. For more information, see

https://gmplib.org/mailman/listinfo/.

The proper place for bug reports is gmp-bugs@gmplib.org. See Chapter 4 [Reporting Bugs], page 29 for information about reporting bugs.

1.1 How to use this Manual

Everyone should read Chapter 3 [GMP Basics], page 17. If you need to install the library yourself, then read Chapter 2 [Installing GMP], page 3. If you have a system with multiple ABIs, then read Section 2.2 [ABI and ISA], page 8, for the compiler options that must be used on applications.

The rest of the manual can be used for later reference, although it is probably a good idea to glance through it.
2 Installing GMP

GMP has an autoconf/automake/libtool based configuration system. On a Unix-like system a basic build can be done with

```
./configure
make
```

Some self-tests can be run with

```
make check
```

And you can install (under /usr/local by default) with

```
make install
```

If you experience problems, please report them to gmp-bugs@gmplib.org. See Chapter 4 [Reporting Bugs], page 29, for information on what to include in useful bug reports.

2.1 Build Options

All the usual autoconf configure options are available, run `./configure --help` for a summary. The file INSTALL.autoconf has some generic installation information too.

Tools

`configure` requires various Unix-like tools. See Section 2.4 [Notes for Particular Systems], page 12, for some options on non-Unix systems.

It might be possible to build without the help of `configure`, certainly all the code is there, but unfortunately you’ll be on your own.

Build Directory

To compile in a separate build directory, cd to that directory, and prefix the configure command with the path to the GMP source directory. For example

```
cd /my/build/dir
/my/sources/gmp-6.2.0/configure
```

Not all `make` programs have the necessary features (VPATH) to support this. In particular, SunOS and Slowaris `make` have bugs that make them unable to build in a separate directory. Use GNU `make` instead.

`--prefix` and `--exec-prefix`

The `--prefix` option can be used in the normal way to direct GMP to install under a particular tree. The default is `/usr/local`.

`--exec-prefix` can be used to direct architecture-dependent files like `libgmp.a` to a different location. This can be used to share architecture-independent parts like the documentation, but separate the dependent parts. Note however that `gmp.h` is architecture-dependent since it encodes certain aspects of `libgmp`, so it will be necessary to ensure both `$prefix/include` and `$exec_prefix/include` are available to the compiler.

`--disable-shared`, `--disable-static`

By default both shared and static libraries are built (where possible), but one or other can be disabled. Shared libraries result in smaller executables and permit code sharing between separate running processes, but on some CPUs are slightly slower, having a small cost on each function call.

Native Compilation, `--build=CPU-VENDOR-OS`

For normal native compilation, the system can be specified with `--build`. By default `./configure` uses the output from running `./config.guess`. On some
systems ‘./config.guess’ can determine the exact CPU type, on others it will be necessary to give it explicitly. For example,

```
./configure --build=ultrasparsc-sun-solaris2.7
```

In all cases the ‘OS’ part is important, since it controls how libtool generates shared libraries. Running ‘./config.guess’ is the simplest way to see what it should be, if you don’t know already.

Cross Compilation, --host=CPU-VENDOR-OS

When cross-compiling, the system used for compiling is given by ‘--build’ and the system where the library will run is given by ‘--host’. For example when using a FreeBSD Athlon system to build GNU/Linux m68k binaries,

```
./configure --build=athlon-pc-freebsd3.5 --host=m68k-mac-linux-gnu
```

Compiler tools are sought first with the host system type as a prefix. For example m68k-mac-linux-gnu-ranlib is tried, then plain ranlib. This makes it possible for a set of cross-compiling tools to co-exist with native tools. The prefix is the argument to ‘--host’, and this can be an alias, such as ‘m68k-linux’. But note that tools don’t have to be setup this way, it’s enough to just have a PATH with a suitable cross-compiling cc etc.

Compiling for a different CPU in the same family as the build system is a form of cross-compilation, though very possibly this would merely be special options on a native compiler. In any case ‘./configure’ avoids depending on being able to run code on the build system, which is important when creating binaries for a newer CPU since they very possibly won’t run on the build system.

In all cases the compiler must be able to produce an executable (of whatever format) from a standard C main. Although only object files will go to make up libgmp, ‘./configure’ uses linking tests for various purposes, such as determining what functions are available on the host system.

Currently a warning is given unless an explicit ‘--build’ is used when cross-compiling, because it may not be possible to correctly guess the build system type if the PATH has only a cross-compiling cc.

Note that the ‘--target’ option is not appropriate for GMP. It’s for use when building compiler tools, with ‘--host’ being where they will run, and ‘--target’ what they’ll produce code for. Ordinary programs or libraries like GMP are only interested in the ‘--host’ part, being where they’ll run. (Some past versions of GMP used ‘--target’ incorrectly.)

CPU types

In general, if you want a library that runs as fast as possible, you should configure GMP for the exact CPU type your system uses. However, this may mean the binaries won’t run on older members of the family, and might run slower on other members, older or newer. The best idea is always to build GMP for the exact machine type you intend to run it on.

The following CPUs have specific support. See configure.ac for details of what code and compiler options they select.

- Cray: ‘c90’, ‘j90’, ‘t90’, ‘sv1’
- HPPA: ‘hppa1.0’, ‘hppa1.1’, ‘hppa2.0’, ‘hppa2.0n’, ‘hppa2.0w’, ‘hppa64’
- IA-64: ‘ia64’, ‘itanium’, ‘itanium2’
- MIPS: ‘mips’, ‘mips3’, ‘mips64’
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- Motorola: ‘m68k’, ‘m68000’, ‘m68010’, ‘m68020’, ‘m68030’, ‘m68040’, ‘m68060’, ‘m68302’, ‘m68360’, ‘m88k’, ‘m88110’
- POWER: ‘power’, ‘power1’, ‘power2’, ‘power2sc’
- Other: ‘arm’, ‘sh’, ‘sh2’, ‘vax’

CPUs not listed will use generic C code.

Generic C Build

If some of the assembly code causes problems, or if otherwise desired, the generic C code can be selected with the configure --disable-assembly.

Note that this will run quite slowly, but it should be portable and should at least make it possible to get something running if all else fails.

Fat binary, --enable-fat

Using --enable-fat selects a “fat binary” build on x86, where optimized low level subroutines are chosen at runtime according to the CPU detected. This means more code, but gives good performance on all x86 chips. (This option might become available for more architectures in the future.)

ABI

On some systems GMP supports multiple ABIs (application binary interfaces), meaning data type sizes and calling conventions. By default GMP chooses the best ABI available, but a particular ABI can be selected. For example

./configure --host=mips64-sgi-irix6 ABI=n32

See Section 2.2 [ABI and ISA], page 8, for the available choices on relevant CPUs, and what applications need to do.

CC, CFLAGS

By default the C compiler used is chosen from among some likely candidates, with gcc normally preferred if it’s present. The usual ‘CC=whatever’ can be passed to ‘./configure’ to choose something different.

For various systems, default compiler flags are set based on the CPU and compiler. The usual ‘CFLAGS=-whatever’ can be passed to ‘./configure’ to use something different or to set good flags for systems GMP doesn’t otherwise know.

The ‘CC’ and ‘CFLAGS’ used are printed during ‘./configure’, and can be found in each generated Makefile. This is the easiest way to check the defaults when considering changing or adding something.

Note that when ‘CC’ and ‘CFLAGS’ are specified on a system supporting multiple ABIs it’s important to give an explicit ‘ABI=whatever’, since GMP can’t determine the ABI just from the flags and won’t be able to select the correct assembly code.

If just ‘CC’ is selected then normal default ‘CFLAGS’ for that compiler will be used (if GMP recognises it). For example ‘CC=gcc’ can be used to force the use of GCC, with default flags (and default ABI).
CPPFLAGS  Any flags like ‘-D’ defines or ‘-I’ includes required by the preprocessor should be set in ‘CPPFLAGS’ rather than ‘CFLAGS’. Compiling is done with both ‘CPPFLAGS’ and ‘CFLAGS’, but preprocessing uses just ‘CPPFLAGS’. This distinction is because most preprocessors won’t accept all the flags the compiler does. Preprocessing is done separately in some configure tests.

CC_FOR_BUILD  Some build-time programs are compiled and run to generate host-specific data tables. ‘CC_FOR_BUILD’ is the compiler used for this. It doesn’t need to be in any particular ABI or mode, it merely needs to generate executables that can run. The default is to try the selected ‘CC’ and some likely candidates such as ‘cc’ and ‘gcc’, looking for something that works.

No flags are used with ‘CC_FOR_BUILD’ because a simple invocation like ‘cc foo.c’ should be enough. If some particular options are required they can be included as for instance ‘CC_FOR_BUILD="cc -whatever"’.

C++ Support, --enable-cxx  
C++ support in GMP can be enabled with ‘--enable-cxx’, in which case a C++ compiler will be required. As a convenience ‘--enable-cxx=detect’ can be used to enable C++ support only if a compiler can be found. The C++ support consists of a library libgmpxx.la and header file gmpxx.h (see Section 3.1 [Headers and Libraries], page 17).

A separate libgmpxx.la has been adopted rather than having C++ objects within libgmp.la in order to ensure dynamic linked C programs aren’t bloated by a dependency on the C++ standard library, and to avoid any chance that the C++ compiler could be required when linking plain C programs.

libgmpxx.la will use certain internals from libgmp.la and can only be expected to work with libgmp.la from the same GMP version. Future changes to the relevant internals will be accompanied by renaming, so a mismatch will cause unresolved symbols rather than perhaps mysterious misbehaviour.

In general libgmpxx.la will be usable only with the C++ compiler that built it, since name mangling and runtime support are usually incompatible between different compilers.

CXX, CXXFLAGS  
When C++ support is enabled, the C++ compiler and its flags can be set with variables ‘CXX’ and ‘CXXFLAGS’ in the usual way. The default for ‘CXX’ is the first compiler that works from a list of likely candidates, with g++ normally preferred when available. The default for ‘CXXFLAGS’ is to try ‘CFLAGS’, ‘CFLAGS’ without ‘-g’, then for g++ either ‘-g -O2’ or ‘-O2’, or for other compilers ‘-g’ or nothing. Trying ‘CFLAGS’ this way is convenient when using ‘gcc’ and ‘g++’ together, since the flags for ‘gcc’ will usually suit ‘g++’.

It’s important that the C and C++ compilers match, meaning their startup and runtime support routines are compatible and that they generate code in the same ABI (if there’s a choice of ABIs on the system). ‘./configure’ isn’t currently able to check these things very well itself, so for that reason ‘--disable-cxx’ is the default, to avoid a build failure due to a compiler mismatch. Perhaps this will change in the future.

Incidentally, it’s normally not good enough to set ‘CXX’ to the same as ‘CC’. Although gcc for instance recognises foo.cc as C++ code, only g++ will invoke the linker the right way when building an executable or shared library from C++ object files.
Temporary Memory, \texttt{--enable-alloca=<choice>}

GMP allocates temporary workspace using one of the following three methods, which can be selected with for instance \texttt{--enable-alloca=malloc-reentrant}.

- \texttt{alloca} - C library or compiler builtin.
- \texttt{malloc-reentrant} - the heap, in a re-entrant fashion.
- \texttt{malloc-notreentrant} - the heap, with global variables.

For convenience, the following choices are also available. \texttt{--disable-alloca} is the same as \texttt{no}.

- \texttt{yes} - a synonym for \texttt{alloca}.
- \texttt{no} - a synonym for \texttt{malloc-reentrant}.
- \texttt{reentrant} - \texttt{alloca} if available, otherwise \texttt{malloc-reentrant}. This is the default.
- \texttt{notreentrant} - \texttt{alloca} if available, otherwise \texttt{malloc-notreentrant}.

\texttt{alloca} is reentrant and fast, and is recommended. It actually allocates just small blocks on the stack; larger ones use malloc-reentrant.

\texttt{malloc-reentrant} is, as the name suggests, reentrant and thread safe, but \texttt{malloc-notreentrant} is faster and should be used if reentrancy is not required.

The two malloc methods in fact use the memory allocation functions selected by \texttt{mp_set_memory_functions}, these being \texttt{malloc} and friends by default. See Chapter 13 [Custom Allocation], page 90.

An additional choice \texttt{--enable-alloca=debug} is available, to help when debugging memory related problems (see Section 3.12 [Debugging], page 24).

FFT Multiplication, \texttt{--disable-fft}

By default multiplications are done using Karatsuba, 3-way Toom, higher degree Toom, and Fermat FFT. The FFT is only used on large to very large operands and can be disabled to save code size if desired.

Assertion Checking, \texttt{--enable-assert}

This option enables some consistency checking within the library. This can be of use while debugging, see Section 3.12 [Debugging], page 24.

Execution Profiling, \texttt{--enable-profiling=prof/gprof/instrument}

Enable profiling support, in one of various styles, see Section 3.13 [Profiling], page 26.

\texttt{MPN_PATH}

Various assembly versions of each mpn subroutines are provided. For a given CPU, a search is made though a path to choose a version of each. For example \texttt{sparcv8} has

\texttt{MPN_PATH="sparc32/v8 sparc32 generic"}

which means look first for v8 code, then plain sparc32 (which is v7), and finally fall back on generic C. Knowledgeable users with special requirements can specify a different path. Normally this is completely unnecessary.

Documentation

The source for the document you’re now reading is \texttt{doc/gmp.texi}, in Texinfo format, see \texttt{Texinfo}.

Info format \texttt{doc/gmp.info} is included in the distribution. The usual automake targets are available to make PostScript, DVI, PDF and HTML (these will require various \TeX\ and Texinfo tools).

DocBook and XML can be generated by the Texinfo \texttt{makeinfo} program too, see Section “Options for \texttt{makeinfo}” in \texttt{Texinfo}.

Some supplementary notes can also be found in the \texttt{doc} subdirectory.
2.2 ABI and ISA

ABI (Application Binary Interface) refers to the calling conventions between functions, meaning what registers are used and what sizes the various C data types are. ISA (Instruction Set Architecture) refers to the instructions and registers a CPU has available.

Some 64-bit ISA CPUs have both a 64-bit ABI and a 32-bit ABI defined, the latter for compatibility with older CPUs in the family. GMP supports some CPUs like this in both ABIs. In fact within GMP ‘ABI’ means a combination of chip ABI, plus how GMP chooses to use it. For example in some 32-bit ABIs, GMP may support a limb as either a 32-bit \texttt{long} or a 64-bit \texttt{long long}.

By default GMP chooses the best ABI available for a given system, and this generally gives significantly greater speed. But an ABI can be chosen explicitly to make GMP compatible with other libraries, or particular application requirements. For example,

```
./configure ABI=32
```

In all cases it’s vital that all object code used in a given program is compiled for the same ABI.

Usually a limb is implemented as a \texttt{long}. When a \texttt{long long} limb is used this is encoded in the generated \texttt{gmp.h}. This is convenient for applications, but it does mean that \texttt{gmp.h} will vary, and can’t be just copied around. \texttt{gmp.h} remains compiler independent though, since all compilers for a particular ABI will be expected to use the same limb type.

Currently no attempt is made to follow whatever conventions a system has for installing library or header files built for a particular ABI. This will probably only matter when installing multiple builds of GMP, and it might be as simple as configuring with a special ‘\texttt{libdir}’, or it might require more than that. Note that builds for different ABIs need to done separately, with a fresh \texttt{./configure} and \texttt{make} each.

AMD64 (‘x86_64’)

On AMD64 systems supporting both 32-bit and 64-bit modes for applications, the following ABI choices are available.

‘ABI=64’ The 64-bit ABI uses 64-bit limbs and pointers and makes full use of the chip architecture. This is the default. Applications will usually not need special compiler flags, but for reference the option is

```
gcc -m64
```

‘ABI=32’ The 32-bit ABI is the usual i386 conventions. This will be slower, and is not recommended except for inter-operating with other code not yet 64-bit capable. Applications must be compiled with

```
gcc -m32
```

(In GCC 2.95 and earlier there’s no ‘-m32’ option, it’s the only mode.)

‘ABI=x32’ The x32 ABI uses 64-bit limbs but 32-bit pointers. Like the 64-bit ABI, it makes full use of the chip’s arithmetic capabilities. This ABI is not supported by all operating systems.

```
gcc -mx32
```
HPPA 2.0 (‘hppa2.0’, ‘hppa64’)

‘ABI=2.0w’

The 2.0w ABI uses 64-bit limbs and pointers and is available on HP-UX 11 or up. Applications must be compiled with

```
gcc [built for 2.0w]
cc +DD64
```

‘ABI=2.0n’

The 2.0n ABI means the 32-bit HPPA 1.0 ABI and all its normal calling conventions, but with 64-bit instructions permitted within functions. GMP uses a 64-bit long long for a limb. This ABI is available on hppa64 GNU/Linux and on HP-UX 10 or higher. Applications must be compiled with

```
gcc [built for 2.0n]
cc +DA2.0 +e
```

Note that current versions of GCC (eg. 3.2) don’t generate 64-bit instructions for long long operations and so may be slower than for 2.0w. (The GMP assembly code is the same though.)

‘ABI=1.0’

HPPA 2.0 CPUs can run all HPPA 1.0 and 1.1 code in the 32-bit HPPA 1.0 ABI. No special compiler options are needed for applications.

All three ABIs are available for CPU types ‘hppa2.0w’, ‘hppa2.0’ and ‘hppa64’, but for CPU type ‘hppa2.0n’ only 2.0n or 1.0 are considered.

Note that GCC on HP-UX has no options to choose between 2.0n and 2.0w modes, unlike HP cc. Instead it must be built for one or the other ABI. GMP will detect how it was built, and skip to the corresponding ‘ABI’.

IA-64 under HP-UX (‘ia64*-*-hpux’, ‘itanium*-*-hpux’)

HP-UX supports two ABIs for IA-64. GMP performance is the same in both.

‘ABI=32’

In the 32-bit ABI, pointers, ints and longs are 32 bits and GMP uses a 64 bit long long for a limb. Applications can be compiled without any special flags since this ABI is the default in both HP C and GCC, but for reference the flags are

```
gcc -milp32
cc +DD32
```

‘ABI=64’

In the 64-bit ABI, longs and pointers are 64 bits and GMP uses a long for a limb. Applications must be compiled with

```
gcc -mlp64
cc +DD64
```

On other IA-64 systems, GNU/Linux for instance, ‘ABI=64’ is the only choice.

MIPS under IRIX 6 (‘mips*-*-irix[6789]’)

IRIX 6 always has a 64-bit MIPS 3 or better CPU, and supports ABIs o32, n32, and 64. n32 or 64 are recommended, and GMP performance will be the same in each. The default is n32.

‘ABI=o32’

The o32 ABI is 32-bit pointers and integers, and no 64-bit operations. GMP will be slower than in n32 or 64, this option only exists to support old compilers, eg. GCC 2.7.2. Applications can be compiled with no special flags on an old compiler, or on a newer compiler with
The n32 ABI is 32-bit pointers and integers, but with a 64-bit limb using a \texttt{long long}. Applications must be compiled with
\begin{verbatim}
gcc -mabi=n32
cc -n32
\end{verbatim}

The 64-bit ABI is 64-bit pointers and integers. Applications must be compiled with
\begin{verbatim}
gcc -mabi=64
cc -64
\end{verbatim}

Note that MIPS GNU/Linux, as of kernel version 2.2, doesn’t have the necessary support for n32 or 64 and so only gets a 32-bit limb and the MIPS 2 code.

PowerPC 64 (’powerpc64’, ’powerpc620’, ’powerpc630’, ’powerpc970’, ’power4’, ’power5’)

The AIX 64 ABI uses 64-bit limbs and pointers and is the default on PowerPC 64 ‘*-*-aix*’ systems. Applications must be compiled with
\begin{verbatim}
gcc -maix64
xlc -q64
\end{verbatim}

On 64-bit GNU/Linux, BSD, and Mac OS X/Darwin systems, the applications must be compiled with
\begin{verbatim}
gcc -m64
\end{verbatim}

The ’mode32’ ABI uses a 64-bit \texttt{long long} limb but with the chip still in 32-bit mode and using 32-bit calling conventions. This is the default for systems where the true 64-bit ABI is unavailable. No special compiler options are typically needed for applications. This ABI is not available under AIX.

This is the basic 32-bit PowerPC ABI, with a 32-bit limb. No special compiler options are needed for applications.

GMP’s speed is greatest for the ’mode64’ ABI, the ’mode32’ ABI is 2nd best. In ’ABI=32’ only the 32-bit ISA is used and this doesn’t make full use of a 64-bit chip.

Sparc V9 (’sparc64’, ’sparcv9’, ’ultrasparc’)

The 64-bit V9 ABI is available on the various BSD sparc64 ports, recent versions of Sparc64 GNU/Linux, and Solaris 2.7 and up (when the kernel is in 64-bit mode). GCC 3.2 or higher, or Sun cc is required. On GNU/Linux, depending on the default gcc mode, applications must be compiled with
\begin{verbatim}
gcc -m64
\end{verbatim}

On Solaris applications must be compiled with
\begin{verbatim}
gcc -m64 -mptr64 -Wa,-xarch=v9 -mcpu=v9
cc -xarch=v9
\end{verbatim}

On the BSD sparc64 systems no special options are required, since 64-bits is the only ABI available.

For the basic 32-bit ABI, GMP still uses as much of the V9 ISA as it can. In the Sun documentation this combination is known as “v8plus”.

\begin{verbatim}
gcc -mabi=32
cc -32
\end{verbatim}

\texttt{ABI=n32}
On GNU/Linux, depending on the default gcc mode, applications may need to be compiled with

```
gcc -m32
```

On Solaris, no special compiler options are required for applications, though using something like the following is recommended. (gcc 2.8 and earlier only support ‘-mv8’ though.)

```
gcc -mv8plus
cc -xarch=v8plus
```

GMP speed is greatest in ‘ABI=64’, so it’s the default where available. The speed is partly because there are extra registers available and partly because 64-bits is considered the more important case and has therefore had better code written for it.

Don’t be confused by the names of the ‘-m’ and ‘-x’ compiler options, they’re called ‘arch’ but effectively control both ABI and ISA.

On Solaris 2.6 and earlier, only ‘ABI=32’ is available since the kernel doesn’t save all registers.

On Solaris 2.7 with the kernel in 32-bit mode, a normal native build will reject ‘ABI=64’ because the resulting executables won’t run. ‘ABI=64’ can still be built if desired by making it look like a cross-compile, for example

```
./configure --build=none --host=sparcv9-sun-solaris2.7 ABI=64
```

### 2.3 Notes for Package Builds

GMP should present no great difficulties for packaging in a binary distribution.

Libtool is used to build the library and ‘-version-info’ is set appropriately, having started from ‘3:0:0’ in GMP 3.0 (see Section “Library interface versions” in GNU Libtool).

The GMP 4 series will be upwardly binary compatible in each release and will be upwardly binary compatible with all of the GMP 3 series. Additional function interfaces may be added in each release, so on systems where libtool versioning is not fully checked by the loader an auxiliary mechanism may be needed to express that a dynamic linked application depends on a new enough GMP.

An auxiliary mechanism may also be needed to express that libgmpxx.la (from `--enable-cxx`, see Section 2.1 [Build Options], page 3) requires libgmp.la from the same GMP version, since this is not done by the libtool versioning, nor otherwise. A mismatch will result in unresolved symbols from the linker, or perhaps the loader.

When building a package for a CPU family, care should be taken to use ‘--host’ (or ‘--build’) to choose the least common denominator among the CPUs which might use the package. For example this might mean plain ‘sparc’ (meaning V7) for SPARCs.

For x86s, `--enable-fat` sets things up for a fat binary build, making a runtime selection of optimized low level routines. This is a good choice for packaging to run on a range of x86 chips.

Users who care about speed will want GMP built for their exact CPU type, to make best use of the available optimizations. Providing a way to suitably rebuild a package may be useful. This could be as simple as making it possible for a user to omit ‘--build’ (and ‘--host’) so ‘./config.guess’ will detect the CPU. But a way to manually specify a ‘--build’ will be wanted for systems where ‘./config.guess’ is inexact.

On systems with multiple ABIs, a packaged build will need to decide which among the choices is to be provided, see Section 2.2 [ABI and ISA], page 8. A given run of ‘./configure’ etc will
only build one ABI. If a second ABI is also required then a second run of ‘./configure’ etc must be made, starting from a clean directory tree (‘make distclean’).

As noted under “ABI and ISA”, currently no attempt is made to follow system conventions for install locations that vary with ABI, such as /usr/lib/sparcv9 for ‘ABI=64’ as opposed to /usr/lib for ‘ABI=32’. A package build can override ‘libdir’ and other standard variables as necessary.

Note that gmp.h is a generated file, and will be architecture and ABI dependent. When attempting to install two ABIs simultaneously it will be important that an application compile gets the correct gmp.h for its desired ABI. If compiler include paths don’t vary with ABI options then it might be necessary to create a /usr/include/gmp.h which tests preprocessor symbols and chooses the correct actual gmp.h.

2.4 Notes for Particular Systems

AIX 3 and 4
On systems ‘*-aix[34]’ shared libraries are disabled by default, since some versions of the native ar fail on the convenience libraries used. A shared build can be attempted with

```
./configure --enable-shared --disable-static
```

Note that the ‘--disable-static’ is necessary because in a shared build libtool makes libgmp.a a symlink to libgmp.so, apparently for the benefit of old versions of ld which only recognise .a, but unfortunately this is done even if a fully functional ld is available.

ARM
On systems ‘arm*-’, versions of GCC up to and including 2.95.3 have a bug in unsigned division, giving wrong results for some operands. GMP ‘./configure’ will demand GCC 2.95.4 or later.

Compaq C++
Compaq C++ on OSF 5.1 has two flavours of iostream, a standard one and an old pre-standard one (see ‘man iostream_intro’). GMP can only use the standard one, which unfortunately is not the default but must be selected by defining __USE_STD_IOSTREAM. Configure with for instance

```
./configure --enable-cxx CPPFLAGS=-D__USE_STD_IOSTREAM
```

Floating Point Mode
On some systems, the hardware floating point has a control mode which can set all operations to be done in a particular precision, for instance single, double or extended on x86 systems (x87 floating point). The GMP functions involving a double cannot be expected to operate to their full precision when the hardware is in single precision mode. Of course this affects all code, including application code, not just GMP.

FreeBSD 7.x, 8.x, 9.0, 9.1, 9.2
m4 in these releases of FreeBSD has an eval function which ignores its 2nd and 3rd arguments, which makes it unsuitable for .asm file processing. ‘./configure’ will detect the problem and either abort or choose another m4 in the PATH. The bug is fixed in FreeBSD 9.3 and 10.0, so either upgrade or use GNU m4. Note that the FreeBSD package system installs GNU m4 under the name ‘gm4’, which GMP cannot guess.

FreeBSD 7.x, 8.x, 9.x
GMP releases starting with 6.0 do not support ‘ABI=32’ on FreeBSD/amd64 prior to release 10.0 of the system. The cause is a broken limits.h, which GMP no longer works around.
Chapter 2: Installing GMP

MS-DOS and MS Windows

On an MS-DOS system DJGPP can be used to build GMP, and on an MS Windows system Cygwin, DJGPP and MINGW can be used. All three are excellent ports of GCC and the various GNU tools.

https://www.cygwin.com/
http://www.delorie.com/djgpp/
http://www.mingw.org/

Microsoft also publishes an Interix “Services for Unix” which can be used to build GMP on Windows (with a normal './configure'), but it’s not free software.

MS Windows DLLs

On systems ‘*-cygwin*’, ‘*-mingw*’ and ‘*-pw32*’ by default GMP builds only a static library, but a DLL can be built instead using

./configure --disable-static --enable-shared

Static and DLL libraries can’t both be built, since certain export directives in gmp.h must be different.

A MINGW DLL build of GMP can be used with Microsoft C. Libtool doesn’t install a .lib format import library, but it can be created with MS lib as follows, and copied to the install directory. Similarly for libmp and libgmpxx.

cd .libs
lib /def:libgmp-3.dll.def /out:libgmp-3.lib

MINGW uses the C runtime library ‘msvcrt.dll’ for I/O, so applications wanting to use the GMP I/O routines must be compiled with ‘cl /MD’ to do the same. If one of the other C runtime library choices provided by MS C is desired then the suggestion is to use the GMP string functions and confine I/O to the application.

Motorola 68k CPU Types

‘m68k’ is taken to mean 68000. ‘m68020’ or higher will give a performance boost on applicable CPUs. ‘m68360’ can be used for CPU32 series chips. ‘m68302’ can be used for “Dragonball” series chips, though this is merely a synonym for ‘m68000’.

NetBSD 5.x

m4 in these releases of NetBSD has an eval function which ignores its 2nd and 3rd arguments, which makes it unsuitable for .asm file processing. './configure' will detect the problem and either abort or choose another m4 in the PATH. The bug is fixed in NetBSD 6, so either upgrade or use GNU m4. Note that the NetBSD package system installs GNU m4 under the name ‘gm4’, which GMP cannot guess.

OpenBSD 2.6

m4 in this release of OpenBSD has a bug in eval that makes it unsuitable for .asm file processing. './configure' will detect the problem and either abort or choose another m4 in the PATH. The bug is fixed in OpenBSD 2.7, so either upgrade or use GNU m4.

Power CPU Types

In GMP, CPU types ‘power*’ and ‘powerpc*’ will each use instructions not available on the other, so it’s important to choose the right one for the CPU that will be used. Currently GMP has no assembly code support for using just the common instruction subset. To get executables that run on both, the current suggestion is to use the generic C code (--disable-assembly), possibly with appropriate compiler options (like ‘-mcpu=common’ for gcc). CPU ‘rs6000’ (which is not a CPU but a family of workstations) is accepted by config.sub, but is currently equivalent to --disable-assembly.
Sparc CPU Types

‘sparcv8’ or ‘supersparc’ on relevant systems will give a significant performance increase over the V7 code selected by plain ‘sparc’.

Sparc App Regs

The GMP assembly code for both 32-bit and 64-bit Sparc clobbers the “application registers” g2, g3 and g4, the same way that the GCC default ‘-mapp-regs’ does (see Section “SPARC Options” in Using the GNU Compiler Collection (GCC)). This makes that code unsuitable for use with the special V9 ‘-mcmmodel=embmedany’ (which uses g4 as a data segment pointer), and for applications wanting to use those registers for special purposes. In these cases the only suggestion currently is to build GMP with --disable-assembly to avoid the assembly code.

SunOS 4

/usr/bin/m4 lacks various features needed to process .asm files, and instead ‘./configure’ will automatically use /usr/5bin/m4, which we believe is always available (if not then use GNU m4).

x86 CPU Types

‘i586’, ‘pentium’ or ‘pentiummmx’ code is good for its intended P5 Pentium chips, but quite slow when run on Intel P6 class chips (PPro, P-II, P-III). ‘i386’ is a better choice when making binaries that must run on both.

x86 MMX and SSE2 Code

If the CPU selected has MMX code but the assembler doesn’t support it, a warning is given and non-MMX code is used instead. This will be an inferior build, since the MMX code that’s present is there because it’s faster than the corresponding plain integer code. The same applies to SSE2.

Old versions of ‘gas’ don’t support MMX instructions, in particular version 1.92.3 that comes with FreeBSD 2.2.8 or the more recent OpenBSD 3.1 doesn’t.

Solaris 2.6 and 2.7 as generate incorrect object code for register to register movq instructions, and so can’t be used for MMX code. Install a recent gas if MMX code is wanted on these systems.

2.5 Known Build Problems

You might find more up-to-date information at https://gmplib.org/.

Compiler link options

The version of libtool currently in use rather aggressively strips compiler options when linking a shared library. This will hopefully be relaxed in the future, but for now if this is a problem the suggestion is to create a little script to hide them, and for instance configure with

./configure CC=gcc-with-my-options

DJGPP (‘*-*msdosdjgpp’)

The DJGPP port of bash 2.03 is unable to run the ‘configure’ script, it exits silently, having died writing a preamble to config.log. Use bash 2.04 or higher.

‘make all’ was found to run out of memory during the final libgmp.la link on one system tested, despite having 64Mb available. Running ‘make libgmp.la’ directly helped, perhaps recursing into the various subdirectories uses up memory.

GNU binutils strip prior to 2.12

strip from GNU binutils 2.11 and earlier should not be used on the static libraries libgmp.a and libmp.a since it will discard all but the last of multiple archive members with the same name, like the three versions of init.o in libgmp.a. Binutils 2.12 or higher can be used successfully.
The shared libraries `libgmp.so` and `libmp.so` are not affected by this and any version of `strip` can be used on them.

**make** syntax error

On certain versions of SCO OpenServer 5 and IRIX 6.5 the native `make` is unable to handle the long dependencies list for `libgmp.la`. The symptom is a “syntax error” on the following line of the top-level `Makefile`.

```
libgmp.la: $(libgmp_la_OBJECTS) $(libgmp_la_DEPENDENCIES)
```

Either use GNU Make, or as a workaround remove `$(libgmp_la_DEPENDENCIES)` from that line (which will make the initial build work, but if any recompiling is done `libgmp.la` might not be rebuilt).

MacOS X (**--*-darwin*')

Libtool currently only knows how to create shared libraries on MacOS X using the native `cc` (which is a modified GCC), not a plain GCC. A static-only build should work though (**--disable-shared**).

NeXT prior to 3.3

The system compiler on old versions of NeXT was a massacred and old GCC, even if it called itself `cc`. This compiler cannot be used to build GMP, you need to get a real GCC, and install that. (NeXT may have fixed this in release 3.3 of their system.)

POWER and PowerPC

Bugs in GCC 2.7.2 (and 2.6.3) mean it can’t be used to compile GMP on POWER or PowerPC. If you want to use GCC for these machines, get GCC 2.7.2.1 (or later).

Sequent Symmetry

Use the GNU assembler instead of the system assembler, since the latter has serious bugs.

Solaris 2.6

The system `sed` prints an error “Output line too long” when libtool builds `libgmp.la`. This doesn’t seem to cause any obvious ill effects, but GNU `sed` is recommended, to avoid any doubt.

Sparc Solaris 2.7 with gcc 2.95.2 in `ABI=32`

A shared library build of GMP seems to fail in this combination, it builds but then fails the tests, apparently due to some incorrect data relocations within `gmp_randinit_lc_2exp_size`. The exact cause is unknown, `--disable-shared` is recommended.

### 2.6 Performance optimization

For optimal performance, build GMP for the exact CPU type of the target computer, see Section 2.1 [Build Options], page 3.

Unlike what is the case for most other programs, the compiler typically doesn’t matter much, since GMP uses assembly language for the most critical operation.

In particular for long-running GMP applications, and applications demanding extremely large numbers, building and running the `tuneup` program in the `tune` subdirectory, can be important. For example,

```
cd tune
make tuneup
./tuneup
```

will generate better contents for the `gmp-mparam.h` parameter file.
To use the results, put the output in the file indicated in the ‘Parameters for ...’ header. Then recompile from scratch.

The `tuneup` program takes one useful parameter, ‘-f NNN’, which instructs the program how long to check FFT multiply parameters. If you’re going to use GMP for extremely large numbers, you may want to run `tuneup` with a large NNN value.
3 GMP Basics

Using functions, macros, data types, etc. not documented in this manual is strongly discouraged. If you do so your application is guaranteed to be incompatible with future versions of GMP.

3.1 Headers and Libraries

All declarations needed to use GMP are collected in the include file `gmp.h`. It is designed to work with both C and C++ compilers.

```c
#include <gmp.h>
```

Note however that prototypes for GMP functions with `FILE *` parameters are only provided if `<stdio.h>` is included too.

```c
#include <stdio.h>
#include <gmp.h>
```

Likewise `<stdarg.h>` is required for prototypes with `va_list` parameters, such as `gmp_vprintf`. And `<obstack.h>` for prototypes with `struct obstack` parameters, such as `gmp_obstack_printf`, when available.

All programs using GMP must link against the `libgmp` library. On a typical Unix-like system this can be done with `'-lgmp'`, for example

```bash
gcc myprogram.c -lgmp
```

GMP C++ functions are in a separate `libgmpxx` library. This is built and installed if C++ support has been enabled (see Section 2.1 [Build Options], page 3). For example,

```bash
g++ mycxxprog.cc -lgmpxx -lgmp
```

GMP is built using Libtool and an application can use that to link if desired, see *GNU Libtool*.

If GMP has been installed to a non-standard location then it may be necessary to use `'-I'` and `'-L'` compiler options to point to the right directories, and some sort of run-time path for a shared library.

3.2 Nomenclature and Types

In this manual, *integer* usually means a multiple precision integer, as defined by the GMP library. The C data type for such integers is `mpz_t`. Here are some examples of how to declare such integers:

```c
mpz_t sum;

struct foo { mpz_t x, y; };

mpz_t vec[20];
```

*Rational number* means a multiple precision fraction. The C data type for these fractions is `mpq_t`. For example:

```c
mpq_t quotient;
```

*Floating point number* or *Float* for short, is an arbitrary precision mantissa with a limited precision exponent. The C data type for such objects is `mpf_t`. For example:

```c
mpf_t fp;
```
The floating point functions accept and return exponents in the C type `mp_exp_t`. Currently this is usually a `long`, but on some systems it’s an `int` for efficiency.

A `limb` means the part of a multi-precision number that fits in a single machine word. (We chose this word because a limb of the human body is analogous to a digit, only larger, and containing several digits.) Normally a limb is 32 or 64 bits. The C data type for a limb is `mp_limb_t`.

Counts of limbs of a multi-precision number represented in the C type `mp_size_t`. Currently this is normally a `long`, but on some systems it’s an `int` for efficiency, and on some systems it will be `long long` in the future.

Counts of bits of a multi-precision number are represented in the C type `mp_bitcnt_t`. Currently this is always an `unsigned long`, but on some systems it will be an `unsigned long long` in the future.

Random state means an algorithm selection and current state data. The C data type for such objects is `gmp_randstate_t`. For example:

```c
    gmp_randstate_t rstate;
```

Also, in general `mp_bitcnt_t` is used for bit counts and ranges, and `size_t` is used for byte or character counts.

### 3.3 Function Classes

There are six classes of functions in the GMP library:

1. Functions for signed integer arithmetic, with names beginning with `mpz_`. The associated type is `mpz_t`. There are about 150 functions in this class. (see Chapter 5 [Integer Functions], page 30)

2. Functions for rational number arithmetic, with names beginning with `mpq_`. The associated type is `mpq_t`. There are about 35 functions in this class, but the integer functions can be used for arithmetic on the numerator and denominator separately. (see Chapter 6 [Rational Number Functions], page 46)

3. Functions for floating-point arithmetic, with names beginning with `mpf_`. The associated type is `mpf_t`. There are about 70 functions in this class. (see Chapter 7 [Floating-point Functions], page 50)

4. Fast low-level functions that operate on natural numbers. These are used by the functions in the preceding groups, and you can also call them directly from very time-critical user programs. These functions’ names begin with `mpn_`. The associated type is array of `mp_limb_t`. There are about 60 (hard-to-use) functions in this class. (see Chapter 8 [Low-level Functions], page 58)

5. Miscellaneous functions. Functions for setting up custom allocation and functions for generating random numbers. (see Chapter 13 [Custom Allocation], page 90, and see Chapter 9 [Random Number Functions], page 70)

### 3.4 Variable Conventions

GMP functions generally have output arguments before input arguments. This notation is by analogy with the assignment operator.

GMP lets you use the same variable for both input and output in one call. For example, the main function for integer multiplication, `mpz_mul`, can be used to square `x` and put the result back in `x` with

```c
    mpz_mul (x, x, x);
```
Before you can assign to a GMP variable, you need to initialize it by calling one of the special initialization functions. When you’re done with a variable, you need to clear it out, using one of the functions for that purpose. Which function to use depends on the type of variable. See the chapters on integer functions, rational number functions, and floating-point functions for details.

A variable should only be initialized once, or at least cleared between each initialization. After a variable has been initialized, it may be assigned to any number of times.

For efficiency reasons, avoid excessive initializing and clearing. In general, initialize near the start of a function and clear near the end. For example,

```c
void
foo (void)
{
  mpz_t n;
  int i;
  mpz_init (n);
  for (i = 1; i < 100; i++)
  {
    mpz_mul (n, ...);
    mpz_fdiv_q (n, ...);
    ...
  }
  mpz_clear (n);
}
```

GMP types like `mpz_t` are implemented as one-element arrays of certain structures. Declaring a variable creates an object with the fields GMP needs, but variables are normally manipulated by using the pointer to the object. For both behavior and efficiency reasons, it is discouraged to make copies of the GMP object itself (either directly or via aggregate objects containing such GMP objects). If copies are done, all of them must be used read-only; using a copy as the output of some function will invalidate all the other copies. Note that the actual fields in each `mpz_t` etc are for internal use only and should not be accessed directly by code that expects to be compatible with future GMP releases.

### 3.5 Parameter Conventions

When a GMP variable is used as a function parameter, it’s effectively a call-by-reference, meaning that when the function stores a value there it will change the original in the caller. Parameters which are input-only can be designated `const` to provoke a compiler error or warning on attempting to modify them.

When a function is going to return a GMP result, it should designate a parameter that it sets, like the library functions do. More than one value can be returned by having more than one output parameter, again like the library functions. A `return` of an `mpz_t` etc doesn’t return the object, only a pointer, and this is almost certainly not what’s wanted.

Here’s an example accepting an `mpz_t` parameter, doing a calculation, and storing the result to the indicated parameter.

```c
void
foo (mpz_t result, const mpz_t param, unsigned long n)
{
  unsigned long i;
  mpz_mul_ui (result, param, n);
```
for (i = 1; i < n; i++)
    mpz_add_ui (result, result, i*7);
}

int
main (void)
{
    mpz_t r, n;
    mpz_init (r);
    mpz_init_set_str (n, "123456", 0);
    foo (r, n, 20L);
    gmp_printf ("%Zd\n", r);
    return 0;
}

Our function foo works even if its caller passes the same variable for \texttt{param} and \texttt{result}, just like the library functions. But sometimes it's tricky to make that work, and an application might not want to bother supporting that sort of thing.

Since GMP types are implemented as one-element arrays, using a GMP variable as a parameter passes a pointer to the object. Hence the call-by-reference.

## 3.6 Memory Management

The GMP types like \texttt{mpz} are small, containing only a couple of sizes, and pointers to allocated data. Once a variable is initialized, GMP takes care of all space allocation. Additional space is allocated whenever a variable doesn't have enough.

\texttt{mpz} and \texttt{mpq} variables never reduce their allocated space. Normally this is the best policy, since it avoids frequent reallocation. Applications that need to return memory to the heap at some particular point can use \texttt{mpz realloc2}, or clear variables no longer needed.

\texttt{mpf} variables, in the current implementation, use a fixed amount of space, determined by the chosen precision and allocated at initialization, so their size doesn't change.

All memory is allocated using \texttt{malloc} and friends by default, but this can be changed, see Chapter 13 [Custom Allocation], page 90. Temporary memory on the stack is also used (via \texttt{alloca}), but this can be changed at build-time if desired, see Section 2.1 [Build Options], page 3.

## 3.7 Reentrancy

GMP is reentrant and thread-safe, with some exceptions:

- If configured with \texttt{--enable-alloca=malloc-notreentrant} (or with \texttt{--enable-alloca=notreentrant} when \texttt{alloca} is not available), then naturally GMP is not reentrant.
- \texttt{mpf_set_default_prec} and \texttt{mpf_init} use a global variable for the selected precision. \texttt{mpf_init2} can be used instead, and in the C++ interface an explicit precision to the \texttt{mpf_class} constructor.
- \texttt{mpz_random} and the other old random number functions use a global random state and are hence not reentrant. The newer random number functions that accept a \texttt{gmp_randstate_t} parameter can be used instead.
- \texttt{gmp_randinit} (obsolete) returns an error indication through a global variable, which is not thread safe. Applications are advised to use \texttt{gmp_randinit_default} or \texttt{gmp_randinit_lc_2exp} instead.
• **mp_set_memory_functions** uses global variables to store the selected memory allocation functions.

• If the memory allocation functions set by a call to **mp_set_memory_functions** (or **malloc** and friends by default) are not reentrant, then GMP will not be reentrant either.

• If the standard I/O functions such as **fwrite** are not reentrant then the GMP I/O functions using them will not be reentrant either.

• It’s safe for two threads to read from the same GMP variable simultaneously, but it’s not safe for one to read while another might be writing, nor for two threads to write simultaneously. It’s not safe for two threads to generate a random number from the same **gmp_randstate_t** simultaneously, since this involves an update of that variable.

### 3.8 Useful Macros and Constants

**const int** mp_bits_per_limb  
The number of bits per limb.

`__GNU_MP_VERSION`  
`__GNU_MP_VERSION_MINOR`  
`__GNU_MP_VERSION_PATCHLEVEL`  
The major and minor GMP version, and patch level, respectively, as integers. For GMP i,j, these numbers will be i, j, and 0, respectively. For GMP i,j,k, these numbers will be i, j, and k, respectively.

**const char * const** gmp_version  
The GMP version number, as a null-terminated string, in the form “i.j.k”. This release is "6.2.0". Note that the format “i.j” was used, before version 4.3.0, when k was zero.

`__GMP_CC`  
`__GMP_CFLAGS`  
The compiler and compiler flags, respectively, used when compiling GMP, as strings.

### 3.9 Compatibility with older versions

This version of GMP is upwardly binary compatible with all 5.x, 4.x, and 3.x versions, and upwardly compatible at the source level with all 2.x versions, with the following exceptions.

• **mpn_gcd** had its source arguments swapped as of GMP 3.0, for consistency with other **mpn** functions.

• **mpf_get_prec** counted precision slightly differently in GMP 3.0 and 3.0.1, but in 3.1 reverted to the 2.x style.

• **mpn_bdivmod**, documented as preliminary in GMP 4, has been removed.

There are a number of compatibility issues between GMP 1 and GMP 2 that of course also apply when porting applications from GMP 1 to GMP 5. Please see the GMP 2 manual for details.

### 3.10 Demonstration programs

The **demos** subdirectory has some sample programs using GMP. These aren’t built or installed, but there’s a **Makefile** with rules for them. For instance,

```
make pexpr
./pexpr 68^975+10
```
The following programs are provided

- 'pexpr' is an expression evaluator, the program used on the GMP web page.
- The 'calc' subdirectory has a similar but simpler evaluator using lex and yacc.
- The 'expr' subdirectory is yet another expression evaluator, a library designed for ease of use within a C program. See demos/expr/README for more information.
- 'factorize' is a Pollard-Rho factorization program.
- 'isprime' is a command-line interface to the mpz_probab_prime_p function.
- 'primes' counts or lists primes in an interval, using a sieve.
- 'qcn' is an example use of mpz_kronecker_ui to estimate quadratic class numbers.
- The 'perl' subdirectory is a comprehensive perl interface to GMP. See demos/perl/INSTALL for more information. Documentation is in POD format in demos/perl/GMP.pm.

As an aside, consideration has been given at various times to some sort of expression evaluation within the main GMP library. Going beyond something minimal quickly leads to matters like user-defined functions, looping, fixnums for control variables, etc, which are considered outside the scope of GMP (much closer to language interpreters or compilers, See Chapter 14 [Language Bindings], page 92.) Something simple for program input convenience may yet be a possibility, a combination of the expr demo and the pexpr tree back-end perhaps. But for now the above evaluators are offered as illustrations.

### 3.11 Efficiency

#### Small Operands

On small operands, the time for function call overheads and memory allocation can be significant in comparison to actual calculation. This is unavoidable in a general purpose variable precision library, although GMP attempts to be as efficient as it can on both large and small operands.

#### Static Linking

On some CPUs, in particular the x86s, the static libgmp.a should be used for maximum speed, since the PIC code in the shared libgmp.so will have a small overhead on each function call and global data address. For many programs this will be insignificant, but for long calculations there’s a gain to be had.

#### Initializing and Clearing

Avoid excessive initializing and clearing of variables, since this can be quite time consuming, especially in comparison to otherwise fast operations like addition. A language interpreter might want to keep a free list or stack of initialized variables ready for use. It should be possible to integrate something like that with a garbage collector too.

#### Reallocations

An mpz_t or mpq_t variable used to hold successively increasing values will have its memory repeatedly allocated, which could be quite slow or could fragment memory, depending on the C library. If an application can estimate the final size then mpz_init2 or mpz_realloc2 can be called to allocate the necessary space from the beginning (see Section 5.1 [Initializing Integers], page 30).

It doesn’t matter if a size set with mpz_init2 or mpz_realloc2 is too small, since all functions will do a further reallocation if necessary. Badly overestimating memory required will waste space though.
2exp Functions

It’s up to an application to call functions like \texttt{mpz\_mul\_2exp} when appropriate. General purpose functions like \texttt{mpz\_mul} make no attempt to identify powers of two or other special forms, because such inputs will usually be very rare and testing every time would be wasteful.

ui and si Functions

The \texttt{ui} functions and the small number of \texttt{si} functions exist for convenience and should be used where applicable. But if for example an \texttt{mpz\_t} contains a value that fits in an \texttt{unsigned long} there’s no need extract it and call a \texttt{ui} function, just use the regular \texttt{mpz} function.

In-Place Operations

\texttt{mpz\_abs}, \texttt{mpq\_abs}, \texttt{mpf\_abs}, \texttt{mpz\_neg}, \texttt{mpq\_neg} and \texttt{mpf\_neg} are fast when used for in-place operations like \texttt{mpz\_abs(x,x)}, since in the current implementation only a single field of \texttt{x} needs changing. On suitable compilers (GCC for instance) this is inlined too.

\texttt{mpz\_add\_ui}, \texttt{mpz\_sub\_ui}, \texttt{mpf\_add\_ui} and \texttt{mpf\_sub\_ui} benefit from an in-place operation like \texttt{mpz\_add\_ui(x,x,y)}, since usually only one or two limbs of \texttt{x} will need to be changed. The same applies to the full precision \texttt{mpz\_add} etc if \texttt{y} is small. If \texttt{y} is big then cache locality may be helped, but that’s all.

\texttt{mpz\_mul} is currently the opposite, a separate destination is slightly better. A call like \texttt{mpz\_mul(x,x,y)} will, unless \texttt{y} is only one limb, make a temporary copy of \texttt{x} before forming the result. Normally that copying will only be a tiny fraction of the time for the multiply, so this is not a particularly important consideration.

\texttt{mpz\_set}, \texttt{mpq\_set}, \texttt{mpq\_set\_num}, \texttt{mpf\_set}, etc, make no attempt to recognise a copy of something to itself, so a call like \texttt{mpz\_set(x,x)} will be wasteful. Naturally that would never be written deliberately, but if it might arise from two pointers to the same object then a test to avoid it might be desirable.

\begin{verbatim}
if (x != y)
  mpz_set (x, y);
\end{verbatim}

Note that it’s never worth introducing extra \texttt{mpz\_set} calls just to get in-place operations. If a result should go to a particular variable then just direct it there and let GMP take care of data movement.

Divisibility Testing (Small Integers)

\texttt{mpz\_divisible\_ui\_p} and \texttt{mpz\_congruent\_ui\_p} are the best functions for testing whether an \texttt{mpz\_t} is divisible by an individual small integer. They use an algorithm which is faster than \texttt{mpz\_tdiv\_ui}, but which gives no useful information about the actual remainder, only whether it’s zero (or a particular value).

However when testing divisibility by several small integers, it’s best to take a remainder modulo their product, to save multi-precision operations. For instance to test whether a number is divisible by any of 23, 29 or 31 take a remainder modulo \(23 \times 29 \times 31 = 20677\) and then test that.

The division functions like \texttt{mpz\_tdiv\_q\_ui} which give a quotient as well as a remainder are generally a little slower than the remainder-only functions like \texttt{mpz\_tdiv\_ui}. If the quotient is only rarely wanted then it’s probably best to just take a remainder and then go back and calculate the quotient if and when it’s wanted (\texttt{mpz\_divexact\_ui} can be used if the remainder is zero).

Rational Arithmetic

The \texttt{mpq} functions operate on \texttt{mpq\_t} values with no common factors in the numerator and denominator. Common factors are checked-for and cast out as necessary. In
general, cancelling factors every time is the best approach since it minimizes the sizes for subsequent operations.

However, applications that know something about the factorization of the values they’re working with might be able to avoid some of the GCDs used for canonicalization, or swap them for divisions. For example when multiplying by a prime it’s enough to check for factors of it in the denominator instead of doing a full GCD. Or when forming a big product it might be known that very little cancellation will be possible, and so canonicalization can be left to the end.

The mpq_numref and mpq_denref macros give access to the numerator and denominator to do things outside the scope of the supplied mpq functions. See Section 6.5 [Applying Integer Functions], page 48.

The canonical form for rationals allows mixed-type mpq_t and integer additions or subtractions to be done directly with multiples of the denominator. This will be somewhat faster than mpq_add. For example,

```c
/* mpq increment */
mpz_add (mpq_numref(q), mpq_numref(q), mpq_denref(q));

/* mpq += unsigned long */
mpz_addmul_ui (mpq_numref(q), mpq_denref(q), 123UL);

/* mpq -= mpz */
mpz_submul (mpq_numref(q), mpq_denref(q), z);
```

Number Sequences

Functions like mpz_fac_ui, mpz_fib_ui and mpz_bin_uiui are designed for calculating isolated values. If a range of values is wanted it’s probably best to call to get a starting point and iterate from there.

Text Input/Output

Hexadecimal or octal are suggested for input or output in text form. Power-of-2 bases like these can be converted much more efficiently than other bases, like decimal. For big numbers there’s usually nothing of particular interest to be seen in the digits, so the base doesn’t matter much.

Maybe we can hope octal will one day become the normal base for everyday use, as proposed by King Charles XII of Sweden and later reformers.

### 3.12 Debugging

**Stack Overflow**

Depending on the system, a segmentation violation or bus error might be the only indication of stack overflow. See ‘--enable-alloca’ choices in Section 2.1 [Build Options], page 3, for how to address this.

In new enough versions of GCC, ‘-fstack-check’ may be able to ensure an overflow is recognised by the system before too much damage is done, or ‘-fstack-limit-symbol’ or ‘-fstack-limit-register’ may be able to add checking if the system itself doesn’t do any (see Section “Options for Code Generation” in Using the GNU Compiler Collection (GCC)). These options must be added to the ‘CFLAGS’ used in the GMP build (see Section 2.1 [Build Options], page 3), adding them just to an application will have no effect. Note also they’re a slowdown, adding overhead to each function call and each stack allocation.

**Heap Problems**

The most likely cause of application problems with GMP is heap corruption. Failing to init GMP variables will have unpredictable effects, and corruption arising
elsewhere in a program may well affect GMP. Initializing GMP variables more than once or failing to clear them will cause memory leaks.

In all such cases a malloc debugger is recommended. On a GNU or BSD system the standard C library malloc has some diagnostic facilities, see Section “Allocation Debugging” in The GNU C Library Reference Manual, or ‘man 3 malloc’. Other possibilities, in no particular order, include

http://cs.eecs.baylor.edu/~donahoo/tools/ccmalloc/
http://dmalloc.com/
https://wiki.gnome.org/Apps/MemProf

The GMP default allocation routines in memory.c also have a simple sentinel scheme which can be enabled with #define DEBUG in that file. This is mainly designed for detecting buffer overruns during GMP development, but might find other uses.

Stack Backtraces

On some systems the compiler options GMP uses by default can interfere with debugging. In particular on x86 and 68k systems ‘-fomit-frame-pointer’ is used and this generally inhibits stack backtracing. Recompiling without such options may help while debugging, though the usual caveats about it potentially moving a memory problem or hiding a compiler bug will apply.

GDB, the GNU Debugger

A sample .gdbinit is included in the distribution, showing how to call some undocumented dump functions to print GMP variables from within GDB. Note that these functions shouldn’t be used in final application code since they’re undocumented and may be subject to incompatible changes in future versions of GMP.

Source File Paths

GMP has multiple source files with the same name, in different directories. For example mpz, mpq and mpf each have an init.c. If the debugger can’t already determine the right one it may help to build with absolute paths on each C file. One way to do that is to use a separate object directory with an absolute path to the source directory.

```
cd /my/build/dir
/my/source/dir/gmp-6.2.0/configure
```

This works via VPATH, and might require GNU make. Alternately it might be possible to change the .c.lo rules appropriately.

Assertion Checking

The build option --enable-assert is available to add some consistency checks to the library (see Section 2.1 [Build Options], page 3). These are likely to be of limited value to most applications. Assertion failures are just as likely to indicate memory corruption as a library or compiler bug.

Applications using the low-level mpn functions, however, will benefit from --enable-assert since it adds checks on the parameters of most such functions, many of which have subtle restrictions on their usage. Note however that only the generic C code has checks, not the assembly code, so --disable-assembly should be used for maximum checking.

Temporary Memory Checking

The build option --enable-alloca=debug arranges that each block of temporary memory in GMP is allocated with a separate call to malloc (or the allocation function set with mp_set_memory_functions).

This can help a malloc debugger detect accesses outside the intended bounds, or detect memory not released. In a normal build, on the other hand, temporary
memory is allocated in blocks which GMP divides up for its own use, or may be allocated with a compiler builtin `alloca` which will go nowhere near any malloc debugger hooks.

**Maximum Debuggability**

To summarize the above, a GMP build for maximum debuggability would be

```
./configure --disable-shared --enable-assert
   --enable-alloca=debug --disable-assembly CFLAGS=-g
```

For C++, add `--enable-cxx CXXFLAGS=-g`.

**Checker**

The GCC checker ([https://savannah.nongnu.org/projects/checker/](https://savannah.nongnu.org/projects/checker/)) can be used with GMP. It contains a stub library which means GMP applications compiled with checker can use a normal GMP build.

A build of GMP with checking within GMP itself can be made. This will run very very slowly. On GNU/Linux for example,

```
./configure --disable-assembly CC=checkergcc
```

`--disable-assembly` must be used, since the GMP assembly code doesn’t support the checking scheme. The GMP C++ features cannot be used, since current versions of checker (0.9.9.1) don’t yet support the standard C++ library.

**Valgrind**

Valgrind ([http://valgrind.org/](http://valgrind.org/)) is a memory checker for x86, ARM, MIPS, PowerPC, and S/390. It translates and emulates machine instructions to do strong checks for uninitialized data (at the level of individual bits), memory accesses through bad pointers, and memory leaks.

Valgrind does not always support every possible instruction, in particular ones recently added to an ISA. Valgrind might therefore be incompatible with a recent GMP or even a less recent GMP which is compiled using a recent GCC.

GMP’s assembly code sometimes promotes a read of the limbs to some larger size, for efficiency. GMP will do this even at the start and end of a multilimb operand, using naturally aligned operations on the larger type. This may lead to benign reads outside of allocated areas, triggering complaints from Valgrind. Valgrind’s option `--partial-loads-ok=yes` should help.

**Other Problems**

Any suspected bug in GMP itself should be isolated to make sure it’s not an application problem, see Chapter 4 [Reporting Bugs], page 29.

### 3.13 Profiling

Running a program under a profiler is a good way to find where it’s spending most time and where improvements can be best sought. The profiling choices for a GMP build are as follows.

`--disable-profiling`

The default is to add nothing special for profiling.

It should be possible to just compile the mainline of a program with `-p` and use `prof` to get a profile consisting of timer-based sampling of the program counter. Most of the GMP assembly code has the necessary symbol information.

This approach has the advantage of minimizing interference with normal program operation, but on most systems the resolution of the sampling is quite low (10 milliseconds for instance), requiring long runs to get accurate information.

`--enable-profiling=prof`

Build with support for the system `prof`, which means `--p` added to the `CFLAGS`.
This provides call counting in addition to program counter sampling, which allows the most frequently called routines to be identified, and an average time spent in each routine to be determined.

The x86 assembly code has support for this option, but on other processors the assembly routines will be as if compiled without `-p' and therefore won’t appear in the call counts.

On some systems, such as GNU/Linux, `-p' in fact means `-pg' and in this case `--enable-profiling=gprof' described below should be used instead.

`--enable-profiling=gprof'
Build with support for gprof, which means `-pg' added to the `CFLAGS'.
This provides call graph construction in addition to call counting and program counter sampling, which makes it possible to count calls coming from different locations. For example the number of calls to mpn_mul from mpz_mul versus the number from mpf_mul. The program counter sampling is still flat though, so only a total time in mpn_mul would be accumulated, not a separate amount for each call site.

The x86 assembly code has support for this option, but on other processors the assembly routines will be as if compiled without `-pg' and therefore not be included in the call counts.

On x86 and m68k systems `-pg' and `-fomit-frame-pointer' are incompatible, so the latter is omitted from the default flags in that case, which might result in poorer code generation.

Incidentally, it should be possible to use the gprof program with a plain `--enable-profiling=prof' build. But in that case only the `gprof -p' flat profile and call counts can be expected to be valid, not the `gprof -q' call graph.

`--enable-profiling=instrument'
Build with the GCC option `--instrument-functions' added to the `CFLAGS' (see Section “Options for Code Generation” in Using the GNU Compiler Collection (GCC)).
This inserts special instrumenting calls at the start and end of each function, allowing exact timing and full call graph construction.

This instrumenting is not normally a standard system feature and will require support from an external library, such as

https://sourceforge.net/projects/fnccheck/

This should be included in ‘LIBS’ during the GMP configure so that test programs will link. For example,

`./configure --enable-profiling=instrument LIBS=-lfc'

On a GNU system the C library provides dummy instrumenting functions, so programs compiled with this option will link. In this case it’s only necessary to ensure the correct library is added when linking an application.

The x86 assembly code supports this option, but on other processors the assembly routines will be as if compiled without `--instrument-functions' meaning time spent in them will effectively be attributed to their caller.

3.14 Autoconf

Autoconf based applications can easily check whether GMP is installed. The only thing to be noted is that GMP library symbols from version 3 onwards have prefixes like __gmpz. The following therefore would be a simple test,

AC_CHECK_LIB(gmp, __gmpz_init)
This just uses the default AC_CHECK_LIB actions for found or not found, but an application that must have GMP would want to generate an error if not found. For example,

```
AC_CHECK_LIB(gmp, __gmpz_init, ,
    [AC_MSG_ERROR([GNU MP not found, see https://gmplib.org/])])
```

If functions added in some particular version of GMP are required, then one of those can be used when checking. For example mpz_mul_si was added in GMP 3.1,

```
AC_CHECK_LIB(gmp, __gmpz_mul_si, ,
    [AC_MSG_ERROR([GNU MP not found, or not 3.1 or up, see https://gmplib.org/])])
```

An alternative would be to test the version number in gmp.h using AC_EGREP_CPP. That would make it possible to test the exact version, if some particular sub-minor release is known to be necessary.

In general it’s recommended that applications should simply demand a new enough GMP rather than trying to provide supplements for features not available in past versions.

Occasionally an application will need or want to know the size of a type at configuration or preprocessing time, not just with sizeof in the code. This can be done in the normal way with mp_limb_t etc, but GMP 4.0 or up is best for this, since prior versions needed certain ‘-D’ defines on systems using a long long limb. The following would suit Autoconf 2.50 or up,

```
AC_CHECK_SIZEOF(mp_limb_t, , [#include <gmp.h>])
```

### 3.15 Emacs

C-h C-i (info-lookup-symbol) is a good way to find documentation on C functions while editing (see Section “Info Documentation Lookup” in The Emacs Editor).

The GMP manual can be included in such lookups by putting the following in your .emacs,

```lisp
(eval-after-load "info-look"
 '(let ((mode-value (assoc 'c-mode (assoc 'symbol info-lookup-alist))))
   (setcar (nthcdr 3 mode-value)
     (cons '("(gmp)Function Index" nil "-.*" "\<\>"
     (nth 3 mode-value))))))
```
4 Reporting Bugs

If you think you have found a bug in the GMP library, please investigate it and report it. We have made this library available to you, and it is not too much to ask you to report the bugs you find.

Before you report a bug, check it’s not already addressed in Section 2.5 [Known Build Problems], page 14, or perhaps Section 2.4 [Notes for Particular Systems], page 12. You may also want to check https://gmplib.org/ for patches for this release.

Please include the following in any report,

- The GMP version number, and if pre-packaged or patched then say so.
- A test program that makes it possible for us to reproduce the bug. Include instructions on how to run the program.
- A description of what is wrong. If the results are incorrect, in what way. If you get a crash, say so.
- If you get a crash, include a stack backtrace from the debugger if it’s informative (‘where’ in gdb, or ‘$C’ in adb).
- Please do not send core dumps, executables or straces.
- The ‘configure’ options you used when building GMP, if any.
- The output from ‘configure’, as printed to stdout, with any options used.
- The name of the compiler and its version. For gcc, get the version with ‘gcc -v’, otherwise perhaps ‘what ‘which cc’’, or similar.
- The output from running ‘uname -a’.
- The output from running ‘./config.guess’, and from running ‘./configfsf.guess’ (might be the same).
- If the bug is related to ‘configure’, then the compressed contents of config.log.
- If the bug is related to an asm file not assembling, then the contents of config.m4 and the offending line or lines from the temporary mpn/tmp-<file>.s.

Please make an effort to produce a self-contained report, with something definite that can be tested or debugged. Vague queries or piecemeal messages are difficult to act on and don’t help the development effort.

It is not uncommon that an observed problem is actually due to a bug in the compiler; the GMP code tends to explore interesting corners in compilers.

If your bug report is good, we will do our best to help you get a corrected version of the library; if the bug report is poor, we won’t do anything about it (except maybe ask you to send a better report).

Send your report to: gmp-bugs@gmplib.org.

If you think something in this manual is unclear, or downright incorrect, or if the language needs to be improved, please send a note to the same address.
5 Integer Functions

This chapter describes the GMP functions for performing integer arithmetic. These functions start with the prefix `mpz_`.

GMP integers are stored in objects of type `mpz_t`.

5.1 Initialization Functions

The functions for integer arithmetic assume that all integer objects are initialized. You do that by calling the function `mpz_init`. For example,

```c
{
    mpz_t integ;
    mpz_init (integ);
    ...  
    mpz_add (integ, ...);
    ...
    mpz_sub (integ, ...);
    
    /* Unless the program is about to exit, do ... */
    mpz_clear (integ);
}
```

As you can see, you can store new values any number of times, once an object is initialized.

- **Function** `void mpz_init (mpz_t x)`
  - Initialize `x`, and set its value to 0.

- **Function** `void mpz_inits (mpz_t x, ...)`
  - Initialize a NULL-terminated list of `mpz_t` variables, and set their values to 0.

- **Function** `void mpz_init2 (mpz_t x, mp_bitcnt_t n)`
  - Initialize `x`, with space for `n`-bit numbers, and set its value to 0. Calling this function instead of `mpz_init` or `mpz_inits` is never necessary; reallocation is handled automatically by GMP when needed.

  While `n` defines the initial space, `x` will grow automatically in the normal way, if necessary, for subsequent values stored. `mpz_init2` makes it possible to avoid such reallocations if a maximum size is known in advance.

  In preparation for an operation, GMP often allocates one limb more than ultimately needed. To make sure GMP will not perform reallocation for `x`, you need to add the number of bits in `mp_limb_t` to `n`.

- **Function** `void mpz_clear (mpz_t x)`
  - Free the space occupied by `x`. Call this function for all `mpz_t` variables when you are done with them.

- **Function** `void mpz_clears (mpz_t x, ...)`
  - Free the space occupied by a NULL-terminated list of `mpz_t` variables.

- **Function** `void mpz_realloc2 (mpz_t x, mp_bitcnt_t n)`
  - Change the space allocated for `x` to `n` bits. The value in `x` is preserved if it fits, or is set to 0 if not.
Calling this function is never necessary; reallocation is handled automatically by GMP when needed. But this function can be used to increase the space for a variable in order to avoid repeated automatic reallocations, or to decrease it to give memory back to the heap.

## 5.2 Assignment Functions

These functions assign new values to already initialized integers (see Section 5.1 [Initializing Integers], page 30).

```c
void mpz_set (mpz_t rop, const mpz_t op)  // Function
void mpz_set_ui (mpz_t rop, unsigned long int op)  // Function
void mpz_set_si (mpz_t rop, signed long int op)  // Function
void mpz_set_d (mpz_t rop, double op)  // Function
void mpz_set_q (mpz_t rop, const mpq_t op)  // Function
void mpz_set_f (mpz_t rop, const mpf_t op)  // Function
```

Set the value of `rop` from `op`.

- `mpz_set_d`, `mpz_set_q`, and `mpz_set_f` truncate `op` to make it an integer.

```c
int mpz_set_str (mpz_t rop, const char *str, int base)  // Function
```

Set the value of `rop` from `str`, a null-terminated C string in base `base`. White space is allowed in the string, and is simply ignored.

- The `base` may vary from 2 to 62, or if `base` is 0, then the leading characters are used: 0x and 0X for hexadecimal, 0b and 0B for binary, 0 for octal, or decimal otherwise.
- For bases up to 36, case is ignored; upper-case and lower-case letters have the same value. For bases 37 to 62, upper-case letter represent the usual 10..35 while lower-case letter represent 36..61.
- This function returns 0 if the entire string is a valid number in base `base`. Otherwise it returns −1.

```c
void mpz_swap (mpz_t rop1, mpz_t rop2)  // Function
```

Swap the values `rop1` and `rop2` efficiently.

## 5.3 Combined Initialization and Assignment Functions

For convenience, GMP provides a parallel series of initialize-and-set functions which initialize the output and then store the value there. These functions’ names have the form `mpz_init_set...`

Here is an example of using one:

```c
{  
    mpz_t pie;  
    mpz_init_set_str (pie, "3141592653589793238462643383279502884", 10);  
    ...  
    mpz_sub (pie, ...);  
    ...  
    mpz_clear (pie);  
}
```

Once the integer has been initialized by any of the `mpz_init_set...` functions, it can be used as the source or destination operand for the ordinary integer functions. Don’t use an initialize-and-set function on a variable already initialized!
void mpz_init_set (mpz_t rop, const mpz_t op)  
    Initialize rop with limb space and set the initial numeric value from op.

void mpz_init_set_ui (mpz_t rop, unsigned long int op)  

void mpz_init_set_si (mpz_t rop, signed long int op)  

void mpz_init_set_d (mpz_t rop, double op)  

int mpz_init_set_str (mpz_t rop, const char *str, int base)  
    Initialize rop and set its value like mpz_set_str (see its documentation above for details).

    If the string is a correct base base number, the function returns 0; if an error occurs it returns −1. rop is initialized even if an error occurs. (I.e., you have to call mpz_clear for it.)

5.4 Conversion Functions
This section describes functions for converting GMP integers to standard C types. Functions for converting \textit{to} GMP integers are described in Section 5.2 \[Assigning Integers\], page 31 and Section 5.12 \[I/O of Integers\], page 40.

unsigned long int mpz_get_ui (const mpz_t op)  
    Return the value of \textit{op} as an unsigned long.

    If \textit{op} is too big to fit an unsigned long then just the least significant bits that do fit are returned. The sign of \textit{op} is ignored, only the absolute value is used.

signed long int mpz_get_si (const mpz_t op)  
    If \textit{op} fits into a signed long int return the value of \textit{op}. Otherwise return the least significant part of \textit{op}, with the same sign as \textit{op}.

    If \textit{op} is too big to fit in a signed long int, the returned result is probably not very useful. To find out if the value will fit, use the function mpz_fits_slong_p.

double mpz_get_d (const mpz_t op)  
    Convert \textit{op} to a double, truncating if necessary (i.e. rounding towards zero).

    If the exponent from the conversion is too big, the result is system dependent. An infinity is returned where available. A hardware overflow trap may or may not occur.

double mpz_get_d_2exp (signed long int *exp, const mpz_t op)  
    Convert \textit{op} to a double, truncating if necessary (i.e. rounding towards zero), and returning the exponent separately.

    The return value is in the range \(0.5 \leq |d| < 1\) and the exponent is stored to \(* \text{exp} \). \(d \times 2^{\text{exp}}\) is the (truncated) \textit{op} value. If \textit{op} is zero, the return is 0.0 and 0 is stored to \(* \text{exp} \).

    This is similar to the standard C \textit{frexp} function (see Section “Normalization Functions” in \textit{The GNU C Library Reference Manual}).

char * mpz_get_str (char *str, int base, const mpz_t op)  
    Convert \textit{op} to a string of digits in base \textit{base}. The base argument may vary from 2 to 62 or from −2 to −36.

    For \textit{base} in the range 2..36, digits and lower-case letters are used; for −2..−36, digits and upper-case letters are used; for 37..62, digits, upper-case letters, and lower-case letters (in that significance order) are used.
If *str* is NULL, the result string is allocated using the current allocation function (see Chapter 13 [Custom Allocation], page 90). The block will be `strlen(str)+1` bytes, that being exactly enough for the string and null-terminator.

If *str* is not NULL, it should point to a block of storage large enough for the result, that being `mpz_sizeinbase (op, base) + 2`. The two extra bytes are for a possible minus sign, and the null-terminator.

A pointer to the result string is returned, being either the allocated block, or the given *str*.

### 5.5 Arithmetic Functions

- **void mpz_add** *(mpz_t rop, const mpz_t op1, const mpz_t op2)*  
  Set rop to `op1 + op2`.

- **void mpz_add_ui** *(mpz_t rop, const mpz_t op1, unsigned long int op2)*  
  [Function]

- **void mpz_sub** *(mpz_t rop, const mpz_t op1, const mpz_t op2)*  
  [Function]

- **void mpz_sub_ui** *(mpz_t rop, const mpz_t op1, unsigned long int op2)*  
  [Function]

- **void mpz_ui_sub** *(mpz_t rop, unsigned long int op1, const mpz_t op2)*  
  Set rop to `op1 - op2`.

- **void mpz_mul** *(mpz_t rop, const mpz_t op1, const mpz_t op2)*  
  [Function]

- **void mpz_mul_si** *(mpz_t rop, const mpz_t op1, long int op2)*  
  [Function]

- **void mpz_mul_ui** *(mpz_t rop, const mpz_t op1, unsigned long int op2)*  
  [Function]

- **void mpz_addmul** *(mpz_t rop, const mpz_t op1, const mpz_t op2)*  
  [Function]

- **void mpz_addmul_ui** *(mpz_t rop, const mpz_t op1, unsigned long int op2)*  
  [Function]

- **void mpz_submul** *(mpz_t rop, const mpz_t op1, const mpz_t op2)*  
  [Function]

- **void mpz_submul_ui** *(mpz_t rop, const mpz_t op1, unsigned long int op2)*  
  [Function]

- **void mpz_mul_2exp** *(mpz_t rop, const mpz_t op1, mp_bitcnt_t op2)*  
  [Function]

  Set rop to `op1 \times 2^{op2}`. This operation can also be defined as a left shift by op2 bits.

- **void mpz_neg** *(mpz_t rop, const mpz_t op)*  
  [Function]

  Set rop to `-op`.

- **void mpz_abs** *(mpz_t rop, const mpz_t op)*  
  [Function]

  Set rop to the absolute value of op.

### 5.6 Division Functions

Division is undefined if the divisor is zero. Passing a zero divisor to the division or modulo functions (including the modular powering functions `mpz_powm` and `mpz_powm_ui`), will cause an intentional division by zero. This lets a program handle arithmetic exceptions in these functions the same way as for normal C `int` arithmetic.

- **void mpz_cdiv_q** *(mpz_t q, const mpz_t n, const mpz_t d)*  
  [Function]

- **void mpz_cdiv_r** *(mpz_t r, const mpz_t n, const mpz_t d)*  
  [Function]

- **void mpz_cdiv_qr** *(mpz_t q, mpz_t r, const mpz_t n, const mpz_t d)*  
  [Function]
unsigned long int mpz_cdiv_q_ui (mpz_t q, const mpz_t n,
    unsigned long int d) [Function]
unsigned long int mpz_cdiv_r_ui (mpz_t r, const mpz_t n,
    unsigned long int d) [Function]
unsigned long int mpz_cdiv_qr_ui (mpz_t q, mpz_t r, const mpz_t n,
    unsigned long int d) [Function]
unsigned long int mpz_cdiv_q_ui (const mpz_t n, unsigned long int d) [Function]
void mpz_cdiv_q_2exp (mpz_t q, const mpz_t n, mp_bitcnt_t b) [Function]
void mpz_cdiv_r_2exp (mpz_t r, const mpz_t n, mp_bitcnt_t b) [Function]
void mpz_cdiv_q (mpz_t q, const mpz_t n, const mpz_t d) [Function]
void mpz_cdiv_r (mpz_t r, const mpz_t n, const mpz_t d) [Function]
void mpz_cdiv_qr (mpz_t q, mpz_t r, const mpz_t n, const mpz_t d) [Function]
unsigned long int mpz_cdiv_qr_ui (mpz_t q, const mpz_t n,
    unsigned long int d) [Function]
unsigned long int mpz_cdiv_r_ui (mpz_t r, const mpz_t n,
    unsigned long int d) [Function]
unsigned long int mpz_cdiv_qr_ui (mpz_t q, mpz_t r, const mpz_t n,
    unsigned long int d) [Function]
unsigned long int mpz_cdiv_ui (const mpz_t n, unsigned long int d) [Function]
void mpz_cdiv_q_2exp (mpz_t q, const mpz_t n, mp_bitcnt_t b) [Function]
void mpz_cdiv_r_2exp (mpz_t r, const mpz_t n, mp_bitcnt_t b) [Function]
void mpz_cdiv_q (mpz_t q, const mpz_t n, const mpz_t d) [Function]
void mpz_cdiv_r (mpz_t r, const mpz_t n, const mpz_t d) [Function]
void mpz_cdiv_qr (mpz_t q, mpz_t r, const mpz_t n, const mpz_t d) [Function]
unsigned long int mpz_cdiv_qr_ui (mpz_t q, const mpz_t n,
    unsigned long int d) [Function]
unsigned long int mpz_cdiv_r_ui (mpz_t r, const mpz_t n,
    unsigned long int d) [Function]
unsigned long int mpz_cdiv_qr_ui (mpz_t q, mpz_t r, const mpz_t n,
    unsigned long int d) [Function]
unsigned long int mpz_cdiv_ui (const mpz_t n, unsigned long int d) [Function]
void mpz_cdiv_q_2exp (mpz_t q, const mpz_t n, mp_bitcnt_t b) [Function]
void mpz_cdiv_r_2exp (mpz_t r, const mpz_t n, mp_bitcnt_t b) [Function]

Divide \( n \) by \( d \), forming a quotient \( q \) and/or remainder \( r \). For the 2exp functions, \( d = 2^b \). The
rounding is in three styles, each suiting different applications.

- \( \text{cdiv} \) rounds \( q \) up towards \( +\infty \), and \( r \) will have the opposite sign to \( d \). The \( c \) stands for
  “ceil”.
- \( \text{fdiv} \) rounds \( q \) down towards \( -\infty \), and \( r \) will have the same sign as \( d \). The \( f \) stands for
  “floor”.
- \( \text{tdiv} \) rounds \( q \) towards zero, and \( r \) will have the same sign as \( n \). The \( t \) stands for
  “truncate”.

In all cases \( q \) and \( r \) will satisfy \( n = qd + r \), and \( r \) will satisfy \( 0 \leq |r| < |d| \).

The \( q \) functions calculate only the quotient, the \( r \) functions only the remainder, and the \( qr \) functions calculate both. Note that for \( qr \) the same variable cannot be passed for both \( q \) and
\( r \), or results will be unpredictable.

For the \( ui \) variants the return value is the remainder, and in fact returning the remainder is
all the \( \text{div}_\text{ui} \) functions do. For \( \text{tdiv} \) and \( \text{cdiv} \) the remainder can be negative, so for those
the return value is the absolute value of the remainder.
For the $2^{\text{exp}}$ variants the divisor is $2^b$. These functions are implemented as right shifts and bit masks, but of course they round the same as the other functions.

For positive $n$ both $\text{mpz\_fdiv\_q\_2exp}$ and $\text{mpz\_tdiv\_q\_2exp}$ are simple bitwise right shifts. For negative $n$, $\text{mpz\_fdiv\_q\_2exp}$ is effectively an arithmetic right shift treating $n$ as two's complement the same as the bitwise logical functions do, whereas $\text{mpz\_tdiv\_q\_2exp}$ effectively treats $n$ as sign and magnitude.

```c
void mpz_mod (mpz_t r, const mpz_t n, const mpz_t d)     // Function
unsigned long int mpz_mod_ui (mpz_t r, const mpz_t n,       // Function
unsigned long int d)
```

Set $r$ to $n \mod d$. The sign of the divisor is ignored; the result is always non-negative.

```c
void mpz_divexact (mpz_t q, const mpz_t n, const mpz_t d)     // Function
void mpz_divexact_ui (mpz_t q, const mpz_t n, unsigned long d) // Function
```

Set $q$ to $n / d$. These functions produce correct results only when it is known in advance that $d$ divides $n$.

These routines are much faster than the other division functions, and are the best choice when exact division is known to occur, for example reducing a rational to lowest terms.

```c
int mpz_divisible_p (const mpz_t n, const mpz_t d)          // Function
int mpz_divisible_ui_p (const mpz_t n, unsigned long int d) // Function
int mpz_divisible_2exp_p (const mpz_t n, mp_bitcnt_t b)     // Function
```

Return non-zero if $n$ is exactly divisible by $d$, or in the case of $\text{mpz\_divisible\_2exp\_p}$ by $2^b$.

$n$ is divisible by $d$ if there exists an integer $q$ satisfying $n = qd$. Unlike the other division functions, $d = 0$ is accepted and following the rule it can be seen that only 0 is considered divisible by 0.

```c
int mpz_congruent_p (const mpz_t n, const mpz_t c, const mpz_t d)     // Function
int mpz_congruent_ui_p (const mpz_t n, unsigned long int c, unsigned long int d) // Function
int mpz_congruent_2exp_p (const mpz_t n, const mpz_t c, mp_bitcnt_t b)     // Function
```

Return non-zero if $n$ is congruent to $c$ modulo $d$, or in the case of $\text{mpz\_congruent\_2exp\_p}$ modulo $2^b$.

$n$ is congruent to $c \mod d$ if there exists an integer $q$ satisfying $n = c + qd$. Unlike the other division functions, $d = 0$ is accepted and following the rule it can be seen that $n$ and $c$ are considered congruent mod 0 only when exactly equal.

### 5.7 Exponentiation Functions

```c
void mpz_powm (mpz_t rop, const mpz_t base, const mpz_t exp, const mpz_t mod)     // Function
void mpz_powm_ui (mpz_t rop, const mpz_t base, unsigned long int exp,       // Function
const mpz_t mod)
```

Set rop to $\text{base}^{\text{exp}} \mod \text{mod}$.

Negative $\text{exp}$ is supported if the inverse $\text{base}^{\text{exp}} - 1 \mod \text{mod}$ exists (see $\text{mpz\_invert}$ in Section 5.9 [Number Theoretic Functions], page 37). If an inverse doesn’t exist then a divide by zero is raised.
void mpz_powm_sec (mpz_t rop, const mpz_t base, const mpz_t exp, const mpz_t mod)
Set rop to \(base^{exp} \mod \text{mod}\).

It is required that \(exp > 0\) and that \(mod\) is odd.

This function is designed to take the same time and have the same cache access patterns for any two same-size arguments, assuming that function arguments are placed at the same position and that the machine state is identical upon function entry. This function is intended for cryptographic purposes, where resilience to side-channel attacks is desired.

void mpz_pow_ui (mpz_t rop, const mpz_t base, unsigned long int exp)
void mpz_ui_pow_ui (mpz_t rop, unsigned long int base, unsigned long int exp)
Set rop to \(base^{exp}\). The case \(0^0\) yields 1.

### 5.8 Root Extraction Functions

int mpz_root (mpz_t rop, const mpz_t op, unsigned long int n)
Set rop to \([\sqrt[n]{op}]\), the truncated integer part of the nth root of op. Return non-zero if the computation was exact, i.e., if \(op\) is rop to the nth power.

void mpz_rootrem (mpz_t root, mpz_t rem, const mpz_t u, unsigned long int n)
Set root to \([\sqrt[n]{u}]\), the truncated integer part of the nth root of u. Set rem to the remainder, \((u - \text{root}^n)\).

void mpz_sqrt (mpz_t rop, const mpz_t op)
Set rop to \([\sqrt{op}]\), the truncated integer part of the square root of op.

void mpz_sqrtrem (mpz_t rop1, mpz_t rop2, const mpz_t op)
Set rop1 to \([\sqrt{op}]\), like mpz_sqrt. Set rop2 to the remainder \((op - \text{rop1}^2)\), which will be zero if \(op\) is a perfect square.
If rop1 and rop2 are the same variable, the results are undefined.

int mpz_perfect_power_p (const mpz_t op)
Return non-zero if \(op\) is a perfect power, i.e., if there exist integers \(a\) and \(b\), with \(b > 1\), such that \(op = a^b\).

Under this definition both 0 and 1 are considered to be perfect powers. Negative values of \(op\) are accepted, but of course can only be odd perfect powers.

int mpz_perfect_square_p (const mpz_t op)
Return non-zero if \(op\) is a perfect square, i.e., if the square root of \(op\) is an integer. Under this definition both 0 and 1 are considered to be perfect squares.
5.9 Number Theoretic Functions

```
int mpz_probab_prime_p (const mpz_t n, int reps) [Function]
Determine whether \( n \) is prime. Return 2 if \( n \) is definitely prime, return 1 if \( n \) is probably prime (without being certain), or return 0 if \( n \) is definitely non-prime.

This function performs some trial divisions, a Baillie-PSW probable prime test, then \( \text{reps}-24 \) Miller-Rabin probabilistic primality tests. A higher \( \text{reps} \) value will reduce the chances of a non-prime being identified as “probably prime”. A composite number will be identified as a prime with an asymptotic probability of less than \( 4^{-\text{reps}} \). Reasonable values of \( \text{reps} \) are between 15 and 50.

GMP versions up to and including 6.1.2 did not use the Baillie-PSW primality test. In those older versions of GMP, this function performed \( \text{reps} \) Miller-Rabin tests.
```

```
void mpz_nextprime (mpz_t rop, const mpz_t op) [Function]
Set \( \text{rop} \) to the next prime greater than \( \text{op} \).

This function uses a probabilistic algorithm to identify primes. For practical purposes it’s adequate, the chance of a composite passing will be extremely small.
```

```
void mpz_gcd (mpz_t rop, const mpz_t op1, const mpz_t op2) [Function]
Set \( \text{rop} \) to the greatest common divisor of \( \text{op1} \) and \( \text{op2} \). The result is always positive even if one or both input operands are negative. Except if both inputs are zero; then this function defines \( \gcd(0,0) = 0 \).
```

```
unsigned long int mpz_gcd_ui (mpz_t rop, const mpz_t op1, unsigned long op2) [Function]
Compute the greatest common divisor of \( \text{op1} \) and \( \text{op2} \). If \( \text{rop} \) is not \text{NULL}, store the result there.

If the result is small enough to fit in an \text{unsigned long int}, it is returned. If the result does not fit, 0 is returned, and the result is equal to the argument \( \text{op1} \). Note that the result will always fit if \( \text{op2} \) is non-zero.
```

```
void mpz_gcdext (mpz_t g, mpz_t s, mpz_t t, const mpz_t a, const mpz_t b) [Function]
Set \( \text{g} \) to the greatest common divisor of \( \text{a} \) and \( \text{b} \), and in addition set \( \text{s} \) and \( \text{t} \) to coefficients satisfying \( \text{as} + \text{bt} = \text{g} \). The value in \( \text{g} \) is always positive, even if one or both of \( \text{a} \) and \( \text{b} \) are negative (or zero if both inputs are zero). The values in \( \text{s} \) and \( \text{t} \) are chosen such that normally, \( |\text{s}| < |\text{b}|/(2\text{g}) \) and \( |\text{t}| < |\text{a}|/(2\text{g}) \), and these relations define \( \text{s} \) and \( \text{t} \) uniquely. There are a few exceptional cases:

If \( |\text{a}| = |\text{b}| \), then \( \text{s} = 0, \text{t} = \text{sgn}(\text{b}) \).

Otherwise, \( \text{s} = \text{sgn}(\text{a}) \) if \( \text{b} = 0 \) or \( |\text{b}| = 2\text{g} \), and \( \text{t} = \text{sgn}(\text{b}) \) if \( \text{a} = 0 \) or \( |\text{a}| = 2\text{g} \).

In all cases, \( \text{s} = 0 \) if and only if \( \text{g} = |\text{b}| \), i.e., if \( \text{b} \) divides \( \text{a} \) or \( \text{a} = \text{b} = 0 \).

If \( \text{t} \) or \( \text{g} \) is \text{NULL} then that value is not computed.
```

```
void mpz_lcm (mpz_t rop, const mpz_t op1, const mpz_t op2) [Function]
void mpz_lcm_ui (mpz_t rop, const mpz_t op1, unsigned long op2) [Function]
Set \( \text{rop} \) to the least common multiple of \( \text{op1} \) and \( \text{op2} \). \( \text{rop} \) is always positive, irrespective of the signs of \( \text{op1} \) and \( \text{op2} \). \( \text{rop} \) will be zero if either \( \text{op1} \) or \( \text{op2} \) is zero.
```
int mpz_invert (mpz_t rop, const mpz_t op1, const mpz_t op2)  [Function]
Compute the inverse of op1 modulo op2 and put the result in rop. If the inverse exists, the
return value is non-zero and rop will satisfy 0 ≤ rop < |op2| (with rop = 0 possible only
when |op2| = 1, i.e., in the somewhat degenerate zero ring). If an inverse doesn’t exist the
return value is zero and rop is undefined. The behaviour of this function is undefined when
op2 is zero.

int mpz_jacobi (const mpz_t a, const mpz_t b)  [Function]
Calculate the Jacobi symbol \( \left( \frac{a}{b} \right) \). This is defined only for \( b \) odd.

int mpz_legrendre (const mpz_t a, const mpz_t p)  [Function]
Calculate the Legendre symbol \( \left( \frac{a}{p} \right) \). This is defined only for \( p \) an odd positive prime, and
for such \( p \) it’s identical to the Jacobi symbol.

int mpz_kronecker (const mpz_t a, const mpz_t b)  [Function]
int mpz_kronecker_si (const mpz_t a, long b)  [Function]
int mpz_kronecker_ui (const mpz_t a, unsigned long b)  [Function]
int mpz_si_kronecker (long a, const mpz_t b)  [Function]
int mpz_ui_kronecker (unsigned long a, const mpz_t b)  [Function]
Calculate the Jacobi symbol \( \left( \frac{a}{b} \right) \) with the Kronecker extension \( \left( \frac{a}{b} \right) = \left( \frac{a}{d} \right) \) when \( a \) odd, or
\( \left( \frac{a}{2} \right) = 0 \) when \( a \) even.

When \( b \) is odd the Jacobi symbol and Kronecker symbol are identical, so mpz_kronecker_ui
each can be used for mixed precision Jacobi symbols too.

For more information see Henri Cohen section 1.4.2 (see Appendix B [References], page 128),
or any number theory textbook. See also the example program demos/qcn.c which uses
mpz_kronecker_ui.

mp_bitcnt_t mpz_remove (mpz_t rop, const mpz_t op, const mpz_t f)  [Function]
Remove all occurrences of the factor \( f \) from \( op \) and store the result in \( rop \). The return value
is how many such occurrences were removed.

void mpz_fac_ui (mpz_t rop, unsigned long int n)  [Function]
void mpz_2fac_ui (mpz_t rop, unsigned long int n)  [Function]
void mpz_mfac_uiui (mpz_t rop, unsigned long int n, unsigned long int m)  [Function]
Set \( rop \) to the factorial of \( n \): mpz_fac_ui computes the plain factorial \( n! \), mpz_2fac_ui
computes the double-factorial \( n!! \), and mpz_mfac_uiui the \( m \)-multi-factorial \( n^{(m)} \).

void mpz_primorial_ui (mpz_t rop, unsigned long int n)  [Function]
Set \( rop \) to the primorial of \( n \), i.e. the product of all positive prime numbers \( \leq n \).

void mpz_bin_ui (mpz_t rop, const mpz_t n, unsigned long int k)  [Function]
void mpz_bin_uiui (mpz_t rop, unsigned long int n, unsigned long int k)  [Function]
Compute the binomial coefficient \( \binom{n}{k} \) and store the result in \( rop \). Negative values of \( n \) are
supported by mpz_bin_ui, using the identity \( \binom{n}{k} = (-1)^k \binom{n+k-1}{k} \), see Knuth volume 1
section 1.2.6 part G.

void mpz_fib_ui (mpz_t fn, unsigned long int n)  [Function]
void mpz_fib2_ui (mpz_t fn, mpz_t fnsub1, unsigned long int n)  [Function]
mpz_fib_ui sets \( fn \) to \( F_n \), the \( n \)th Fibonacci number. mpz_fib2_ui sets \( fn \) to \( F_n \), and
fnsub1 to \( F_{n-1} \).
These functions are designed for calculating isolated Fibonacci numbers. When a sequence of values is wanted it’s best to start with \texttt{mpz\_fib2\_ui} and iterate the defining $F_{n+1} = F_n + F_{n-1}$ or similar.

\texttt{void mpz\_lucnum\_ui (mpz\_t ln, unsigned long int n)}
\texttt{void mpz\_lucnum2\_ui (mpz\_t ln, mpz\_t lnsub1, unsigned long int n)}
\texttt{mpz\_lucnum\_ui sets ln to to $L_n$, the $n$‘th Lucas number. mpz\_lucnum2\_ui sets ln to $L_n$, and lnsub1 to $L_{n-1}$.}

These functions are designed for calculating isolated Lucas numbers. When a sequence of values is wanted it’s best to start with \texttt{mpz\_lucnum2\_ui} and iterate the defining $L_{n+1} = L_n + L_{n-1}$ or similar.

The Fibonacci numbers and Lucas numbers are related sequences, so it’s never necessary to call both \texttt{mpz\_fib2\_ui} and \texttt{mpz\_lucnum2\_ui}. The formulas for going from Fibonacci to Lucas can be found in \textsection 15.7.5 \cite{Lucas Numbers Algorithm}, page 113, the reverse is straightforward too.

\section*{5.10 Comparison Functions}

\texttt{int mpz\_cmp (const mpz\_t op1, const mpz\_t op2)}
\texttt{int mpz\_cmp\_d (const mpz\_t op1, double op2)}
\texttt{int mpz\_cmp\_si (const mpz\_t op1, signed long int op2)}
\texttt{int mpz\_cmp\_ui (const mpz\_t op1, unsigned long int op2)}
\texttt{Compare op1 and op2. Return a positive value if op1 > op2, zero if op1 = op2, or a negative value if op1 < op2.}

\texttt{mpz\_cmp\_ui and mpz\_cmp\_si are macros and will evaluate their arguments more than once.}
\texttt{mpz\_cmp\_d can be called with an infinity, but results are undefined for a NaN.}

\texttt{int mpz\_cmpabs (const mpz\_t op1, const mpz\_t op2)}
\texttt{int mpz\_cmpabs\_d (const mpz\_t op1, double op2)}
\texttt{int mpz\_cmpabs\_ui (const mpz\_t op1, unsigned long int op2)}
\texttt{Compare the absolute values of op1 and op2. Return a positive value if $|op1| > |op2|$, zero if $|op1| = |op2|$, or a negative value if $|op1| < |op2|$.}

\texttt{mpz\_cmpabs\_d can be called with an infinity, but results are undefined for a NaN.}

\texttt{int mpz\_sgn (const mpz\_t op)}
\texttt{Return +1 if op > 0, 0 if op = 0, and -1 if op < 0.}

This function is actually implemented as a macro. It evaluates its argument multiple times.

\section*{5.11 Logical and Bit Manipulation Functions}

These functions behave as if two’s complement arithmetic were used (although sign-magnitude is the actual implementation). The least significant bit is number 0.

\texttt{void mpz\_and (mpz\_t rop, const mpz\_t op1, const mpz\_t op2)}
\texttt{Set rop to op1 bitwise-and op2.}

\texttt{void mpz\_ior (mpz\_t rop, const mpz\_t op1, const mpz\_t op2)}
\texttt{Set rop to op1 bitwise inclusive-or op2.}
**void mpz_xor (mpz_t rop, const mpz_t op1, const mpz_t op2)**

Set rop to op1 bitwise exclusive-or op2.

**void mpz_com (mpz_t rop, const mpz_t op)**

Set rop to the one’s complement of op.

**mp_bitcnt_t mpz_popcount (const mpz_t op)**

If op \(\geq 0\), return the population count of op, which is the number of 1 bits in the binary representation. If op < 0, the number of 1s is infinite, and the return value is the largest possible mp_bitcnt_t.

**mp_bitcnt_t mpz_hamdist (const mpz_t op1, const mpz_t op2)**

If op1 and op2 are both \(\geq 0\) or both < 0, return the hamming distance between the two operands, which is the number of bit positions where op1 and op2 have different bit values. If one operand is \(\geq 0\) and the other < 0 then the number of bits different is infinite, and the return value is the largest possible mp_bitcnt_t.

**mp_bitcnt_t mpz_scan0 (const mpz_t op, mp_bitcnt_t starting_bit)**

Scan op, starting from bit starting_bit, towards more significant bits, until the first 0 or 1 bit (respectively) is found. Return the index of the found bit.

If the bit at starting_bit is already what’s sought, then starting_bit is returned.

If there’s no bit found, then the largest possible mp_bitcnt_t is returned. This will happen in mpz_scan0 past the end of a negative number, or mpz_scan1 past the end of a nonnegative number.

**void mpz_setbit (mpz_t rop, mp_bitcnt_t bit_index)**

Set bit bit_index in rop.

**void mpz_clrbit (mpz_t rop, mp_bitcnt_t bit_index)**

Clear bit bit_index in rop.

**void mpz_combit (mpz_t rop, mp_bitcnt_t bit_index)**

Complement bit bit_index in rop.

**int mpz_tstbit (const mpz_t op, mp_bitcnt_t bit_index)**

Test bit bit_index in op and return 0 or 1 accordingly.

### 5.12 Input and Output Functions

Functions that perform input from a stdio stream, and functions that output to a stdio stream, of mpz numbers. Passing a NULL pointer for a stream argument to any of these functions will make them read from stdin and write to stdout, respectively.

When using any of these functions, it is a good idea to include stdio.h before gmp.h, since that will allow gmp.h to define prototypes for these functions.

See also Chapter 10 [Formatted Output], page 72 and Chapter 11 [Formatted Input], page 77.

**size_t mpz_out_str (FILE *stream, int base, const mpz_t op)**

Output op on stdio stream stream, as a string of digits in base base. The base argument may vary from 2 to 62 or from -2 to -36.
For base in the range 2..36, digits and lower-case letters are used; for −2..−36, digits and upper-case letters are used; for 37..62, digits, upper-case letters, and lower-case letters (in that significance order) are used.

Return the number of bytes written, or if an error occurred, return 0.

```
size_t mpz_inp_str (mpz_t rop, FILE *stream, int base)
```

Input a possibly white-space preceded string in base base from stdio stream stream, and put the read integer in rop.

The base may vary from 2 to 62, or if base is 0, then the leading characters are used: 0x and 0X for hexadecimal, 0b and 0B for binary, 0 for octal, or decimal otherwise.

For bases up to 36, case is ignored; upper-case and lower-case letters have the same value. For bases 37 to 62, upper-case letter represent the usual 10..35 while lower-case letter represent 36..61.

Return the number of bytes read, or if an error occurred, return 0.

```
size_t mpz_out_raw (FILE *stream, const mpz_t op)
```

Output op on stdio stream stream, in raw binary format. The integer is written in a portable format, with 4 bytes of size information, and that many bytes of limbs. Both the size and the limbs are written in decreasing significance order (i.e., in big-endian).

The output can be read with mpz_inp_raw.

Return the number of bytes written, or if an error occurred, return 0.

The output of this can not be read by mpz_inp_raw from GMP 1, because of changes necessary for compatibility between 32-bit and 64-bit machines.

```
size_t mpz_inp_raw (mpz_t rop, FILE *stream)
```

Input from stdio stream stream in the format written by mpz_out_raw, and put the result in rop. Return the number of bytes read, or if an error occurred, return 0.

This routine can read the output from mpz_out_raw also from GMP 1, in spite of changes necessary for compatibility between 32-bit and 64-bit machines.

### 5.13 Random Number Functions

The random number functions of GMP come in two groups; older function that rely on a global state, and newer functions that accept a state parameter that is read and modified. Please see the Chapter 9 [Random Number Functions], page 70 for more information on how to use and not to use random number functions.

```
void mpz_urandomb (mpz_t rop, gmp_randstate_t state, mp_bitcnt_t n)
```

Generate a uniformly distributed random integer in the range 0 to $2^n - 1$, inclusive.

The variable state must be initialized by calling one of the gmp_randinit functions (Section 9.1 [Random State Initialization], page 70) before invoking this function.

```
void mpz_urandomm (mpz_t rop, gmp_randstate_t state, const mpq_t n)
```

Generate a uniform random integer in the range 0 to $n - 1$, inclusive.

The variable state must be initialized by calling one of the gmp_randinit functions (Section 9.1 [Random State Initialization], page 70) before invoking this function.
void mpz_rrandomb (mpz_t rop, gmp_randstate_t state, mp_bitcnt_t n)  [Function]
Generate a random integer with long strings of zeros and ones in the binary representation. Useful for testing functions and algorithms, since this kind of random numbers have proven to be more likely to trigger corner-case bugs. The random number will be in the range $2^{n} - 1$ to $2^{n} - 1$, inclusive.

The variable state must be initialized by calling one of the gmp_randinit functions (Section 9.1 [Random State Initialization], page 70) before invoking this function.

void mpz_random (mpz_t rop, mp_size_t max_size)  [Function]
Generate a random integer of at most max_size limbs. The generated random number doesn’t satisfy any particular requirements of randomness. Negative random numbers are generated when max_size is negative.

This function is obsolete. Use mpz_urandomb or mpz_urandomm instead.

void mpz_random2 (mpz_t rop, mp_size_t max_size)  [Function]
Generate a random integer of at most max_size limbs, with long strings of zeros and ones in the binary representation. Useful for testing functions and algorithms, since this kind of random numbers have proven to be more likely to trigger corner-case bugs. Negative random numbers are generated when max_size is negative.

This function is obsolete. Use mpz_rrandomb instead.

5.14 Integer Import and Export

mpz_t variables can be converted to and from arbitrary words of binary data with the following functions.

void mpz_import (mpz_t rop, size_t count, int order, size_t size, int endian, size_t nails, const void *op)  [Function]
Set rop from an array of word data at op.

The parameters specify the format of the data. count many words are read, each size bytes. order can be 1 for most significant word first or -1 for least significant first. Within each word endian can be 1 for most significant byte first, -1 for least significant first, or 0 for the native endianness of the host CPU. The most significant nails bits of each word are skipped, this can be 0 to use the full words.

There is no sign taken from the data, rop will simply be a positive integer. An application can handle any sign itself, and apply it for instance with mpz_neg.

There are no data alignment restrictions on op, any address is allowed.

Here’s an example converting an array of unsigned long data, most significant element first, and host byte order within each value.

```c
unsigned long a[20];
/* Initialize z and a */
mpz_import (z, 20, 1, sizeof(a[0]), 0, 0, a);
```

This example assumes the full sizeof bytes are used for data in the given type, which is usually true, and certainly true for unsigned long everywhere we know of. However on Cray vector systems it may be noted that short and int are always stored in 8 bytes (and with sizeof indicating that) but use only 32 or 46 bits. The nails feature can account for this, by passing for instance 8*sizeof(int)-INT_BIT.
void * mpz_export (void *rop, size_t *countp, int order, size_t size, int endian, size_t nails, const mpz_t op)

Fill rop with word data from op.

The parameters specify the format of the data produced. Each word will be size bytes and order can be 1 for most significant word first or -1 for least significant first. Within each word endian can be 1 for most significant byte first, -1 for least significant first, or 0 for the native endianness of the host CPU. The most significant nails bits of each word are unused and set to zero, this can be 0 to produce full words.

The number of words produced is written to *countp, or countp can be NULL to discard the count. rop must have enough space for the data, or if rop is NULL then a result array of the necessary size is allocated using the current GMP allocation function (see Chapter 13 [Custom Allocation], page 90). In either case the return value is the destination used, either rop or the allocated block.

If op is non-zero then the most significant word produced will be non-zero. If op is zero then the count returned will be zero and nothing written to rop. If rop is NULL in this case, no block is allocated, just NULL is returned.

The sign of op is ignored, just the absolute value is exported. An application can use mpz_sgn to get the sign and handle it as desired. (see Section 5.10 [Integer Comparisons], page 39)

There are no data alignment restrictions on rop, any address is allowed.

When an application is allocating space itself the required size can be determined with a calculation like the following. Since mpz_sizeinbase always returns at least 1, count here will be at least one, which avoids any portability problems with malloc(0), though if z is zero no space at all is actually needed (or written).

\[
\text{numb} = 8 \times \text{size} - \text{nail}; \\
\text{count} = (\text{mpz\_sizeinbase} (\text{z}, 2) + \text{numb}-1) / \text{numb}; \\
\text{p} = \text{malloc} (\text{count} \times \text{size});
\]

### 5.15 Miscellaneous Functions

**int mpz_fits_ulong_p (const mpz_t op)**

Return non-zero iff the value of op fits in an unsigned long int.

**int mpz_fits_slong_p (const mpz_t op)**

Return non-zero iff the value of op fits in a signed long int.

**int mpz_fits_uint_p (const mpz_t op)**

Return non-zero iff the value of op fits in an unsigned int.

**int mpz_fits_sint_p (const mpz_t op)**

Return non-zero iff the value of op fits in a signed int.

**int mpz_fits_ushort_p (const mpz_t op)**

Return non-zero iff the value of op fits in an unsigned short int.

**int mpz_fits_sshort_p (const mpz_t op)**

Return non-zero iff the value of op fits in a signed short int.

These functions evaluate their argument more than once.

**int mpz_odd_p (const mpz_t op)**

Determine whether op is odd or even, respectively. Return non-zero if yes, zero if no. These macros evaluate their argument more than once.

**int mpz_even_p (const mpz_t op)**

Determine whether op is odd or even, respectively. Return non-zero if yes, zero if no. These macros evaluate their argument more than once.

**size_t mpz_sizeinbase (const mpz_t op, int base)**

Return the size of op measured in number of digits in the given base. base can vary from 2 to 62. The sign of op is ignored, just the absolute value is used. The result will be either
exact or 1 too big. If base is a power of 2, the result is always exact. If op is zero the return value is always 1.

This function can be used to determine the space required when converting op to a string. The right amount of allocation is normally two more than the value returned by `mpz_sizeinbase`, one extra for a minus sign and one for the null-terminator.

It will be noted that `mpz_sizeinbase(op,2)` can be used to locate the most significant 1 bit in op, counting from 1. (Unlike the bitwise functions which start from 0, See Section 5.11 [Logical and Bit Manipulation Functions], page 39.)

### 5.16 Special Functions

The functions in this section are for various special purposes. Most applications will not need them.

#### `void mpz_array_init (mpz_t integer_array, mp_size_t array_size, mp_size_t fixed_num_bits)`

This is an obsolete function. Do not use it.

#### `void * _mpz_realloc (mpz_t integer, mp_size_t new_alloc)`

Change the space for integer to new_alloc limbs. The value in integer is preserved if it fits, or is set to 0 if not. The return value is not useful to applications and should be ignored.

`mpz_realloc2` is the preferred way to accomplish allocation changes like this. `mpz_realloc2` and `_mpz_realloc` are the same except that `_mpz_realloc` takes its size in limbs.

#### `mp_limb_t mpz_getlimbn (const mpz_t op, mp_size_t n)`

Return limb number n from op. The sign of op is ignored, just the absolute value is used. The least significant limb is number 0.

`mpz_size` can be used to find how many limbs make up op. `mpz_getlimbn` returns zero if n is outside the range 0 to `mpz_size(op)-1`.

#### `size_t mpz_size (const mpz_t op)`

Return the size of op measured in number of limbs. If op is zero, the returned value will be zero.

#### `const mp_limb_t * mpz_limbs_read (const mpz_t x)`

Return a pointer to the limb array representing the absolute value of x. The size of the array is `mpz_size(x)`. Intended for read access only.

#### `mp_limb_t * mpz_limbs_write (mpz_t x, mp_size_t n)`

Return a pointer to the limb array, intended for write access. The array is reallocated as needed, to make room for n limbs. Requires n > 0. The `mpz_limbs_modify` function returns an array that holds the old absolute value of x, while `mpz_limbs_write` may destroy the old value and return an array with unspecified contents.

#### `void mpz_limbs_finish (mpz_t x, mp_size_t s)`

Updates the internal size field of x. Used after writing to the limb array pointer returned by `mpz_limbs_write` or `mpz_limbs_modify` is completed. The array should contain |s| valid limbs, representing the new absolute value for x, and the sign of x is taken from the sign of s. This function never reallocates x, so the limb pointer remains valid.
void foo (mpz_t x)
{
    mp_size_t n, i;
    mp_limb_t *xp;

    n = mpz_size (x);
    xp = mpz_limbs_modify (x, 2*n);
    for (i = 0; i < n; i++)
        xp[n+i] = xp[n-1-i];
    mpz_limbs_finish (x, mpz_sgn (x) < 0 ? -2*n : 2*n);
}

mpz_srcptr mpz_roinit_n (mpz_t x, const mp_limb_t *xp, mp_size_t xs) [Function]
Special initialization of x, using the given limb array and size. x should be treated as read-
only: it can be passed safely as input to any mpz function, but not as an output. The array
xp must point to at least a readable limb, its size is |xs|, and the sign of x is the sign of xs.
For convenience, the function returns x, but cast to a const pointer type.

void foo (mpz_t x)
{
    static const mp_limb_t y[3] = { 0x1, 0x2, 0x3 };
    mp_t tmp;
    mpz_add (x, x, mpz_roinit_n (tmp, y, 3));
}

mpz_t MPZ_ROINIT_N (mp_limb_t *xp, mp_size_t xs) [Macro]
This macro expands to an initializer which can be assigned to an mpz_t variable. The
limb array xp must point to at least a readable limb, moreover, unlike the mpz_roinit_n
function, the array must be normalized: if xs is non-zero, then xp[|xs|−1] must be non-zero.
Intended primarily for constant values. Using it for non-constant values requires a C compiler
supporting C99.

void foo (mpz_t x)
{
    static const mp_limb_t ya[3] = { 0x1, 0x2, 0x3 };
    static const mpz_t y = MPZ_ROINIT_N ((mp_limb_t *) ya, 3);

    mpz_add (x, x, y);
}
6 Rational Number Functions

This chapter describes the GMP functions for performing arithmetic on rational numbers. These functions start with the prefix `mpq_`.

Rational numbers are stored in objects of type `mpq_t`.

All rational arithmetic functions assume operands have a canonical form, and canonicalize their result. The canonical form means that the denominator and the numerator have no common factors, and that the denominator is positive. Zero has the unique representation 0/1.

Pure assignment functions do not canonicalize the assigned variable. It is the responsibility of the user to canonicalize the assigned variable before any arithmetic operations are performed on that variable.

```c
void mpq_canonicalize (mpq_t op)
```

Remove any factors that are common to the numerator and denominator of `op`, and make the denominator positive.

### 6.1 Initialization and Assignment Functions

```c
void mpq_init (mpq_t x)
```

Initialize `x` and set it to 0/1. Each variable should normally only be initialized once, or at least cleared out (using the function `mpq_clear`) between each initialization.

```c
void mpq_inits (mpq_t x, ...)
```

Initialize a NULL-terminated list of `mpq_t` variables, and set their values to 0/1.

```c
void mpq_clear (mpq_t x)
```

Free the space occupied by `x`. Make sure to call this function for all `mpq_t` variables when you are done with them.

```c
void mpq_clears (mpq_t x, ...)
```

Free the space occupied by a NULL-terminated list of `mpq_t` variables.

```c
void mpq_set (mpq_t rop, const mpq_t op)
void mpq_set_z (mpq_t rop, const mpz_t op)
```

Assign `rop` from `op`.

```c
void mpq_set_ui (mpq_t rop, unsigned long int op1, unsigned long int op2)
void mpq_set_si (mpq_t rop, signed long int op1, unsigned long int op2)
```

Set the value of `rop` to `op1/op2`. Note that if `op1` and `op2` have common factors, `rop` has to be passed to `mpq_canonicalize` before any operations are performed on `rop`.

```c
int mpq_set_str (mpq_t rop, const char *str, int base)
```

Set `rop` from a null-terminated string `str` in the given `base`.

The string can be an integer like “41” or a fraction like “41/152”. The fraction must be in canonical form (see Chapter 6 [Rational Number Functions], page 46), or if not then `mpq_canonicalize` must be called.

The numerator and optional denominator are parsed the same as in `mpz_set_str` (see Section 5.2 [Assigning Integers], page 31). White space is allowed in the string, and is simply ignored. The `base` can vary from 2 to 62, or if `base` is 0 then the leading characters are used:
0x or 0X for hex, 0b or 0B for binary, 0 for octal, or decimal otherwise. Note that this is done separately for the numerator and denominator, so for instance 0xEF/100 is 239/100, whereas 0xEF/0x100 is 239/256.

The return value is 0 if the entire string is a valid number, or −1 if not.

```c
void mpq_swap (mpq_t rop1, mpq_t rop2)  ; [Function]
Swap the values rop1 and rop2 efficiently.
```

### 6.2 Conversion Functions

```c
double mpq_get_d (const mpq_t op)  ; [Function]
Convert op to a double, truncating if necessary (i.e. rounding towards zero).
If the exponent from the conversion is too big or too small to fit a double then the result is system dependent. For too big an infinity is returned when available. For too small 0.0 is normally returned. Hardware overflow, underflow and denorm traps may or may not occur.
```

```c
void mpq_set_d (mpq_t rop, double op)  ; [Function]
void mpq_set_f (mpq_t rop, const mpf_t op)  ; [Function]
Set rop to the value of op. There is no rounding, this conversion is exact.
```

```c
char * mpq_get_str (char *str, int base, const mpq_t op)  ; [Function]
Convert op to a string of digits in base base. The base argument may vary from 2 to 62 or from −2 to −36. The string will be of the form ‘num/den’, or if the denominator is 1 then just ‘num’.
For base in the range 2..36, digits and lower-case letters are used; for −2..−36, digits and upper-case letters are used; for 37..62, digits, upper-case letters, and lower-case letters (in that significance order) are used.
If str is NULL, the result string is allocated using the current allocation function (see Chapter 13 [Custom Allocation], page 90). The block will be strlen(str)+1 bytes, that being exactly enough for the string and null-terminator.
If str is not NULL, it should point to a block of storage large enough for the result, that being

\[
\text{mpz_sizeinbase (mpq_numref(op), base)} \\
+ \text{mpz_sizeinbase (mpq_denref(op), base)} + 3
\]

The three extra bytes are for a possible minus sign, possible slash, and the null-terminator.
A pointer to the result string is returned, being either the allocated block, or the given str.
```

### 6.3 Arithmetic Functions

```c
void mpq_add (mpq_t sum, const mpq_t addend1, const mpq_t addend2)  ; [Function]
Set sum to addend1 + addend2.
```

```c
void mpq_sub (mpq_t difference, const mpq_t minuend, const mpq_t subtrahend)  ; [Function]
Set difference to minuend − subtrahend.
```

```c
void mpq_mul (mpq_t product, const mpq_t multiplier, const mpq_t multiplicand)  ; [Function]
Set product to multiplier × multiplicand.
```
void mpq_mul_2exp (mpq_t rop, const mpq_t op1, mp_bitcnt_t op2)  
  Set rop to op1 × 2^{op2}.

void mpq_div (mpq_t quotient, const mpq_t dividend, const mpq_t divisor)  
  Set quotient to dividend/divisor.

void mpq_div_2exp (mpq_t rop, const mpq_t op1, mp_bitcnt_t op2)  
  Set rop to op1/2^{op2}.

void mpq_neg (mpq_t negated_operand, const mpq_t operand)  
  Set negated_operand to −operand.

void mpq_abs (mpq_t rop, const mpq_t op)  
  Set rop to the absolute value of op.

void mpq_inv (mpq_t inverted_number, const mpq_t number)  
  Set inverted_number to 1/number. If the new denominator is zero, this routine will divide by zero.

6.4 Comparison Functions

int mpq_cmp (const mpq_t op1, const mpq_t op2)  
  Compare op1 and op2. Return a positive value if op1 > op2, zero if op1 = op2, and a negative value if op1 < op2.

  To determine if two rationals are equal, mpq_equal is faster than mpq_cmp.

int mpq_cmp_z (const mpq_t op1, const mpz_t op2)  
  Compare op1 and op2. Return a positive value if op1 > op2, zero if op1 = op2, and a negative value if op1 < op2.

num2 and den2 are allowed to have common factors.

These functions are implemented as a macros and evaluate their arguments multiple times.

int mpq_cmp_ui (const mpq_t op1, unsigned long int num2, unsigned long int den2)  
  Compare op1 and num2/den2. Return a positive value if op1 > num2/den2, zero if op1 = num2/den2, and a negative value if op1 < num2/den2.

int mpq_sgn (const mpq_t op)  
  Return +1 if op > 0, 0 if op = 0, and −1 if op < 0.

This function is actually implemented as a macro. It evaluates its argument multiple times.

int mpq_equal (const mpq_t op1, const mpq_t op2)  
  Return non-zero if op1 and op2 are equal, zero if they are non-equal. Although mpq_cmp can be used for the same purpose, this function is much faster.

6.5 Applying Integer Functions to Rationals

The set of mpq functions is quite small. In particular, there are few functions for either input or output. The following functions give direct access to the numerator and denominator of an mpq_t.
Note that if an assignment to the numerator and/or denominator could take an mpq_t out of the canonical form described at the start of this chapter (see Chapter 6 [Rational Number Functions], page 46) then mpq_canonicalize must be called before any other mpq functions are applied to that mpq_t.

```
mpz_t mpq_numref (const mpq_t op)  [Macro]
mpz_t mpq_denref (const mpq_t op)  [Macro]
```

Return a reference to the numerator and denominator of op, respectively. The mpz functions can be used on the result of these macros.

```
void mpq_get_num (mpz_t numerator, const mpq_t rational)  [Function]
void mpq_get_den (mpz_t denominator, const mpq_t rational)  [Function]
void mpq_set_num (mpq_t rational, const mpz_t numerator)  [Function]
void mpq_set_den (mpq_t rational, const mpz_t denominator)  [Function]
```

Get or set the numerator or denominator of a rational. These functions are equivalent to calling mpq_set with an appropriate mpq_numref or mpq_denref. Direct use of mpq_numref or mpq_denref is recommended instead of these functions.

### 6.6 Input and Output Functions

Functions that perform input from a stdio stream, and functions that output to a stdio stream, of mpq numbers. Passing a NULL pointer for a stream argument to any of these functions will make them read from stdin and write to stdout, respectively.

When using any of these functions, it is a good idea to include stdio.h before gmp.h, since that will allow gmp.h to define prototypes for these functions.

See also Chapter 10 [Formatted Output], page 72 and Chapter 11 [Formatted Input], page 77.

```
size_t mpq_out_str (FILE *stream, int base, const mpq_t op)  [Function]
```

Output op on stdio stream stream, as a string of digits in base base. The base argument may vary from 2 to 62 or from −2 to −36. Output is in the form ‘num/den’ or if the denominator is 1 then just ‘num’.

For base in the range 2..36, digits and lower-case letters are used; for −2..−36, digits and upper-case letters are used; for 37..62, digits, upper-case letters, and lower-case letters (in that significance order) are used.

Return the number of bytes written, or if an error occurred, return 0.

```
size_t mpq_inp_str (mpq_t rop, FILE *stream, int base)  [Function]
```

Read a string of digits from stream and convert them to a rational in rop. Any initial white-space characters are read and discarded. Return the number of characters read (including white space), or 0 if a rational could not be read.

The input can be a fraction like ‘17/63’ or just an integer like ‘123’. Reading stops at the first character not in this form, and white space is not permitted within the string. If the input might not be in canonical form, then mpq_canonicalize must be called (see Chapter 6 [Rational Number Functions], page 46).

The base can be between 2 and 62, or can be 0 in which case the leading characters of the string determine the base, ‘0x’ or ‘0X’ for hexadecimal, ‘0b’ and ‘0B’ for binary, ‘0’ for octal, or decimal otherwise. The leading characters are examined separately for the numerator and denominator of a fraction, so for instance ‘0x10/11’ is 16/11, whereas ‘0x10/0x11’ is 16/17.
7 Floating-point Functions

GMP floating point numbers are stored in objects of type `mpf_t` and functions operating on them have an `mpf_` prefix.

The mantissa of each float has a user-selectable precision, in practice only limited by available memory. Each variable has its own precision, and that can be increased or decreased at any time. This selectable precision is a minimum value, GMP rounds it up to a whole limb.

The accuracy of a calculation is determined by the priorly set precision of the destination variable and the numeric values of the input variables. Input variables' set precisions do not affect calculations (except indirectly as their values might have been affected when they were assigned).

The exponent of each float has fixed precision, one machine word on most systems. In the current implementation the exponent is a count of limbs, so for example on a 32-bit system this means a range of roughly $2^{-68719476768}$ to $2^{68719476736}$, or on a 64-bit system this will be much greater. Note however that `mpf_get_str` can only return an exponent which fits an `mpf_exp_t` and currently `mpf_set_str` doesn’t accept exponents bigger than a `long`.

Each variable keeps track of the mantissa data actually in use. This means that if a float is exactly represented in only a few bits then only those bits will be used in a calculation, even if the variable’s selected precision is high. This is a performance optimization; it does not affect the numeric results.

Internally, GMP sometimes calculates with higher precision than that of the destination variable in order to limit errors. Final results are always truncated to the destination variable’s precision.

The mantissa is stored in binary. One consequence of this is that decimal fractions like 0.1 cannot be represented exactly. The same is true of plain IEEE `double` floats. This makes both highly unsuitable for calculations involving money or other values that should be exact decimal fractions. (Suitably scaled integers, or perhaps rationals, are better choices.)

The `mpf` functions and variables have no special notion of infinity or not-a-number, and applications must take care not to overflow the exponent or results will be unpredictable.

Note that the `mpf` functions are not intended as a smooth extension to IEEE P754 arithmetic. In particular results obtained on one computer often differ from the results on a computer with a different word size.

New projects should consider using the GMP extension library MPFR (http://mpfr.org) instead. MPFR provides well-defined precision and accurate rounding, and thereby naturally extends IEEE P754.

7.1 Initialization Functions

```c
void mpf_set_default_prec (mp_bitcnt_t prec)          [Function]
    Set the default precision to be at least prec bits. All subsequent calls to mpf_init will use this precision, but previously initialized variables are unaffected.

mp_bitcnt_t mpf_get_default_prec (void)               [Function]
    Return the default precision actually used.
```

An `mpf_t` object must be initialized before storing the first value in it. The functions `mpf_init` and `mpf_init2` are used for that purpose.
void mpf_init (mpf_t x)  
Initialize x to 0. Normally, a variable should be initialized once only or at least be cleared, using mpf_clear, between initializations. The precision of x is undefined unless a default precision has already been established by a call to mpf_set_default_prec.

void mpf_init2 (mpf_t x, mp_bitcnt_t prec)  
Initialize x to 0 and set its precision to be at least prec bits. Normally, a variable should be initialized once only or at least be cleared, using mpf_clear, between initializations.

void mpf_inits (mpf_t x, ...)  
Initialize a NULL-terminated list of mpf_t variables, and set their values to 0. The precision of the initialized variables is undefined unless a default precision has already been established by a call to mpf_set_default_prec.

void mpf_clear (mpf_t x)  
Free the space occupied by x. Make sure to call this function for all mpf_t variables when you are done with them.

void mpf_clears (mpf_t x, ...)  
Free the space occupied by a NULL-terminated list of mpf_t variables.

Here is an example on how to initialize floating-point variables:

```c
{  
    mpf_t x, y;
    mpf_init (x); /* use default precision */
    mpf_init2 (y, 256); /* precision at least 256 bits */
    ...
    /* Unless the program is about to exit, do ... */
    mpf_clear (x);
    mpf_clear (y);
}
```

The following three functions are useful for changing the precision during a calculation. A typical use would be for adjusting the precision gradually in iterative algorithms like Newton-Raphson, making the computation precision closely match the actual accurate part of the numbers.

mp_bitcnt_t mpf_get_prec (const mpf_t op)  
Return the current precision of op, in bits.

void mpf_set_prec (mpf_t rop, mp_bitcnt_t prec)  
Set the precision of rop to be at least prec bits. The value in rop will be truncated to the new precision.

This function requires a call to realloc, and so should not be used in a tight loop.

void mpf_set_prec_raw (mpf_t rop, mp_bitcnt_t prec)  
Set the precision of rop to be at least prec bits, without changing the memory allocated.

prec must be no more than the allocated precision for rop, that being the precision when rop was initialized, or in the most recent mpf_set_prec.

The value in rop is unchanged, and in particular if it had a higher precision than prec it will retain that higher precision. New values written to rop will use the new prec.
Before calling `mpf_clear` or the full `mpf_set_prec`, another `mpf_set_prec_raw` call must be made to restore `rop` to its original allocated precision. Failing to do so will have unpredictable results.

`mpf_get_prec` can be used before `mpf_set_prec_raw` to get the original allocated precision. After `mpf_set_prec_raw` it reflects the `prec` value set.

`mpf_set_prec_raw` is an efficient way to use an `mpf_t` variable at different precisions during a calculation, perhaps to gradually increase precision in an iteration, or just to use various different precisions for different purposes during a calculation.

### 7.2 Assignment Functions

These functions assign new values to already initialized floats (see Section 7.1 [Initializing Floats], page 50).

```c
void mpf_set (mpf_t rop, const mpf_t op) [Function]
void mpf_set_ui (mpf_t rop, unsigned long int op) [Function]
void mpf_set_si (mpf_t rop, signed long int op) [Function]
void mpf_set_d (mpf_t rop, double op) [Function]
void mpf_set_z (mpf_t rop, const mpz_t op) [Function]
void mpf_set_q (mpf_t rop, const mpq_t op) [Function]
```

Set the value of `rop` from `op`.

```c
int mpf_set_str (mpf_t rop, const char *str, int base) [Function]
```

Set the value of `rop` from the string in `str`. The string is of the form `M@N` or, if the base is 10 or less, alternatively `MeN`. `M` is the mantissa and `N` is the exponent. The mantissa is always in the specified base. The exponent is either in the specified base or, if `base` is negative, in decimal. The decimal point expected is taken from the current locale, on systems providing `localeconv`.

The argument `base` may be in the ranges 2 to 62, or −62 to −2. Negative values are used to specify that the exponent is in decimal.

For bases up to 36, case is ignored; upper-case and lower-case letters have the same value; for bases 37 to 62, upper-case letter represent the usual 10..35 while lower-case letter represent 36..61.

Unlike the corresponding `mpz` function, the base will not be determined from the leading characters of the string if `base` is 0. This is so that numbers like `0.23` are not interpreted as octal.

White space is allowed in the string, and is simply ignored. [This is not really true; white-space is ignored in the beginning of the string and within the mantissa, but not in other places, such as after a minus sign or in the exponent. We are considering changing the definition of this function, making it fail when there is any white-space in the input, since that makes a lot of sense. Please tell us your opinion about this change. Do you really want it to accept "3 14" as meaning 314 as it does now?]

This function returns 0 if the entire string is a valid number in base `base`. Otherwise it returns −1.

```c
void mpf_swap (mpf_t rop1, mpf_t rop2) [Function]
```

Swap `rop1` and `rop2` efficiently. Both the values and the precisions of the two variables are swapped.
7.3 Combined Initialization and Assignment Functions

For convenience, GMP provides a parallel series of initialize-and-set functions which initialize the output and then store the value there. These functions’ names have the form `mpf_init_set...`

Once the float has been initialized by any of the `mpf_init_set...` functions, it can be used as the source or destination operand for the ordinary float functions. Don’t use an initialize-and-set function on a variable already initialized!

```c
void mpf_init_set (mpf_t rop, const mpf_t op)  // Function
void mpf_init_set_ui (mpf_t rop, unsigned long int op)  // Function
void mpf_init_set_si (mpf_t rop, signed long int op)  // Function
void mpf_init_set_d (mpf_t rop, double op)  // Function
```

Initialize `rop` and set its value from `op`.

The precision of `rop` will be taken from the active default precision, as set by `mpf_set_default_prec`.

```c
int mpf_init_set_str (mpf_t rop, const char *str, int base)  // Function
```

Initialize `rop` and set its value from the string in `str`. See `mpf_set_str` above for details on the assignment operation.

Note that `rop` is initialized even if an error occurs. (I.e., you have to call `mpf_clear` for it.) The precision of `rop` will be taken from the active default precision, as set by `mpf_set_default_prec`.

7.4 Conversion Functions

```c
double mpf_get_d (const mpf_t op)  // Function
  Convert `op` to a `double`, truncating if necessary (i.e. rounding towards zero).
```

If the exponent in `op` is too big or too small to fit a `double` then the result is system dependent. For too big an infinity is returned when available. For too small 0.0 is normally returned. Hardware overflow, underflow and denorm traps may or may not occur.

```c
double mpf_get_d_2exp (signed long int *exp, const mpf_t op)  // Function
  Convert `op` to a `double`, truncating if necessary (i.e. rounding towards zero), and with an exponent returned separately.
```

The return value is in the range $0.5 \leq |d| < 1$ and the exponent is stored to `*exp`. $d \times 2^{exp}$ is the (truncated) `op` value. If `op` is zero, the return is 0.0 and 0 is stored to `*exp`.

This is similar to the standard C `frexp` function (see Section “Normalization Functions” in The GNU C Library Reference Manual).

```c
long mpf_get_si (const mpf_t op)  // Function
unsigned long mpf_get_ui (const mpf_t op)  // Function
  Convert `op` to a `long` or unsigned `long`, truncating any fraction part. If `op` is too big for the return type, the result is undefined.
```

See also `mpf_fits_slong_p` and `mpf_fits_ulong_p` (see Section 7.8 [Miscellaneous Float Functions], page 56).
char * mpf_get_str (char *str, mpf_t *exp, int base, size_t n_digits, const mpf_t op)

Convert op to a string of digits in base base. The base argument may vary from 2 to 62 or from −2 to −36. Up to n_digits digits will be generated. No more digits than can be accurately represented by op are ever generated. If n_digits is 0 then that accurate maximum number of digits are generated.

For base in the range 2..36, digits and lower-case letters are used; for −2..−36, digits and upper-case letters are used; for 37..62, digits, upper-case letters, and lower-case letters (in that significance order) are used.

If str is NULL, the result string is allocated using the current allocation function (see Chapter 13 [Custom Allocation], page 90). The block will be strlen(str)+1 bytes, that being exactly enough for the string and null-terminator.

If str is not NULL, it should point to a block of n_digits + 2 bytes, that being enough for the mantissa, a possible minus sign, and a null-terminator. When n_digits is 0 to get all significant digits, an application won’t be able to know the space required, and str should be NULL in that case.

The generated string is a fraction, with an implicit radix point immediately to the left of the first digit. The applicable exponent is written through the expptr pointer. For example, the number 3.1416 would be returned as string "31416" and exponent 1.

When op is zero, an empty string is produced and the exponent returned is 0.

A pointer to the result string is returned, being either the allocated block or the given str.

7.5 Arithmetic Functions

void mpf_add (mpf_t rop, const mpf_t op1, const mpf_t op2)  
Set rop to op1 + op2.

void mpf_add_ui (mpf_t rop, const mpf_t op1, unsigned long int op2)  
Set rop to op1 + op2.

void mpf_sub (mpf_t rop, const mpf_t op1, const mpf_t op2)  
Set rop to op1 − op2.

void mpf_sub_ui (mpf_t rop, const mpf_t op1, unsigned long int op2)  
Set rop to op1 − op2.

void mpf_mul (mpf_t rop, const mpf_t op1, const mpf_t op2)  
Set rop to op1 × op2.

void mpf_mul_ui (mpf_t rop, const mpf_t op1, unsigned long int op2)  
Set rop to op1 × op2.

Division is undefined if the divisor is zero, and passing a zero divisor to the divide functions will make these functions intentionally divide by zero. This lets the user handle arithmetic exceptions in these functions in the same manner as other arithmetic exceptions.

void mpf_div (mpf_t rop, const mpf_t op1, const mpf_t op2)  
Set rop to op1/op2.

void mpf_ui_div (mpf_t rop, const mpf_t op1, unsigned long int op2)  
Set rop to op1/op2.

void mpf_mpfdiv (mpf_t rop, const mpf_t op1, unsigned long int op2)  
Set rop to op1/op2.

void mpf_sqrt (mpf_t rop, const mpf_t op)  
Set rop to √op.

void mpf_sqrt_ui (mpf_t rop, unsigned long int op)  
Set rop to √op.
void mpf_pow_ui (mpf_t rop, const mpf_t op1, unsigned long int op2)
    Set rop to \( op1^{op2} \).

void mpf_neg (mpf_t rop, const mpf_t op)
    Set rop to \(-op\).

void mpf_abs (mpf_t rop, const mpf_t op)
    Set rop to the absolute value of \( op \).

void mpf_mul_2exp (mpf_t rop, const mpf_t op1, mp_bitcnt_t op2)
    Set rop to \( op1 \times 2^{op2} \).

void mpf_div_2exp (mpf_t rop, const mpf_t op1, mp_bitcnt_t op2)
    Set rop to \( op1 / 2^{op2} \).

7.6 Comparison Functions

int mpf_cmp (const mpf_t op1, const mpf_t op2)
    Compare \( op1 \) and \( op2 \). Return a positive value if \( op1 > op2 \), zero if \( op1 = op2 \), and a negative value if \( op1 < op2 \).

mpf_cmp can be called with an infinity, but results are undefined for a NaN.

int mpf_eq (const mpf_t op1, const mpf_t op2, mp_bitcnt_t op3)
    This function is mathematically ill-defined and should not be used.
    Return non-zero if the first \( op3 \) bits of \( op1 \) and \( op2 \) are equal, zero otherwise. Note that numbers like e.g., 256 (binary 100000000) and 255 (binary 11111111) will never be equal by this function’s measure, and furthermore that 0 will only be equal to itself.

void mpf_reldiff (mpf_t rop, const mpf_t op1, const mpf_t op2)
    Compute the relative difference between \( op1 \) and \( op2 \) and store the result in \( rop \). This is \(|op1 - op2|/op1\).

int mpf_sgn (const mpf_t op)
    Return +1 if \( op > 0 \), 0 if \( op = 0 \), and \(-1\) if \( op < 0 \).
    This function is actually implemented as a macro. It evaluates its argument multiple times.

7.7 Input and Output Functions

Functions that perform input from a stdio stream, and functions that output to a stdio stream, of mpf numbers. Passing a NULL pointer for a stream argument to any of these functions will make them read from stdin and write to stdout, respectively.

When using any of these functions, it is a good idea to include stdio.h before gmp.h, since that will allow gmp.h to define prototypes for these functions.

See also Chapter 10 [Formatted Output], page 72 and Chapter 11 [Formatted Input], page 77.
size_t mpf_out_str (FILE *stream, int base, size_t n_digits, const mpf_t op)

Print op to stream, as a string of digits. Return the number of bytes written, or if an error occurred, return 0.

The mantissa is prefixed with an ‘0.’ and is in the given base, which may vary from 2 to 62 or from −2 to −36. An exponent is then printed, separated by an ‘e’, or if the base is greater than 10 then by an ‘@’. The exponent is always in decimal. The decimal point follows the current locale, on systems providing localeconv.

For base in the range 2..36, digits and lower-case letters are used; for −2..−36, digits and upper-case letters are used; for 37..62, digits, upper-case letters, and lower-case letters (in that significance order) are used.

Up to n_digits will be printed from the mantissa, except that no more digits than are accurately representable by op will be printed. n_digits can be 0 to select that accurate maximum.

size_t mpf_inp_str (mpf_t rop, FILE *stream, int base)

Read a string in base base from stream, and put the read float in rop. The string is of the form ‘M@N’ or, if the base is 10 or less, alternatively ‘MeN’. ‘M’ is the mantissa and ‘N’ is the exponent. The mantissa is always in the specified base. The exponent is either in the specified base or, if base is negative, in decimal. The decimal point expected is taken from the current locale, on systems providing localeconv.

The argument base may be in the ranges 2 to 36, or −36 to −2. Negative values are used to specify that the exponent is in decimal.

Unlike the corresponding mpz function, the base will not be determined from the leading characters of the string if base is 0. This is so that numbers like ‘0.23’ are not interpreted as octal.

Return the number of bytes read, or if an error occurred, return 0.

7.8 Miscellaneous Functions

void mpf.ceil (mpf_t rop, const mpf_t op) [Function]
void mpf.floor (mpf_t rop, const mpf_t op) [Function]
void mpf.trunc (mpf_t rop, const mpf_t op) [Function]

Set rop to op rounded to an integer. mpf.ceil rounds to the next higher integer, mpf.floor to the next lower, and mpf.trunc to the integer towards zero.

int mpf.integer_p (const mpf_t op) [Function]

Return non-zero if op is an integer.

int mpf.fits_ulong_p (const mpf_t op) [Function]
int mpf.fits_slong_p (const mpf_t op) [Function]
int mpf.fits_uint_p (const mpf_t op) [Function]
int mpf.fits_sint_p (const mpf_t op) [Function]
int mpf.fits_ushort_p (const mpf_t op) [Function]
int mpf.fits_sshort_p (const mpf_t op) [Function]

Return non-zero if op would fit in the respective C data type, when truncated to an integer.
void mpf_urandomb (mpf_t rop, gmp_randstate_t state, mp_bitcnt_t nbits)  
Generate a uniformly distributed random float in rop, such that $0 \leq rop < 1$, with nbits significant bits in the mantissa or less if the precision of rop is smaller.

The variable state must be initialized by calling one of the gmp_randinit functions (Section 9.1 [Random State Initialization], page 70) before invoking this function.

void mpf_random2 (mpf_t rop, mp_size_t max_size, mp_exp_t exp)  
Generate a random float of at most max_size limbs, with long strings of zeros and ones in the binary representation. The exponent of the number is in the interval $-exp$ to $exp$ (in limbs). This function is useful for testing functions and algorithms, since these kind of random numbers have proven to be more likely to trigger corner-case bugs. Negative random numbers are generated when max_size is negative.
8 Low-level Functions

This chapter describes low-level GMP functions, used to implement the high-level GMP functions, but also intended for time-critical user code.

These functions start with the prefix mpn_.

The mpn functions are designed to be as fast as possible, not to provide a coherent calling interface. The different functions have somewhat similar interfaces, but there are variations that make them hard to use. These functions do as little as possible apart from the real multiple precision computation, so that no time is spent on things that not all callers need.

A source operand is specified by a pointer to the least significant limb and a limb count. A destination operand is specified by just a pointer. It is the responsibility of the caller to ensure that the destination has enough space for storing the result.

With this way of specifying operands, it is possible to perform computations on subranges of an argument, and store the result into a subrange of a destination.

A common requirement for all functions is that each source area needs at least one limb. No size argument may be zero. Unless otherwise stated, in-place operations are allowed where source and destination are the same, but not where they only partly overlap.

The mpn functions are the base for the implementation of the mpz_, mpf_, and mpq_ functions.

This example adds the number beginning at s1p and the number beginning at s2p and writes the sum at destp. All areas have n limbs.

\[
\text{cy} = \text{mpn\_add\_n} \ (\text{destp}, \ s1p, \ s2p, \ n)
\]

It should be noted that the mpn functions make no attempt to identify high or low zero limbs on their operands, or other special forms. On random data such cases will be unlikely and it’d be wasteful for every function to check every time. An application knowing something about its data can take steps to trim or perhaps split its calculations.

In the notation used below, a source operand is identified by the pointer to the least significant limb, and the limb count in braces. For example, \{s1p, s1n\}.

\[
\begin{align*}
\text{mp\_limb\_t} & \quad \text{mpn\_add\_n} \ (\text{mp\_limb\_t} \ *rp, \ \text{const mp\_limb\_t} \ *s1p, \ \text{const mp\_limb\_t} \ *s2p, \ \text{mp\_size\_t} \ n) \\
& \quad \text{Add} \ \{s1p, n\} \ \text{and} \ \{s2p, n\}, \ \text{and write the} \ n \ \text{least significant limbs of the result to} \ rp. \ \text{Return carry, either 0 or 1.}
\end{align*}
\]

This is the lowest-level function for addition. It is the preferred function for addition, since it is written in assembly for most CPUs. For addition of a variable to itself (i.e., s1p equals s2p) use mpn_lshift with a count of 1 for optimal speed.

\[
\begin{align*}
\text{mp\_limb\_t} & \quad \text{mpn\_add\_1} \ (\text{mp\_limb\_t} \ *rp, \ \text{const mp\_limb\_t} \ *s1p, \ \text{mp\_size\_t} \ n, \ \text{mp\_limb\_t} \ s2\text{limb}) \\
& \quad \text{Add} \ \{s1p, n\} \ \text{and} \ s2\text{limb}, \ \text{and write the} \ n \ \text{least significant limbs of the result to} \ rp. \ \text{Return carry, either 0 or 1.}
\end{align*}
\]

\[
\begin{align*}
\text{mp\_limb\_t} & \quad \text{mpn\_add} \ (\text{mp\_limb\_t} \ *rp, \ \text{const mp\_limb\_t} \ *s1p, \ \text{mp\_size\_t} \ s1n, \ \text{const mp\_limb\_t} \ *s2p, \ \text{mp\_size\_t} \ s2n) \\
& \quad \text{Add} \ \{s1p, s1n\} \ \text{and} \ \{s2p, s2n\}, \ \text{and write the} \ s1n \ \text{least significant limbs of the result to} \ rp. \ \text{Return carry, either 0 or 1.}
\end{align*}
\]
This function requires that $s1n$ is greater than or equal to $s2n$.

\[
\text{mp_limb_t mpn_sub_n (mp_limb_t *rp, const mp_limb_t *s1p, const mp_limb_t *s2p, mp_size_t n)}
\]

Subtract $\{s2p, n\}$ from $\{s1p, n\}$, and write the $n$ least significant limbs of the result to $rp$. Return borrow, either 0 or 1.

This is the lowest-level function for subtraction. It is the preferred function for subtraction, since it is written in assembly for most CPUs.

\[
\text{mp_limb_t mpn_sub_1 (mp_limb_t *rp, const mp_limb_t *s1p, mp_size_t n, mp_limb_t s2limb)}
\]

Subtract $s2limb$ from $\{s1p, n\}$, and write the $n$ least significant limbs of the result to $rp$. Return borrow, either 0 or 1.

\[
\text{mp_limb_t mpn_sub (mp_limb_t *rp, const mp_limb_t *s1p, mp_size_t s1n, const mp_limb_t *s2p, mp_size_t s2n)}
\]

Subtract $\{s2p, s2n\}$ from $\{s1p, s1n\}$, and write the $s1n$ least significant limbs of the result to $rp$. Return borrow, either 0 or 1.

This function requires that $s1n$ is greater than or equal to $s2n$.

\[
\text{mp_limb_t mpn_neg (mp_limb_t *rp, const mp_limb_t *sp, mp_size_t n)}
\]

Perform the negation of $\{sp, n\}$, and write the result to $\{rp, n\}$. This is equivalent to calling \text{mpn_sub_n} with a $n$-limb zero minuend and passing $\{sp, n\}$ as subtrahend. Return borrow, either 0 or 1.

\[
\text{void mpn_mul_n (mp_limb_t *rp, const mp_limb_t *s1p, const mp_limb_t *s2p, mp_size_t n)}
\]

Multiply $\{s1p, n\}$ and $\{s2p, n\}$, and write the $2^*n$-limb result to $rp$. The destination has to have space for $2^*n$ limbs, even if the product’s most significant limb is zero. No overlap is permitted between the destination and either source.

If the two input operands are the same, use \text{mpn_sqr}.

\[
\text{mp_limb_t mpn.mul (mp_limb_t *rp, const mp_limb_t *s1p, mp_size_t s1n, const mp_limb_t *s2p, mp_size_t s2n)}
\]

Multiply $\{s1p, s1n\}$ and $\{s2p, s2n\}$, and write the $(s1n+s2n)$-limb result to $rp$. Return the most significant limb of the result.

The destination has to have space for $s1n + s2n$ limbs, even if the product’s most significant limb is zero. No overlap is permitted between the destination and either source.

This function requires that $s1n$ is greater than or equal to $s2n$.

\[
\text{void mpn.sqr (mp_limb_t *rp, const mp_limb_t *s1p, mp_size_t n)}
\]

Compute the square of $\{s1p, n\}$ and write the $2^*n$-limb result to $rp$.

The destination has to have space for $2n$ limbs, even if the result’s most significant limb is zero. No overlap is permitted between the destination and the source.
mp_limb_t mpn_mul_1 (mp_limb_t *rp, const mp_limb_t *s1p, mp_size_t n, mp_limb_t s2limb)  
Multiply \{s1p, n\} by \s2limb, and write the \n least significant limbs of the product to \rp. 
Return the most significant limb of the product, \n\{s1p, n\} and \{rp, n\} are allowed to overlap 
provided \rp \leq \s1p.

This is a low-level function that is a building block for general multiplication as well as other 
operations in GMP. It is written in assembly for most CPUs.

Don’t call this function if \s2limb is a power of 2; use \mpn_lshift with a count equal to the 
logarithm of \s2limb instead, for optimal speed.

mp_limb_t mpn_addmul_1 (mp_limb_t *rp, const mp_limb_t *s1p, mp_size_t n, mp_limb_t s2limb)  
Multiply \{s1p, n\} and \s2limb, and add the \nleast significant limbs of the product to \{\rp, \n\} and write the result to \rp. Return the most significant limb of the product, plus carry-out 
from the addition. \{s1p, n\} and \{rp, n\} are allowed to overlap provided \rp \leq \s1p.

This is a low-level function that is a building block for general multiplication as well as other 
operations in GMP. It is written in assembly for most CPUs.

mp_limb_t mpn_submul_1 (mp_limb_t *rp, const mp_limb_t *s1p, mp_size_t n, mp_limb_t s2limb)  
Multiply \{s1p, n\} and \s2limb, and subtract the \nleast significant limbs of the product from \{\rp, \n\} and write the result to \rp. Return the most significant limb of the product, plus 
borrow-out from the subtraction. \{s1p, n\} and \{rp, n\} are allowed to overlap provided \rp \leq \s1p.

This is a low-level function that is a building block for general multiplication and division as 
well as other operations in GMP. It is written in assembly for most CPUs.

void mpn_tdiv_qr (mp_limb_t *qp, mp_limb_t *rp, mp_size_t qxn, const 
mp_limb_t *np, mp_size_t nn, const mp_limb_t *dp, mp_size_t dn)  
Divide \{np, nn\} by \{dp, dn\} and put the quotient at \{qp, \nn–\dn+1\} and the remainder at 
\{rp, \dn\}. The quotient is rounded towards 0.

No overlap is permitted between arguments, except that \np might equal \rp. The dividend 
size \nn must be greater than or equal to divisor size \dn. The most significant limb of the 
divisor must be non-zero. The \qxn operand must be zero.

mp_limb_t mpn_divrem (mp_limb_t *rp, mp_size_t qxn, mp_limb_t *rs2p, 
mp_size_t rs2n, const mp_limb_t *s3p, mp_size_t s3n)  
[This function is obsolete. Please call \mpn_tdiv_qr instead for best performance.]

Divide \{rs2p, rs2n\} by \{s3p, s3n\}, and write the quotient at \r1p, with the exception of the 
most significant limb, which is returned. The remainder replaces the dividend at \rs2p; it will 
be \s3n limbs long (i.e., as many limbs as the divisor).

In addition to an integer quotient, \qxn fraction limbs are developed, and stored after the 
integral limbs. For most usages, \qxn will be zero.

It is required that \rs2n is greater than or equal to \s3n. It is required that the most significant 
bit of the divisor is set.

If the quotient is not needed, pass \rs2p + \s3n as \r1p. Aside from that special case, no overlap 
between arguments is permitted.
Return the most significant limb of the quotient, either 0 or 1.

The area at \( r1p \) needs to be \( rs2n - s3n + qxn \) limbs large.

```
mp_limb_t mpn_divrem_1 (mp_limb_t *r1p, mp_size_t qxn, mp_limb_t *s2p,  
                       mp_size_t s2n, mp_limb_t s3limb)  
```

```
mp_limb_t mpn_divmod_1 (mp_limb_t *r1p, mp_limb_t *s2p, mp_size_t s2n,  
                       mp_limb_t s3limb)  
```

Divide \( \{s2p, s2n\} \) by \( s3limb \), and write the quotient at \( r1p \). Return the remainder.

The integer quotient is written to \( \{r1p + qxn, s2n\} \) and in addition \( qxn \) fraction limbs are developed and written to \( \{r1p, qxn\} \). Either or both \( s2n \) and \( qxn \) can be zero. For most usages, \( qxn \) will be zero.

\( \text{mpn\_divmod\_1} \) exists for upward source compatibility and is simply a macro calling \( \text{mpn\_divrem\_1} \) with a \( qxn \) of 0.

The areas at \( r1p \) and \( s2p \) have to be identical or completely separate, not partially overlapping.

```
mp_limb_t mpn_divmod (mp_limb_t *r1p, mp_limb_t *rs2p, mp_size_t rs2n,  
                      const mp_limb_t *s3p, mp_size_t s3n)  
```

[This function is obsolete. Please call \( \text{mpn\_tdiv\_qr} \) instead for best performance.]

```
void mpn_divexact_1 (mp_limb_t *rp, const mp_limb_t *sp, mp_size_t n,  
                     mp_limb_t d)  
```

Divide \( \{sp, n\} \) by \( d \), expecting it to divide exactly, and writing the result to \( \{rp, n\} \). If \( d \) doesn’t divide exactly, the value written to \( \{rp, n\} \) is undefined. The areas at \( rp \) and \( sp \) have to be identical or completely separate, not partially overlapping.

```
mp_limb_t mpn_divexact_by3 (mp_limb_t *rp, mp_limb_t *sp, mp_size_t n)  
```

```
mp_limb_t mpn_divexact_by3c (mp_limb_t *rp, mp_limb_t *sp,  
                           mp_size_t n, mp_limb_t carry)  
```

Divide \( \{sp, n\} \) by 3, expecting it to divide exactly, and writing the result to \( \{rp, n\} \). If 3 divides exactly, the return value is zero and the result is the quotient. If not, the return value is non-zero and the result won’t be anything useful.

\( \text{mpn\_divexact\_by3c} \) takes an initial carry parameter, which can be the return value from a previous call, so a large calculation can be done piece by piece from low to high. \( \text{mpn\_divexact\_by3c} \) is simply a macro calling \( \text{mpn\_divexact\_by3c} \) with a 0 carry parameter.

These routines use a multiply-by-inverse and will be faster than \( \text{mpn\_divrem\_1} \) on CPUs with fast multiplication but slow division.

The source \( a \), result \( q \), size \( n \), initial carry \( i \), and return value \( c \) satisfy \( cb^n + a - i = 3q \), where \( b = \text{GMP\_NUMB\_BITS} \). The return \( c \) is always 0, 1 or 2, and the initial carry \( i \) must also be 0, 1 or 2 (these are both borrows really). When \( c = 0 \) clearly \( q = (a - i)/3 \). When \( c \neq 0 \), the remainder \( (a - i) \mod 3 \) is given by \( 3 - c \), because \( b \equiv 1 \mod 3 \) (when \( \text{mp\_bits\_per\_limb} \) is even, which is always so currently).

```
mp_limb_t mpn_mod_1 (const mp_limb_t *s1p, mp_size_t s1n, mp_limb_t s2limb)  
```

Divide \( \{s1p, s1n\} \) by \( s2limb \), and return the remainder. \( s1n \) can be zero.
mp_limb_t mpn_lshift (mp_limb_t *rp, const mp_limb_t *sp, mp_size_t n, unsigned int count)
Shift \{sp, n\} left by count bits, and write the result to \{rp, n\}. The bits shifted out at the left are returned in the least significant count bits of the return value (the rest of the return value is zero).

count must be in the range 1 to mp_bits_per_limb−1. The regions \{sp, n\} and \{rp, n\} may overlap, provided rp ≥ sp.
This function is written in assembly for most CPUs.

mp_limb_t mpn_rshift (mp_limb_t *rp, const mp_limb_t *sp, mp_size_t n, unsigned int count)
Shift \{sp, n\} right by count bits, and write the result to \{rp, n\}. The bits shifted out at the right are returned in the most significant count bits of the return value (the rest of the return value is zero).

count must be in the range 1 to mp_bits_per_limb−1. The regions \{sp, n\} and \{rp, n\} may overlap, provided rp ≤ sp.
This function is written in assembly for most CPUs.

int mpn_cmp (const mp_limb_t *s1p, const mp_limb_t *s2p, mp_size_t n)
Compare \{s1p, n\} and \{s2p, n\} and return a positive value if s1 > s2, 0 if they are equal, or a negative value if s1 < s2.

int mpn_zero_p (const mp_limb_t *sp, mp_size_t n)
Test \{sp, n\} and return 1 if the operand is zero, 0 otherwise.

mp_size_t mpn_gcd (mp_limb_t *rp, mp_limb_t *xp, mp_size_t xn, mp_limb_t *yp, mp_size_t yn)
Set \{rp, retval\} to the greatest common divisor of \{xp, xn\} and \{yp, yn\}. The result can be up to yn limbs, the return value is the actual number produced. Both source operands are destroyed.

It is required that xn ≥ yn > 0, the most significant limb of \{yp, yn\} must be non-zero, and at least one of the two operands must be odd. No overlap is permitted between \{xp, xn\} and \{yp, yn\}.

mp_limb_t mpn_gcd_1 (const mp_limb_t *xp, mp_size_t xn, mp_limb_t y1limb)
Return the greatest common divisor of \{xp, xn\} and y1limb. Both operands must be non-zero.

mp_size_t mpn_gcdext (mp_limb_t *gp, mp_limb_t *sp, mp_size_t *sn, mp_limb_t *up, mp_size_t un, mp_limb_t *vp, mp_size_t vn)
Let U be defined by \{up, un\} and let V be defined by \{vp, vn\}.

Compute the greatest common divisor G of U and V. Compute a cofactor S such that \(G = US + VT\). The second cofactor T is not computed but can easily be obtained from \((G − US)/V\) (the division will be exact). It is required that un ≥ vn > 0, and the most significant limb of \{vp, vn\} must be non-zero.

S satisfies \(|S| < V/(2G)\). S = 0 if and only if V divides U (i.e., \(G = V\)).
Store \( G \) at \( gp \) and let the return value define its limb count. Store \( S \) at \( sp \) and let \(|*sn|\) define its limb count. \( S \) can be negative; when this happens \(*sn\) will be negative. The area at \( gp \) should have room for \( vn \) limbs and the area at \( sp \) should have room for \( vn + 1 \) limbs.

Both source operands are destroyed.

Compatibility notes: GMP 4.3.0 and 4.3.1 defined \( S \) less strictly. Earlier as well as later GMP releases define \( S \) as described here. GMP releases before GMP 4.3.0 required additional space for both input and output areas. More precisely, the areas \( \{up, un+1\} \) and \( \{vp, vn+1\} \) were destroyed (i.e. the operands plus an extra limb past the end of each), and the areas pointed to by \( gp \) and \( sp \) should each have room for \( un + 1 \) limbs.

\[
\text{mp\_size\_t mpn\_sqrtrem (mp\_limb\_t } r1p, mp\_limb\_t } r2p, \text{ const mp\_limb\_t } sp, \text{ mp\_size\_t } n) \]

Compute the square root of \( \{sp, n\} \) and put the result at \( \{r1p, \lceil n/2 \rceil\} \) and the remainder at \( \{r2p, \text{retval}\} \). \( r2p \) needs space for \( n \) limbs, but the return value indicates how many are produced.

The most significant limb of \( \{sp, n\} \) must be non-zero. The areas \( \{r1p, \lceil n/2 \rceil\} \) and \( \{sp, n\} \) must be completely separate. The areas \( \{r2p, n\} \) and \( \{sp, n\} \) must be either identical or completely separate.

If the remainder is not wanted then \( r2p \) can be \texttt{NULL}, and in this case the return value is zero or non-zero according to whether the remainder would have been zero or non-zero.

A return value of zero indicates a perfect square. See also \texttt{mpn\_perfect\_square\_p}.

\[
\text{size\_t mpn\_sizeinbase (const mp\_limb\_t } xp, \text{ mp\_size\_t } n, \text{ int } base) } \]

Return the size of \( \{xp,n\} \) measured in number of digits in the given \( base \). \( base \) can vary from 2 to 62. Requires \( n > 0 \) and \( xp[n-1] > 0 \). The result will be either exact or 1 too big. If \( base \) is a power of 2, the result is always exact.

\[
\text{mp\_size\_t mpn\_get\_str (unsigned char } *str, \text{ int } base, \text{ mp\_limb\_t } s1p, \text{ mp\_size\_t } s1n) } \]

Convert \( \{s1p, s1n\} \) to a raw unsigned char array at \( str \) in base \( base \), and return the number of characters produced. There may be leading zeros in the string. The string is not in ASCII; to convert it to printable format, add the ASCII codes for ‘0’ or ‘A’, depending on the base and range. \( base \) can vary from 2 to 256.

The most significant limb of the input \( \{s1p, s1n\} \) must be non-zero. The input \( \{s1p, s1n\} \) is clobbered, except when \( base \) is a power of 2, in which case it’s unchanged.

The area at \( str \) has to have space for the largest possible number represented by a \( s1n \) long limb array, plus one extra character.

\[
\text{mp\_size\_t mpn\_set\_str (mp\_limb\_t } rp, \text{ const unsigned char } *str, \text{ size\_t } strsize, \text{ int } base) } \]

Convert bytes \( \{str,strsize\} \) in the given \( base \) to limbs at \( rp \).

\( str[0] \) is the most significant input byte and \( str[strsize-1] \) is the least significant input byte. Each byte should be a value in the range 0 to \( base - 1 \), not an ASCII character. \( base \) can vary from 2 to 256.

The converted value is \( \{rp, rn\} \) where \( rn \) is the return value. If the most significant input byte \( str[0] \) is non-zero, then \( rp[rn-1] \) will be non-zero, else \( rp[rn-1] \) and some number of subsequent limbs may be zero.
The area at \( rp \) has to have space for the largest possible number with \( strsize \) digits in the chosen base, plus one extra limb.

The input must have at least one byte, and no overlap is permitted between \{\( str, strsize \)} and the result at \( rp \).

\[
\text{mp\_bitcnt\_t mpn\_scan0 (const mp\_limb\_t *s1p, mp\_bitcnt\_t bit)}
\]

Scan \( s1p \) from bit position \( bit \) for the next clear bit.

It is required that there be a clear bit within the area at \( s1p \) at or beyond bit position \( bit \), so that the function has something to return.

\[
\text{mp\_bitcnt\_t mpn\_scan1 (const mp\_limb\_t *s1p, mp\_bitcnt\_t bit)}
\]

Scan \( s1p \) from bit position \( bit \) for the next set bit.

It is required that there be a set bit within the area at \( s1p \) at or beyond bit position \( bit \), so that the function has something to return.

\[
\text{void mpn\_random (mp\_limb\_t *r1p, mp\_size\_t r1n)}
\]

Generate a random number of length \( r1n \) and store it at \( r1p \). The most significant limb is always non-zero. \text{mpn\_random} generates uniformly distributed limb data, \text{mpn\_random2} generates long strings of zeros and ones in the binary representation.

\text{mpn\_random2} is intended for testing the correctness of the \text{mpn} routines.

\[
\text{mp\_bitcnt\_t mpn\_popcount (const mp\_limb\_t *s1p, mp\_size\_t n)}
\]

Count the number of set bits in \{\( s1p, n \}\}.

\[
\text{mp\_bitcnt\_t mpn\_hamdist (const mp\_limb\_t *s1p, const mp\_limb\_t *s2p, mp\_size\_t n)}
\]

Compute the hamming distance between \{\( s1p, n \}\} and \{\( s2p, n \}\}, which is the number of bit positions where the two operands have different bit values.

\[
\text{int mpn\_perfect\_square\_p (const mp\_limb\_t *s1p, mp\_size\_t n)}
\]

Return non-zero iff \{\( s1p, n \}\} is a perfect square. The most significant limb of the input \{\( s1p, n \}\} must be non-zero.

\[
\text{void mpn\_and\_n (mp\_limb\_t *rp, const mp\_limb\_t *s1p, const mp\_limb\_t *s2p, mp\_size\_t n)}
\]

Perform the bitwise logical and of \{\( s1p, n \}\} and \{\( s2p, n \}\}, and write the result to \{\( rp, n \}\}.

\[
\text{void mpn\_ior\_n (mp\_limb\_t *rp, const mp\_limb\_t *s1p, const mp\_limb\_t *s2p, mp\_size\_t n)}
\]

Perform the bitwise logical inclusive or of \{\( s1p, n \}\} and \{\( s2p, n \}\}, and write the result to \{\( rp, n \}\}.

\[
\text{void mpn\_xor\_n (mp\_limb\_t *rp, const mp\_limb\_t *s1p, const mp\_limb\_t *s2p, mp\_size\_t n)}
\]

Perform the bitwise logical exclusive or of \{\( s1p, n \}\} and \{\( s2p, n \}\}, and write the result to \{\( rp, n \}\}.
void mpn_andn_n (mp_limb_t *rp, const mp_limb_t *s1p, const mp_limb_t *s2p, mp_size_t n)  
  Perform the bitwise logical and of \{s1p, n\} and the bitwise complement of \{s2p, n\}, and write the result to \{rp, n\}.

void mpn_iorn_n (mp_limb_t *rp, const mp_limb_t *s1p, const mp_limb_t *s2p, mp_size_t n)  
  Perform the bitwise logical inclusive or of \{s1p, n\} and the bitwise complement of \{s2p, n\}, and write the result to \{rp, n\}.

void mpn_nand_n (mp_limb_t *rp, const mp_limb_t *s1p, const mp_limb_t *s2p, mp_size_t n)  
  Perform the bitwise logical and of \{s1p, n\} and \{s2p, n\}, and write the bitwise complement of the result to \{rp, n\}.

void mpn_nior_n (mp_limb_t *rp, const mp_limb_t *s1p, const mp_limb_t *s2p, mp_size_t n)  
  Perform the bitwise logical inclusive or of \{s1p, n\} and \{s2p, n\}, and write the bitwise complement of the result to \{rp, n\}.

void mpn_xnor_n (mp_limb_t *rp, const mp_limb_t *s1p, const mp_limb_t *s2p, mp_size_t n)  
  Perform the bitwise logical exclusive or of \{s1p, n\} and \{s2p, n\}, and write the bitwise complement of the result to \{rp, n\}.

void mpn_com (mp_limb_t *rp, const mp_limb_t *sp, mp_size_t n)  
  Perform the bitwise complement of \{sp, n\}, and write the result to \{rp, n\}.

void mpn_copyi (mp_limb_t *rp, const mp_limb_t *s1p, mp_size_t n)  
  Copy from \{s1p, n\} to \{rp, n\}, increasingly.

void mpn_copyd (mp_limb_t *rp, const mp_limb_t *s1p, mp_size_t n)  
  Copy from \{s1p, n\} to \{rp, n\}, decreasingly.

void mpn_zero (mp_limb_t *rp, mp_size_t n)  
  Zero \{rp, n\}.

8.1 Low-level functions for cryptography

The functions prefixed with mpn_sec_ and mpn_cnd_ are designed to perform the exact same low-level operations and have the same cache access patterns for any two same-size arguments, assuming that function arguments are placed at the same position and that the machine state is identical upon function entry. These functions are intended for cryptographic purposes, where resilience to side-channel attacks is desired.

These functions are less efficient than their “leaky” counterparts; their performance for operands of the sizes typically used for cryptographic applications is between 15% and 100% worse. For larger operands, these functions might be inadequate, since they rely on asymptotically elementary algorithms.

These functions do not make any explicit allocations. Those of these functions that need scratch space accept a scratch space operand. This convention allows callers to keep sensitive data in
dened memory areas. Note however that compilers may choose to spill scalar values used within these functions to their stack frame and that such scalars may contain sensitive data.

In addition to these specially crafted functions, the following mpn functions are naturally side-channel resistant: mpn_add_n, mpn_sub_n, mpn_lshift, mpn_rshift, mpn_zero, mpn_copyi, mpn_copyd, mpn_com, and the logical function (mpn_and_n, etc).

There are some exceptions from the side-channel resilience: (1) Some assembly implementations of mpn_lshift identify shift-by-one as a special case. This is a problem iff the shift count is a function of sensitive data. (2) Alpha ev6 and Pentium4 using 64-bit limbs have leaky mpn_add_n and mpn_sub_n. (3) Alpha ev6 has a leaky mpn_mul_1 which also makes mpn_sec_mul on those systems unsafe.

#define mpn_sec_mul_itch (mpn_sec_mul, mpn_sec_mul_1)
#define mpn_sec_add_1_itch (mpn_sec_add_1)
#define mpn_sec_sub_1_itch (mpn_sec_sub_1)

void mpn_cnd_swap (mpn_limb_t cnd, volatile mpn_limb_t *ap, volatile
    mpn_limb_t *bp, mpn_size_t n) [Function]

If cnd is non-zero, swaps the contents of the areas {ap,n} and {bp,n}. Otherwise, the areas are left unmodified. Implemented using logical operations on the limbs, with the same memory access patterns depending only on size and location of the data areas, but independent of the condition cnd. Like for mpn_add_n and mpn_sub_n, on most machines, the timing will also be independent of the actual limb values.

These functions do conditional addition and subtraction. If cnd is non-zero, they produce the same result as a regular mpn_add_n or mpn_sub_n, and if cnd is zero, they copy {s1p,n} to the result area and return zero. The functions are designed to have timing and memory access patterns independent of the value of cnd.

#define mpn_lshift (mpn_lshift, mpn_lshift_1)

These functions take $O(N)$ time, unlike the leaky functions mpn_add_1 which are $O(1)$ on average. They require scratch space of mpn_sec_add_1_itch(n) and mpn_sec_sub_1_itch(n) limbs, respectively, to be passed in the tp parameter. The scratch space requirements are guaranteed to be at most n limbs, and increase monotonously in the operand size.

void mpn_cnd_add_n (mpn_limb_t cnd, mpn_limb_t *rp, const
    mpn_limb_t *s1p, const mpn_limb_t *s2p, mpn_size_t n) [Function]

mpn_cnd_sub_n (mpn_limb_t cnd, mpn_limb_t *rp, const
    mpn_limb_t *s1p, const mpn_limb_t *s2p, mpn_size_t n) [Function]

Set R to A + b or A - b, respectively, where R = \{ rp,n \}, A = \{ ap,n \}, and b is a single limb. Returns carry.

These functions do conditional addition and subtraction. If cnd is non-zero, they produce the same result as a regular mpn_add_n or mpn_sub_n, and if cnd is zero, they copy {s1p,n} to the result area and return zero. The functions are designed to have timing and memory access patterns independent of the value of cnd.

#define mpn_sec_add_1 (mpn_sec_add_1, mpn_sec_add_1_1)
#define mpn_sec_sub_1 (mpn_sec_sub_1, mpn_sec_sub_1_1)

These functions take $O(N)$ time, unlike the leaky functions mpn_add_1 which are $O(1)$ on average. They require scratch space of mpn_sec_add_1_itch(n) and mpn_sec_sub_1_itch(n) limbs, respectively, to be passed in the tp parameter. The scratch space requirements are guaranteed to be at most n limbs, and increase monotonously in the operand size.

mpn_cnd_add_n (mpn_limb_t cnd, mpn_limb_t *rp, const
    mpn_limb_t *ap, mpn_size_t n, mpn_limb_t *bp, mpn_limb_t *tp) [Function]

mpn_sec_add_1 (mpn_limb_t *rp, const mpn_limb_t *ap, mpn_size_t n, mpn_limb_t *bp, mpn_limb_t *tp) [Function]

mpn_sec_sub_1 (mpn_limb_t *rp, const mpn_limb_t *ap, mpn_size_t n, mpn_limb_t *bp, mpn_limb_t *tp) [Function]

These functions take $O(N)$ time, unlike the leaky functions mpn_add_1 which are $O(1)$ on average. They require scratch space of mpn_sec_add_1_itch(n) and mpn_sec_sub_1_itch(n) limbs, respectively, to be passed in the tp parameter. The scratch space requirements are guaranteed to be at most n limbs, and increase monotonously in the operand size.

void mpn_cnd_swap (mpn_limb_t cnd, volatile mpn_limb_t *ap, volatile
    mpn_limb_t *bp, mpn_size_t n) [Function]

If cnd is non-zero, swaps the contents of the areas {ap,n} and {bp,n}. Otherwise, the areas are left unmodified. Implemented using logical operations on the limbs, with the same memory accesses independent of the value of cnd.

void mpn_sec_mul (mpn_limb_t *rp, const mpn_limb_t *ap, mpn_size_t an, const
    mpn_limb_t *bp, mpn_size_t bn, mpn_limb_t *tp) [Function]

mpn_sec_mul_itch (mpn_size_t an, mpn_size_t bn) [Function]

Set R to A × B, where A = \{ ap,an \}, B = \{ bp,bn \}, and R = \{ rp,an + bn \}.

It is required that an ≥ bn > 0.

No overlapping between R and the input operands is allowed. For A = B, use mpn_sec_sqr for optimal performance.

This function requires scratch space of mpn_sec_mul_itch(an, bn) limbs to be passed in the tp parameter. The scratch space requirements are guaranteed to increase monotonously in the operand sizes.
void mpn_sec_sqr (mp_limb_t *rp, const mp_limb_t *ap, mp_size_t an,      [Function]      mp_limb_t *tp)          

mp_size_t mpn_sec_sqr_itch (mp_size_t an)                             [Function]  

Set $R$ to $A^2$, where $A = \{ap,an\}$, and $R = \{rp,2an\}$.  

It is required that $an > 0$.  

No overlapping between $R$ and the input operands is allowed.  

This function requires scratch space of $\text{mpn_sec_sqr_itch}(an)$ limbs to be passed in the $tp$ parameter. The scratch space requirements are guaranteed to increase monotonously in the operand size.

void mpn_sec_powm (mp_limb_t *rp, const mp_limb_t *bp, mp_size_t bn,          [Function]      const mp_limb_t *ep, mp_bitcnt_t enb, const mp_limb_t *mp, mp_size_t n,      mp_limb_t *tp)          

mp_size_t mpn_sec_powm_itch (mp_size_t bn, mp_bitcnt_t enb, size_t n)      [Function]  

Set $R$ to $B^E \mod M$, where $R = \{rp,n\}$, $M = \{mp,n\}$, and $E = \{ep,\lceil\text{enb}/\text{GMP_NUMB_BITS}\rceil\}$.  

It is required that $B > 0$, that $M > 0$ is odd, and that $E < 2^{\text{enb}}$, with $\text{enb} > 0$.  

No overlapping between $R$ and the input operands is allowed.  

This function requires scratch space of $\text{mpn_sec_powm_itch}(bn, \text{enb}, n)$ limbs to be passed in the $tp$ parameter. The scratch space requirements are guaranteed to increase monotonously in the operand sizes.

void mpn_sec_tabselect (mp_size_t *rp, const mp_size_t *tab, size_t n,      [Function]      size_t nents, mp_size_t which)  

Select entry which from table tab, which has nents entries, each $n$ limbs. Store the selected entry at $rp$.  

This function reads the entire table to avoid side-channel information leaks.

mp_limb_t mpn_sec_div_qr (mp_limb_t *qp, mp_limb_t *np, mp_size_t nn,          [Function]      const mp_limb_t *dp, mp_size_t dn, mp_limb_t *tp)          

mp_size_t mpn_sec_div_qr_itch (mp_size_t nn, mp_size_t dn)      [Function]  

Set $Q$ to $\lfloor N/D\rfloor$ and $R$ to $N \mod D$, where $N = \{np,nn\}$, $D = \{dp,dn\}$, $Q$’s most significant limb is the function return value and the remaining limbs are $\{qp,nn-dn\}$, and $R = \{np,dn\}$.  

It is required that $nn \geq dn \geq 1$, and that $dp[dn-1] \neq 0$. This does not imply that $N \geq D$ since $N$ might be zero-padded.  

Note the overlapping between $N$ and $R$. No other operand overlapping is allowed. The entire space occupied by $N$ is overwritten.  

This function requires scratch space of $\text{mpn_sec_div_qr_itch}(nn, dn)$ limbs to be passed in the $tp$ parameter.

void mpn_sec_div_r (mp_limb_t *np, mp_size_t nn, const mp_limb_t *dp,      [Function]      mp_size_t dn, mp_limb_t *tp)          

mp_size_t mpn_sec_div_r_itch (mp_size_t nn, mp_size_t dn)      [Function]  

Set $R$ to $N \mod D$, where $N = \{np,nn\}$, $D = \{dp,dn\}$, and $R = \{np,dn\}$.  

It is required that $nn \geq dn \geq 1$, and that $dp[dn-1] \neq 0$. This does not imply that $N \geq D$ since $N$ might be zero-padded.
Note the overlapping between $N$ and $R$. No other operand overlapping is allowed. The entire space occupied by $N$ is overwritten.

This function requires scratch space of $\text{mpn\_sec\_div\_r\_itch}(nn, dn)$ limbs to be passed in the $tp$ parameter.

```c
int mpn_sec_invert (mp_limb_t *rp, mp_limb_t *ap, const mp_limb_t *mp,
                   mp_size_t n, mp_bitcnt_t nbcnt, mp_limb_t *tp)
```

Set $R$ to $A^{-1} \mod M$, where $R = \{rp, n\}$, $A = \{ap, n\}$, and $M = \{mp, n\}$. This function’s interface is preliminary.

If an inverse exists, return 1, otherwise return 0 and leave $R$ undefined. In either case, the input $A$ is destroyed.

It is required that $M$ is odd, and that $nbcnt \geq \lceil \log(A + 1) \rceil + \lceil \log(M + 1) \rceil$. A safe choice is $nbcnt = 2n \times \text{GMP\_NUMB\_BITS}$, but a smaller value might improve performance if $M$ or $A$ are known to have leading zero bits.

This function requires scratch space of $\text{mpn\_sec\_invert\_itch}(n)$ limbs to be passed in the $tp$ parameter.

### 8.2 Nails

Everything in this section is highly experimental and may disappear or be subject to incompatible changes in a future version of GMP.

Nails are an experimental feature whereby a few bits are left unused at the top of each $\text{mp\_limb\_t}$. This can significantly improve carry handling on some processors.

All the $\text{mpn}$ functions accepting limb data will expect the nail bits to be zero on entry, and will return data with the nails similarly all zero. This applies both to limb vectors and to single limb arguments.

Nails can be enabled by configuring with ‘--enable-nails’. By default the number of bits will be chosen according to what suits the host processor, but a particular number can be selected with ‘--enable-nails=N’.

At the $\text{mpn}$ level, a nail build is neither source nor binary compatible with a non-nail build, strictly speaking. But programs acting on limbs only through the $\text{mpn}$ functions are likely to work equally well with either build, and judicious use of the definitions below should make any program compatible with either build, at the source level.

For the higher level routines, meaning $\text{mpz}$ etc, a nail build should be fully source and binary compatible with a non-nail build.

```
GMP_NAIL_BITS [Macro]
GMP_NUMB_BITS  [Macro]
GMP_LIMB_BITS  [Macro]
```

$\text{GMP\_NAIL\_BITS}$ is the number of nail bits, or 0 when nails are not in use. $\text{GMP\_NUMB\_BITS}$ is the number of data bits in a limb. $\text{GMP\_LIMB\_BITS}$ is the total number of bits in an $\text{mp\_limb\_t}$. In all cases

$$\text{GMP\_LIMB\_BITS} == \text{GMP\_NAIL\_BITS} + \text{GMP\_NUMB\_BITS}$$
GMP_NAIL_MASK
GMP_NUMB_MASK
Macro

Bit masks for the nail and number parts of a limb. GMP_NAIL_MASK is 0 when nails are not in use.

GMP_NAIL_MASK is not often needed, since the nail part can be obtained with \( x >> GMP_NUMB_BITS \), and that means one less large constant, which can help various RISC chips.

GMP_NUMB_MAX
Macro

The maximum value that can be stored in the number part of a limb. This is the same as GMP_NUMB_MASK, but can be used for clarity when doing comparisons rather than bit-wise operations.

The term “nails” comes from finger or toe nails, which are at the ends of a limb (arm or leg). “numb” is short for number, but is also how the developers felt after trying for a long time to come up with sensible names for these things.

In the future (the distant future most likely) a non-zero nail might be permitted, giving non-unique representations for numbers in a limb vector. This would help vector processors since carries would only ever need to propagate one or two limbs.
9 Random Number Functions

Sequences of pseudo-random numbers in GMP are generated using a variable of type `gmp_randstate_t`, which holds an algorithm selection and a current state. Such a variable must be initialized by a call to one of the `gmp_randinit` functions, and can be seeded with one of the `gmp_randseed` functions.

The functions actually generating random numbers are described in Section 5.13 [Integer Random Numbers], page 41, and Section 7.8 [Miscellaneous Float Functions], page 56.

The older style random number functions don’t accept a `gmp_randstate_t` parameter but instead share a global variable of that type. They use a default algorithm and are currently not seeded (though perhaps that will change in the future). The new functions accepting a `gmp_randstate_t` are recommended for applications that care about randomness.

9.1 Random State Initialization

```c
void gmp_randinit_default (gmp_randstate_t state)  // [Function]
    Initialize state with a default algorithm. This will be a compromise between speed and randomness, and is recommended for applications with no special requirements. Currently this is `gmp_randinit_mt`.

void gmp_randinit_mt (gmp_randstate_t state)  // [Function]
    Initialize state for a Mersenne Twister algorithm. This algorithm is fast and has good randomness properties.

void gmp_randinit_lc_2exp (gmp_randstate_t state, const mpz_t a, unsigned long c, mp_bitcnt_t m2exp)  // [Function]
    Initialize state with a linear congruential algorithm \( X = (aX + c) \mod 2^{m2exp} \).

    The low bits of \( X \) in this algorithm are not very random. The least significant bit will have a period no more than 2, and the second bit no more than 4, etc. For this reason only the high half of each \( X \) is actually used.

    When a random number of more than \( m2exp/2 \) bits is to be generated, multiple iterations of the recurrence are used and the results concatenated.

int gmp_randinit_lc_2exp_size (gmp_randstate_t state, mp_bitcnt_t size)  // [Function]
    Initialize state for a linear congruential algorithm as per `gmp_randinit_lc_2exp`. \( a, c \) and \( m2exp \) are selected from a table, chosen so that \( size \) bits (or more) of each \( X \) will be used, i.e. \( m2exp/2 \geq size \).

    If successful the return value is non-zero. If \( size \) is bigger than the table data provides then the return value is zero. The maximum \( size \) currently supported is 128.

void gmp_randinit_set (gmp_randstate_t rop, gmp_randstate_t op)  // [Function]
    Initialize rop with a copy of the algorithm and state from op.

void gmp_randinit (gmp_randstate_t state, gmp_randalg_t alg, ...)  // [Function]
    This function is obsolete.

    Initialize state with an algorithm selected by alg. The only choice is GMP_RAND_ALG_LC, which is `gmp_randinit_lc_2exp_size` described above. A third parameter of type `unsigned long`
is required, this is the size for that function. GMP_RAND_ALG_DEFAULT or 0 are the same as GMP_RAND_ALG_LC.

gmp_randinit sets bits in the global variable gmp_errno to indicate an error. GMP_ERROR_UNSUPPORTED_ARGUMENT if alg is unsupported, or GMP_ERROR_INVALID_ARGUMENT if the size parameter is too big. It may be noted this error reporting is not thread safe (a good reason to use gmp_randinit_lc_2exp_size instead).

void gmp_randclear (gmp_rndstate_t state) [Function]
Free all memory occupied by state.

9.2 Random State Seeding

void gmp_randseed (gmp_rndstate_t state, const mpz_t seed) [Function]
void gmp_randseed_ui (gmp_rndstate_t state, unsigned long int seed) [Function]
Set an initial seed value into state.

The size of a seed determines how many different sequences of random numbers that it’s possible to generate. The “quality” of the seed is the randomness of a given seed compared to the previous seed used, and this affects the randomness of separate number sequences. The method for choosing a seed is critical if the generated numbers are to be used for important applications, such as generating cryptographic keys.

Traditionally the system time has been used to seed, but care needs to be taken with this. If an application seeds often and the resolution of the system clock is low, then the same sequence of numbers might be repeated. Also, the system time is quite easy to guess, so if unpredictability is required then it should definitely not be the only source for the seed value. On some systems there’s a special device /dev/random which provides random data better suited for use as a seed.

9.3 Random State Miscellaneous

unsigned long gmp_urandomb_ui (gmp_rndstate_t state, unsigned long n) [Function]
Return a uniformly distributed random number of n bits, i.e. in the range 0 to \(2^n - 1\) inclusive. n must be less than or equal to the number of bits in an unsigned long.

unsigned long gmp_urandomm_ui (gmp_rndstate_t state, unsigned long n) [Function]
Return a uniformly distributed random number in the range 0 to \(n - 1\), inclusive.
10 Formatted Output

10.1 Format Strings

gmp_printf and friends accept format strings similar to the standard C printf (see Section “Formatted Output” in The GNU C Library Reference Manual). A format specification is of the form

\[
% [flags] [width] [.precision] [type] conv
\]

GMP adds types ‘Z’, ‘Q’ and ‘F’ for mpz_t, mpq_t and mpf_t respectively, ‘M’ for mpn_t, and ‘N’ for an mpn_t array. ‘Z’, ‘Q’, ‘M’ and ‘N’ behave like integers. ‘Q’ will print a ‘/’ and a denominator, if needed. ‘F’ behaves like a float. For example,

```c
mpz_t z;
gmp_printf("%s is an mpz %Zd\n", "here", z);

mpq_t q;
gmp_printf("a hex rational: %#40Qx\n", q);

mpf_t f;
int n;
gmp_printf("fixed point mpf %.*Ff with %d digits\n", n, f, n);

mpn_t l;
gmp_printf("limb %Mu\n", l);

const mpn_t *ptr;
mp_size_t size;
gmp_printf("limb array %Nx\n", ptr, size);
```

For ‘N’ the limbs are expected least significant first, as per the mpn functions (see Chapter 8 [Low-level Functions], page 58). A negative size can be given to print the value as a negative.

All the standard C printf types behave the same as the C library printf, and can be freely intermixed with the GMP extensions. In the current implementation the standard parts of the format string are simply handed to printf and only the GMP extensions handled directly.

The flags accepted are as follows. GLIBC style ‘’ is only for the standard C types (not the GMP types), and only if the C library supports it.

- 0 pad with zeros (rather than spaces)
- # show the base with ‘0x’, ‘0X’ or ‘0’
- + always show a sign
- (space) show a space or a ‘-’ sign
- , group digits, GLIBC style (not GMP types)

The optional width and precision can be given as a number within the format string, or as a ‘*’ to take an extra parameter of type int, the same as the standard printf.

The standard types accepted are as follows. ‘h’ and ‘l’ are portable, the rest will depend on the compiler (or include files) for the type and the C library for the output.

- h short
- hh char
The GMP types are

- **F** `mpf_t`, float conversions
- **Q** `mpq_t`, integer conversions
- **M** `mp_limb_t`, integer conversions
- **N** `mp_limb_t` array, integer conversions
- **Z** `mpz_t`, integer conversions

The conversions accepted are as follows. ‘a’ and ‘A’ are always supported for `mpf_t` but depend on the C library for standard C float types. ‘m’ and ‘p’ depend on the C library.

- **a, A** hex floats, C99 style
- **c** character
- **d** decimal integer
- **e, E** scientific format float
- **f** fixed point float
- **i** same as d
- **g, G** fixed or scientific float
- **m** `strerror` string, GLIBC style
- **n** store characters written so far
- **o** octal integer
- **p** pointer
- **s** string
- **u** unsigned integer
- **x, X** hex integer

‘o’, ‘x’ and ‘X’ are unsigned for the standard C types, but for types ‘Z’, ‘Q’ and ‘N’ they are signed. ‘u’ is not meaningful for ‘Z’, ‘Q’ and ‘N’.

‘m’ is a proxy for the C library ‘l’ or ‘L’, according to the size of `mp_limb_t`. Unsigned conversions will be usual, but a signed conversion can be used and will interpret the value as a two's complement negative.

‘n’ can be used with any type, even the GMP types.

Other types or conversions that might be accepted by the C library `printf` cannot be used through `gmp_printf`, this includes for instance extensions registered with GLIBC `register_printf_function`. Also currently there’s no support for POSIX `$` style numbered arguments (perhaps this will be added in the future).

The precision field has its usual meaning for integer ‘Z’ and float ‘F’ types, but is currently undefined for ‘Q’ and should not be used with that.

`mpf_t` conversions only ever generate as many digits as can be accurately represented by the operand, the same as `mpf_get_str` does. Zeros will be used if necessary to pad to the requested precision. This happens even for an ‘f’ conversion of an `mpf_t` which is an integer, for instance
2^{1024} in an mpf_t of 128 bits precision will only produce about 40 digits, then pad with zeros to the decimal point. An empty precision field like ‘%.Fe’ or ‘%.Ff’ can be used to specifically request just the significant digits. Without any dot and thus no precision field, a precision value of 6 will be used. Note that these rules mean that ‘%.FF’, ‘%.Ff’, and ‘%.0FF’ will all be different.

The decimal point character (or string) is taken from the current locale settings on systems which provide localeconv (see Section “Locales and Internationalization” in The GNU C Library Reference Manual). The C library will normally do the same for standard float output.

The format string is only interpreted as plain chars, multibyte characters are not recognised. Perhaps this will change in the future.

10.2 Functions

Each of the following functions is similar to the corresponding C library function. The basic printf forms take a variable argument list. The vprintf forms take an argument pointer, see Section “Variadic Functions” in The GNU C Library Reference Manual, or ‘man 3 va_start’.

It should be emphasised that if a format string is invalid, or the arguments don’t match what the format specifies, then the behaviour of any of these functions will be unpredictable. GCC format string checking is not available, since it doesn’t recognise the GMP extensions.

The file based functions gmp_printf and gmp_fprintf will return −1 to indicate a write error. Output is not “atomic”, so partial output may be produced if a write error occurs. All the functions can return −1 if the C library printf variant in use returns −1, but this shouldn’t normally occur.

```c
#include <gmp.h>

int gmp_printf (const char *fmt, ...) { /* Function */
    Print to the standard output stdout. Return the number of characters written, or −1 if an error occurred.
}

int gmp_vprintf (const char *fmt, va_list ap) { /* Function */
    Print to the standard output stdout. Return the number of characters written, or −1 if an error occurred.
}

int gmp_fprintf (FILE *fp, const char *fmt, ...) { /* Function */
    Print to the stream fp. Return the number of characters written, or −1 if an error occurred.
}

int gmp_vfprintf (FILE *fp, const char *fmt, va_list ap) { /* Function */
    Print to the stream fp. Return the number of characters written, or −1 if an error occurred.
}

int gmp_sprintf (char *buf, const char *fmt, ...) { /* Function */
    Form a null-terminated string in buf. Return the number of characters written, excluding the terminating null.
}

int gmp_vsprintf (char *buf, const char *fmt, va_list ap) { /* Function */
    Form a null-terminated string in buf. Return the number of characters written, excluding the terminating null.
}

int gmp_snprintf (char *buf, size_t size, const char *fmt, ...) { /* Function */
    Form a null-terminated string in buf. No more than size bytes will be written. To get the full output, size must be enough for the string and null-terminator.
}

int gmp_vsnprintf (char *buf, size_t size, const char *fmt, va_list ap) { /* Function */
    Form a null-terminated string in buf. No more than size bytes will be written. To get the full output, size must be enough for the string and null-terminator.
}
```

No overlap is permitted between the space at buf and the string fmt.

These functions are not recommended, since there’s no protection against exceeding the space available at buf.

The return value is the total number of characters which ought to have been produced, excluding the terminating null. If retval ≥ size then the actual output has been truncated to the first size − 1 characters, and a null appended.

No overlap is permitted between the region {buf, size} and the fmt string.
Notice the return value is in ISO C99 \texttt{snprintf} style. This is so even if the C library \texttt{vsnprintf} is the older GLIBC 2.0.x style.

```c
int gmp_asprintf (char **pp, const char *fmt, ...) [Function]
int gmp_vasprintf (char **pp, const char *fmt, va_list ap) [Function]
```

Form a null-terminated string in a block of memory obtained from the current memory allocation function (see Chapter 13 [Custom Allocation], page 90). The block will be the size of the string and null-terminator. The address of the block in stored to *pp. The return value is the number of characters produced, excluding the null-terminator.

Unlike the C library \texttt{asprintf}, \texttt{gmp_asprintf} doesn’t return $-1$ if there’s no more memory available, it lets the current allocation function handle that.

```c
int gmp_obstack_printf (struct obstack *ob, const char *fmt, ...) [Function]
int gmp_obstack_vprintf (struct obstack *ob, const char *fmt, va_list ap) [Function]
```

Append to the current object in \texttt{ob}. The return value is the number of characters written. A null-terminator is not written.

\texttt{fmt} cannot be within the current object in \texttt{ob}, since that object might move as it grows.

These functions are available only when the C library provides the obstack feature, which probably means only on GNU systems, see Section “Obstacks” in The GNU C Library Reference Manual.

### 10.3 C++ Formatted Output

The following functions are provided in \texttt{libgmpxx} (see Section 3.1 [Headers and Libraries], page 17), which is built if C++ support is enabled (see Section 2.1 [Build Options], page 3). Prototypes are available from <\texttt{gmp.h}>.

```cpp
ostream& operator<< (ostream& stream, const mpz_t op) [Function]
Print \texttt{op} to \texttt{stream}, using its \texttt{ios} formatting settings. \texttt{ios::width} is reset to 0 after output, the same as the standard \texttt{ostream operator<<} routines do.

In hex or octal, \texttt{op} is printed as a signed number, the same as for decimal. This is unlike the standard \texttt{operator<<} routines on \texttt{int} etc, which instead give twos complement.

ostream& operator<< (ostream& stream, const mpq_t op) [Function]
Print \texttt{op} to \texttt{stream}, using its \texttt{ios} formatting settings. \texttt{ios::width} is reset to 0 after output, the same as the standard \texttt{ostream operator<<} routines do.

Output will be a fraction like \texttt{‘5/9’}, or if the denominator is 1 then just a plain integer like \texttt{‘123’}.

In hex or octal, \texttt{op} is printed as a signed value, the same as for decimal. If \texttt{ios::showbase} is set then a base indicator is shown on both the numerator and denominator (if the denominator is required).

ostream& operator<< (ostream& stream, const mpf_t op) [Function]
Print \texttt{op} to \texttt{stream}, using its \texttt{ios} formatting settings. \texttt{ios::width} is reset to 0 after output, the same as the standard \texttt{ostream operator<<} routines do.

The decimal point follows the standard library float \texttt{operator<<}, which on recent systems means the \texttt{std::locale} imbued on \texttt{stream}.
Hex and octal are supported, unlike the standard `operator<<` on `double`. The mantissa will be in hex or octal, the exponent will be in decimal. For hex the exponent delimiter is an ‘@’. This is as per `mpf_out_str`.

`ios::showbase` is supported, and will put a base on the mantissa, for example hex ‘0x1.8’ or ‘0x0.8’, or octal ‘01.4’ or ‘00.4’. This last form is slightly strange, but at least differentiates itself from decimal.

These operators mean that GMP types can be printed in the usual C++ way, for example,

```cpp
cmpz_t z;
int n;
...
cout << "iteration " << n << " value " << z << "\n";
```

But note that `ostream` output (and `istream` input, see Section 11.3 [C++ Formatted Input], page 79) is the only overloading available for the GMP types and that for instance using + with an `mpz_t` will have unpredictable results. For classes with overloading, see Chapter 12 [C++ Class Interface], page 81.
11 Formatted Input

11.1 Formatted Input Strings

`gmp_scanf` and friends accept format strings similar to the standard C `scanf` (see Section “Formatted Input” in The GNU C Library Reference Manual). A format specification is of the form

```
% [flags] [width] [type] conv
```

GMP adds types ‘Z’, ‘Q’ and ‘F’ for `mpz_t`, `mpq_t` and `mpf_t` respectively. ‘Z’ and ‘Q’ behave like integers. ‘Q’ will read a ‘/’ and a denominator, if present. ‘F’ behaves like a float.

GMP variables don’t require an & when passed to `gmp_scanf`, since they’re already “call-by-reference”. For example,

```c
/* to read say "a(5) = 1234" */
int n;
mpz_t z;
gmp_scanf ("a(%d) = %Zd\n", &n, z);

mpq_t q1, q2;
gmp_sscanf ("0377 + 0x10/0x11", "%Qi + %Qi", q1, q2);

/* to read say "topleft (1.55,-2.66)" */
mpf_t x, y;
char buf[32];
gmp_scanf ("%31s (%Ff, %Ff)", buf, x, y);
```

All the standard C `scanf` types behave the same as in the C library `scanf`, and can be freely intermixed with the GMP extensions. In the current implementation the standard parts of the format string are simply handed to `scanf` and only the GMP extensions handled directly.

The flags accepted are as follows. ‘a’ and ‘’ will depend on support from the C library, and ‘’ cannot be used with GMP types.

```
*        read but don’t store
a        allocate a buffer (string conversions)
'        grouped digits, GLIBC style (not GMP types)
```

The standard types accepted are as follows. ‘h’ and ‘l’ are portable, the rest will depend on the compiler (or include files) for the type and the C library for the input.

```
h        short
hh       char
j        intmax_t or uintmax_t
l        long int, double or wchar_t
ll       long long
L        long double
q        quad_t or u_quad_t
t        ptdiff_t
z        size_t
```

The GMP types are...
GNU MP 6.2.0

\[
\begin{align*}
F & \quad \text{mpf}_t, \text{float conversions} \\
Q & \quad \text{mpq}_t, \text{integer conversions} \\
Z & \quad \text{mpz}_t, \text{integer conversions}
\end{align*}
\]

The conversions accepted are as follows. ‘p’ and ‘[’ will depend on support from the C library, the rest are standard.

- `c` character or characters
- `d` decimal integer
- `e E f g` float
- `i` integer with base indicator
- `n` characters read so far
- `o` octal integer
- `p` pointer
- `s` string of non-whitespace characters
- `u` decimal integer
- `x X` hex integer
- `[` string of characters in a set

‘e’, ‘E’, ‘f’, ‘g’ and ‘G’ are identical, they all read either fixed point or scientific format, and either upper or lower case ‘e’ for the exponent in scientific format.

C99 style hex float format (\texttt{printf \%a}, see Section 10.1 [Formatted Output Strings], page 72) is always accepted for \texttt{mpf}_t, but for the standard float types it will depend on the C library.

‘x’ and ‘X’ are identical, both accept both upper and lower case hexadecimal.

‘o’, ‘u’, ‘x’ and ‘X’ all read positive or negative values. For the standard C types these are described as “unsigned” conversions, but that merely affects certain overflow handling, negatives are still allowed (per \texttt{strtol}, see Section “Parsing of Integers” in The GNU C Library Reference Manual). For GMP types there are no overflows, so ‘d’ and ‘u’ are identical.

‘Q’ type reads the numerator and (optional) denominator as given. If the value might not be in canonical form then \texttt{mpq_canonicalize} must be called before using it in any calculations (see Chapter 6 [Rational Number Functions], page 46).

‘Qi’ will read a base specification separately for the numerator and denominator. For example ‘0x10/11’ would be 16/11, whereas ‘0x10/0x11’ would be 16/17.

‘n’ can be used with any of the types above, even the GMP types. ‘*’ to suppress assignment is allowed, though in that case it would do nothing at all.

Other conversions or types that might be accepted by the C library \texttt{scanf} cannot be used through \texttt{gmp_scanf}.

Whitespace is read and discarded before a field, except for ‘c’ and ‘[’ conversions.

For float conversions, the decimal point character (or string) expected is taken from the current locale settings on systems which provide \texttt{localeconv} (see Section “Locales and Internationalization” in The GNU C Library Reference Manual). The C library will normally do the same for standard float input.

The format string is only interpreted as plain \texttt{chars}, multibyte characters are not recognised. Perhaps this will change in the future.
11.2 Formatted Input Functions

Each of the following functions is similar to the corresponding C library function. The plain `scanf` forms take a variable argument list. The `vscanf` forms take an argument pointer, see Section “Variadic Functions” in The GNU C Library Reference Manual, or ‘man 3 va_start’.

It should be emphasised that if a format string is invalid, or the arguments don’t match what the format specifies, then the behaviour of any of these functions will be unpredictable. GCC format string checking is not available, since it doesn’t recognise the GMP extensions.

No overlap is permitted between the `fmt` string and any of the results produced.

```c
int gmp_sscanf (const char *fmt, ...)                [Function]
int gmp_vsscanf (const char *fmt, va_list ap)        [Function]
  Read from the standard input stdin.

int gmp_fscanf (FILE *fp, const char *fmt, ...)      [Function]
int gmp_vfscanf (FILE *fp, const char *fmt, va_list ap) [Function]
  Read from the stream fp.

int gmp_ssscanf (const char *s, const char *fmt, ...) [Function]
int gmp_vsscanf (const char *s, const char *fmt, va_list ap) [Function]
  Read from a null-terminated string s.
```

The return value from each of these functions is the same as the standard C99 `scanf`, namely the number of fields successfully parsed and stored. ‘%n’ fields and fields read but suppressed by ‘*’ don’t count towards the return value.

If end of input (or a file error) is reached before a character for a field or a literal, and if no previous non-suppressed fields have matched, then the return value is `EOF` instead of 0. A whitespace character in the format string is only an optional match and doesn’t induce an `EOF` in this fashion. Leading whitespace read and discarded for a field don’t count as characters for that field.

For the GMP types, input parsing follows C99 rules, namely one character of lookahead is used and characters are read while they continue to meet the format requirements. If this doesn’t provide a complete number then the function terminates, with that field not stored nor counted towards the return value. For instance with `mpf_t` an input ‘1.23e-XYZ’ would be read up to the ‘X’ and that character pushed back since it’s not a digit. The string ‘1.23e-’ would then be considered invalid since an ‘e’ must be followed by at least one digit.

For the standard C types, in the current implementation GMP calls the C library `scanf` functions, which might have looser rules about what constitutes a valid input.

Note that `gmp_ssscanf` is the same as `gmp_fscanf` and only does one character of lookahead when parsing. Although clearly it could look at its entire input, it is deliberately made identical to `gmp_fscanf`, the same way C99 `sscanf` is the same as `fscanf`.

11.3 C++ Formatted Input

The following functions are provided in `libgmpxx` (see Section 3.1 [Headers and Libraries], page 17), which is built only if C++ support is enabled (see Section 2.1 [Build Options], page 3). Prototypes are available from `<gmp.h>.

```cpp
istream& operator>> (istream& stream, mpz_t rop)     [Function]
  Read rop from stream, using its ios formatting settings.
```


**istream\& operator\>>** (istream\& stream, mpq\_t rop) \[Function\]
An integer like ‘123’ will be read, or a fraction like ‘5/9’. No whitespace is allowed around the ‘/’. If the fraction is not in canonical form then mpq\_canonicalize must be called (see Chapter 6 [Rational Number Functions], page 46) before operating on it.

As per integer input, an ‘0’ or ‘0x’ base indicator is read when none of ios::dec, ios::oct or ios::hex are set. This is done separately for numerator and denominator, so that for instance ‘0x10/11’ is 16/11 and ‘0x10/0x11’ is 16/17.

**istream\& operator\>>** (istream\& stream, mpf\_t rop) \[Function\]
Read rop from stream, using its ios formatting settings.

Hex or octal floats are not supported, but might be in the future, or perhaps it’s best to accept only what the standard float operator\>> does.

Note that digit grouping specified by the istream locale is currently not accepted. Perhaps this will change in the future.

These operators mean that GMP types can be read in the usual C++ way, for example,

```c
type z;
...
cin >> z;
```

But note that istream input (and ostream output, see Section 10.3 [C++ Formatted Output], page 75) is the only overloading available for the GMP types and that for instance using + with an mpz\_t will have unpredictable results. For classes with overloading, see Chapter 12 [C++ Class Interface], page 81.
12 C++ Class Interface

This chapter describes the C++ class based interface to GMP.

All GMP C language types and functions can be used in C++ programs, since gmp.h has extern "C" qualifiers, but the class interface offers overloaded functions and operators which may be more convenient.

Due to the implementation of this interface, a reasonably recent C++ compiler is required, one supporting namespaces, partial specialization of templates and member templates.

Everything described in this chapter is to be considered preliminary and might be subject to incompatible changes if some unforeseen difficulty reveals itself.

12.1 C++ Interface General

All the C++ classes and functions are available with

```c
#include <gmpxx.h>
```

Programs should be linked with the libgmpxx and libgmp libraries. For example,

```c
g++ mycxxprog.cc -lgmpxx -lgmp
```

The classes defined are

```c
mpz_class
mpq_class
mpf_class
```

The standard operators and various standard functions are overloaded to allow arithmetic with these classes. For example,

```c
int
main (void)
{
    mpz_class a, b, c;

    a = 1234;
    b = "-5678";
    c = a+b;
    cout << "sum is " << c << "\n";
    cout << "absolute value is " << abs(c) << "\n";

    return 0;
}
```

An important feature of the implementation is that an expression like a=b+c results in a single call to the corresponding mpz_add, without using a temporary for the b+c part. Expressions which by their nature imply intermediate values, like a=b*c+d*e, still use temporaries though.

The classes can be freely intermixed in expressions, as can the classes and the standard types long, unsigned long and double. Smaller types like int or float can also be intermixed, since C++ will promote them.

Note that bool is not accepted directly, but must be explicitly cast to an int first. This is because C++ will automatically convert any pointer to a bool, so if GMP accepted bool it
would make all sorts of invalid class and pointer combinations compile but almost certainly not do anything sensible.

Conversions back from the classes to standard C++ types aren’t done automatically, instead member functions like `get_si` are provided (see the following sections for details).

Also there are no automatic conversions from the classes to the corresponding GMP C types, instead a reference to the underlying C object can be obtained with the following functions,

```cpp
class mxp_class::get_mpz_t ()
class mpz_class::get_mpq_t ()
class mpz_class::get_mpf_t ()
```

These can be used to call a C function which doesn’t have a C++ class interface. For example to set `a` to the GCD of `b` and `c`,

```cpp
mpz_class a, b, c;
... mpz_gcd (a.get_mpz_t(), b.get_mpz_t(), c.get_mpz_t());
```

In the other direction, a class can be initialized from the corresponding GMP C type, or assigned to if an explicit constructor is used. In both cases this makes a copy of the value, it doesn’t create any sort of association. For example,

```cpp
mpz_t z;
// ... init and calculate z ...
mpz_class x(z);
mpz_class y;
y = mpz_class (z);
```

There are no namespace setups in `gmpxx.h`, all types and functions are simply put into the global namespace. This is what `gmp.h` has done in the past, and continues to do for compatibility. The extras provided by `gmpxx.h` follow GMP naming conventions and are unlikely to clash with anything.

### 12.2 C++ Interface Integers

**`mpz_class::mpz_class (type n)`**

Construct an `mpz_class`. All the standard C++ types may be used, except `long long` and `long double`, and all the GMP C++ classes can be used, although conversions from `mpq_class` and `mpf_class` are explicit. Any necessary conversion follows the corresponding C function, for example `double` follows `mpz_set_d` (see Section 5.2 [Assigning Integers], page 31).

**`explicit mpz_class::mpz_class (const mpz_t z)`**

Construct an `mpz_class` from an `mpz_t`. The value in `z` is copied into the new `mpz_class`, there won’t be any permanent association between it and `z`.

**`explicit mpz_class::mpz_class (const char *s, int base = 0)`**

**`explicit mpz_class::mpz_class (const string& s, int base = 0)`**

Construct an `mpz_class` converted from a string using `mpz_set_str` (see Section 5.2 [Assigning Integers], page 31).

If the string is not a valid integer, an `std::invalid_argument` exception is thrown. The same applies to `operator=`.
With C++11 compilers, integers can be constructed with the syntax `123mpz` which is equivalent to `mpz_class("123")`.

Divisions involving `mpz_class` round towards zero, as per the `mpz_tdiv_q` and `mpz_tdiv_r` functions (see Section 5.6 [Integer Division], page 33). This is the same as the C99 `/` and `%` operators.

The `mpz_fdiv...` or `mpz_cdiv...` functions can always be called directly if desired. For example,

```cpp
mpz_class q, a, d;
...
mpz_fdiv_q(q.get_mpz_t(), a.get_mpz_t(), d.get_mpz_t());
```

These functions provide a C++ class interface to the corresponding GMP C routines. Calling `factorial` or `primorial` on a negative number is undefined.

`cmp` can be used with any of the classes or the standard C++ types, except `long long` and `long double`.

Overloaded operators for combinations of `mpz_class` and `double` are provided for completeness, but it should be noted that if the given `double` is not an integer then the way any rounding is
done is currently unspecified. The rounding might take place at the start, in the middle, or at the end of the operation, and it might change in the future.

Conversions between `mpz_class` and `double`, however, are defined to follow the corresponding C functions `mpz_get_d` and `mpz_set_d`. And comparisons are always made exactly, as per `mpz_cmp_d`.

### 12.3 C++ Interface Rationals

In all the following constructors, if a fraction is given then it should be in canonical form, or if not then `mpq_class::canonicalize` called.

- **`mpq_class::mpq_class (type op)`**
- **`mpq_class::mpq_class (integer num, integer den)`**

Construct an `mpq_class`. The initial value can be a single value of any type (conversion from `mpf_class` is explicit), or a pair of integers (`mpz_class` or standard C++ integer types) representing a fraction, except that `long long` and `long double` are not supported. For example,

```cpp
mpq_class q (99);
mpq_class q (1.75);
mpq_class q (1, 3);
```

- **`explicit mpq_class::mpq_class (const mpq_t q)`**

Construct an `mpq_class` from an `mpq_t`. The value in `q` is copied into the new `mpq_class`, there won’t be any permanent association between it and `q`.

- **`explicit mpq_class::mpq_class (const char *s, int base = 0)`**
- **`explicit mpq_class::mpq_class (const string& s, int base = 0)`**

Construct an `mpq_class` converted from a string using `mpq_set_str` (see Section 6.1 [Initializing Rationals], page 46).

If the string is not a valid rational, an `std::invalid_argument` exception is thrown. The same applies to `operator=`.

- **`mpq_class operator"" _mpq (const char *str)`**

With C++11 compilers, integral rationals can be constructed with the syntax `123_mpq` which is equivalent to `mpq_class(123_mpz)`. Other rationals can be built as `-1_mpq/2` or `0xb_mpq/123456_mpz`.

- **`void mpq_class::canonicalize ()`**

Put an `mpq_class` into canonical form, as per Chapter 6 [Rational Number Functions], page 46. All arithmetic operators require their operands in canonical form, and will return results in canonical form.
void swap (mpq_class& op1, mpq_class& op2)

These functions provide a C++ class interface to the corresponding GMP C routines.

cmp can be used with any of the classes or the standard C++ types, except long long and long double.

mpz_class& mpq_class::get_num ()
mpz_class& mpq_class::get_den ()

Get a reference to an mpz_class which is the numerator or denominator of an mpq_class. This can be used both for read and write access. If the object returned is modified, it modifies the original mpq_class.

If direct manipulation might produce a non-canonical value, then mpq_class::canonicalize must be called before further operations.

mpz_t mpq_class::get_num_mpz_t ()
mpz_t mpq_class::get_den_mpz_t ()

Get a reference to the underlying mpz_t numerator or denominator of an mpq_class. This can be passed to C functions expecting an mpz_t. Any modifications made to the mpz_t will modify the original mpq_class.

If direct manipulation might produce a non-canonical value, then mpq_class::canonicalize must be called before further operations.

istream& operator >> (istream& stream, mpq_class& rop);

Read rop from stream, using its ios formatting settings, the same as mpq_t operator >> (see Section 11.3 [C++ Formatted Input], page 79).

If the rop read might not be in canonical form then mpq_class::canonicalize must be called.

12.4 C++ Interface Floats

When an expression requires the use of temporary intermediate mpf_class values, like f = g + h * x * y, those temporaries will have the same precision as the destination f. Explicit constructors can be used if this doesn’t suit.

mpf_class::mpf_class (type op)
mpf_class::mpf_class (type op, mp_bitcnt_t prec)

Construct an mpf_class. Any standard C++ type can be used, except long long and long double, and any of the GMP C++ classes can be used.

If prec is given, the initial precision is that value, in bits. If prec is not given, then the initial precision is determined by the type of op given. An mpz_class, mpq_class, or C++ builtin type will give the default mpf precision (see Section 7.1 [Initializing Floats], page 50). An mpf_class or expression will give the precision of that value. The precision of a binary expression is the higher of the two operands.

mpf_class f(1.5); // default precision
mpf_class f(1.5, 500); // 500 bits (at least)
mpf_class f(x); // precision of x
mpf_class f(abs(x)); // precision of x
mpf_class f(-g, 1000); // 1000 bits (at least)
mpf_class f(x+y); // greater of precisions of x and y
explicit mpf_class::mpf_class (const mpf_t f) [Function]
mpf_class::mpf_class (const mpf_t f, mp_bitcnt_t prec) [Function]

Construct an mpf_class from an mpf_t. The value in \( f \) is copied into the new mpf_class, there won't be any permanent association between it and \( f \).

If \( \text{prec} \) is given, the initial precision is that value, in bits. If \( \text{prec} \) is not given, then the initial precision is that of \( f \).

explicit mpf_class::mpf_class (const char *s) [Function]
mpf_class::mpf_class (const char *s, mp_bitcnt_t prec, int base = 0) [Function]
explicit mpf_class::mpf_class (const string &s) [Function]
mpf_class::mpf_class (const string &s, mp_bitcnt_t prec, int base = 0) [Function]

Construct an mpf_class converted from a string using mpf_set_str (see Section 7.2 [Assigning Floats], page 52). If \( \text{prec} \) is given, the initial precision is that value, in bits. If not, the default mpf precision (see Section 7.1 [Initializing Floats], page 50) is used.

If the string is not a valid float, an std::invalid_argument exception is thrown. The same applies to operator=.

mpf_class operator"" (const char *str) [Function]

With C++11 compilers, floats can be constructed with the syntax 1.23e-1_mpf which is equivalent to mpf_class("1.23e-1").

mpf_class& mpf_class::operator= (type op) [Function]

Convert and store the given \( \text{op} \) value to an mpf_class object. The same types are accepted as for the constructors above.

Note that \( \text{operator=} \) only stores a new value, it doesn't copy or change the precision of the destination, instead the value is truncated if necessary. This is the same as mpf_set etc. Note in particular this means for mpf_class a copy constructor is not the same as a default constructor plus assignment.

mpf_class x (y); // x created with precision of y
mpf_class x; // x created with default precision
x = y; // value truncated to that precision

Applications using templated code may need to be careful about the assumptions the code makes in this area, when working with mpf_class values of various different or non-default precisions. For instance implementations of the standard complex template have been seen in both styles above, though of course complex is normally only actually specified for use with the built-in float types.

mpf_class abs (mpf_class op) [Function]
mpf_class ceil (mpf_class op) [Function]
int cmp (mpf_class op1, type op2) [Function]
int cmp (type op1, mpf_class op2) [Function]
bool mpf_class::fits_sint_p (void) [Function]
bool mpf_class::fits_slong_p (void) [Function]
bool mpf_class::fits_sshort_p (void) [Function]
bool mpf_class::fits_uint_p (void) [Function]
bool mpf_class::fits_ulong_p (void) [Function]
bool mpf_class::fits_ushort_p (void) [Function]
mpf_class floor (mpf_class op) [Function]
mpf_class hypot (mpf_class op1, mpf_class op2) [Function]
double mpf_class::get_d (void) [Function]
long mpf_class::get_si (void) [Function]
string mpf_class::get_str (mpf_exp_t & exp, int base = 10, size_t digits = 0) [Function]
unsigned long mpf_class::get_ui (void) [Function]
int mpf_class::set_str (const char * str, int base) [Function]
int mpf_class::set_str (const string & str, int base) [Function]
int sgn (mpf_class op) [Function]
mpf_class sqrt (mpf_class op) [Function]
void mpf_class::swap (mpf_class & op) [Function]
void swap (mpf_class & op1, mpf_class & op2) [Function]
mpf_class trunc (mpf_class op) [Function]

These functions provide a C++ class interface to the corresponding GMP C routines.

cmp can be used with any of the classes or the standard C++ types, except long long and long double.

The accuracy provided by hypot is not currently guaranteed.

mp_bitcnt_t mpf_class::get_prec () [Function]
void mpf_class::set_prec (mp_bitcnt_t prec) [Function]
void mpf_class::set_prec_raw (mp_bitcnt_t prec) [Function]

Get or set the current precision of an mpf_class.

The restrictions described for mpf_set_prec_raw (see Section 7.1 [Initializing Floats], page 50) apply to mpf_class::set_prec_raw. Note in particular that the mpf_class must be restored to it’s allocated precision before being destroyed. This must be done by application code, there’s no automatic mechanism for it.

12.5 C++ Interface Random Numbers

gmp_randclass [Class]
The C++ class interface to the GMP random number functions uses gmp_randclass to hold an algorithm selection and current state, as per gmp_randstate_t.

gmp_randclass::gmp_randclass (void (*randinit) (gmp_randstate_t, ...), ...) [Function]

Construct a gmp_randclass, using a call to the given randinit function (see Section 9.1 [Random State Initialization], page 70). The arguments expected are the same as randinit, but with mpz_class instead of mpz_t. For example,

gmp_randclass r1 (gmp_randinit_default);
gmp_randclass r2 (gmp_randinit_lc_2exp_size, 32);
gmp_randclass r3 (gmp_randinit_lc_2exp, a, c, m2exp);
gmp_randclass r4 (gmp_randinit_mt);

gmp_randinit_lc_2exp_size will fail if the size requested is too big, an std::length_error exception is thrown in that case.

gmp_randclass::gmp_randclass (gmp_randalg_t alg, ...) [Function]

Construct a gmp_randclass using the same parameters as gmp_randinit (see Section 9.1 [Random State Initialization], page 70). This function is obsolete and the above randinit style should be preferred.
void gmp_randclass::seed (unsigned long int s)  [Function]
void gmp_randclass::seed (mpz_class s)  [Function]
    Seed a random number generator. See see Chapter 9 [Random Number Functions], page 70, for how to choose a good seed.

mpz_class gmp_randclass::get_z_bits (mp_bitcnt_t bits)  [Function]
mpz_class gmp_randclass::get_z_bits (mpz_class bits)  [Function]
    Generate a random integer with a specified number of bits.

mpz_class gmp_randclass::get_z_range (mpz_class n)  [Function]
    Generate a random integer in the range 0 to \( n - 1 \) inclusive.

mpf_class gmp_randclass::get_f ()  [Function]
mpf_class gmp_randclass::get_f (mp_bitcnt_t prec)  [Function]
    Generate a random float \( f \) in the range 0 \( \leq f < 1 \). \( f \) will be to \( \text{prec} \) bits precision, or if \( \text{prec} \) is not given then to the precision of the destination. For example,
    
    ```
    gmp_randclass r;
    ...
    mpf_class f (0, 512);  // 512 bits precision
    f = r.get_f();  // random number, 512 bits
    ```

12.6 C++ Interface Limitations

**mpq_class** and Templated Reading

A generic piece of template code probably won’t know that **mpq_class** requires a `canonicalize` call if inputs read with `operator>>` might be non-canonical. This can lead to incorrect results.

`operator>>` behaves as it does for reasons of efficiency. A canonicalize can be quite time consuming on large operands, and is best avoided if it’s not necessary.

But this potential difficulty reduces the usefulness of **mpq_class**. Perhaps a mechanism to tell `operator>>` what to do will be adopted in the future, maybe a preprocessor define, a global flag, or an `ios` flag pressed into service. Or maybe, at the risk of inconsistency, the **mpq_class** `operator>>` could canonicalize and leave **mpq_t** `operator>>` not doing so, for use on those occasions when that’s acceptable.

Send feedback or alternate ideas to **gmp-bugs@gmplib.org**.

**Subclassing**

Subclassing the GMP C++ classes works, but is not currently recommended.

Expressions involving subclasses resolve correctly (or seem to), but in normal C++ fashion the subclass doesn’t inherit constructors and assignments. There’s many of those in the GMP classes, and a good way to reestablish them in a subclass is not yet provided.

**Templated Expressions**

A subtle difficulty exists when using expressions together with application-defined template functions. Consider the following, with \( T \) intended to be some numeric type,

```
    template <class T>
    T fun (const T &, const T &);
```

When used with, say, plain **mpz_class** variables, it works fine: \( T \) is resolved as **mpz_class**.
mpz_class f(1), g(2);
fun (f, g);  // Good

But when one of the arguments is an expression, it doesn’t work.
mpz_class f(1), g(2), h(3);
fun (f, g+h);  // Bad

This is because g+h ends up being a certain expression template type internal to gmpxx.h, which the C++ template resolution rules are unable to automatically convert to mpz_class. The workaround is simply to add an explicit cast.
mpz_class f(1), g(2), h(3);
fun (f, mpz_class(g+h));  // Good

Similarly, within fun it may be necessary to cast an expression to type T when calling a templated fun2.

    template <class T>
    void fun (T f, T g)
    {
      fun2 (f, f+g);  // Bad
    }

    template <class T>
    void fun (T f, T g)
    {
      fun2 (f, T(f+g));  // Good
    }

C++11  C++11 provides several new ways in which types can be inferred: auto, decltype, etc. While they can be very convenient, they don’t mix well with expression templates. In this example, the addition is performed twice, as if we had defined sum as a macro.
mpz_class z = 33;
auto sum = z + z;
mpz_class prod = sum * sum;

This other example may crash, though some compilers might make it look like it is working, because the expression z+z goes out of scope before it is evaluated.
mpz_class z = 33;
auto sum = z + z + z;
mpz_class prod = sum * 2;

It is thus strongly recommended to avoid auto anywhere a GMP C++ expression may appear.
13 Custom Allocation

By default GMP uses malloc, realloc and free for memory allocation, and if they fail GMP prints a message to the standard error output and terminates the program.

Alternate functions can be specified, to allocate memory in a different way or to have a different error action on running out of memory.

```c
void mp_set_memory_functions (void *(*alloc_func_ptr)(size_t),
  void *(*realloc_func_ptr)(void *, size_t, size_t),
  void (*free_func_ptr)(void *, size_t))
```

Replace the current allocation functions from the arguments. If an argument is NULL, the corresponding default function is used.

These functions will be used for all memory allocation done by GMP, apart from temporary space from alloca if that function is available and GMP is configured to use it (see Section 2.1 [Build Options], page 3).

Be sure to call mp_set_memory_functions only when there are no active GMP objects allocated using the previous memory functions! Usually that means calling it before any other GMP function.

The functions supplied should fit the following declarations:

```c
void * allocate_function (size_t alloc_size)
  Return a pointer to newly allocated space with at least alloc_size bytes.

void * reallocate_function (void *ptr, size_t old_size, size_t new_size)
  Resize a previously allocated block ptr of old_size bytes to be new_size bytes.
  The block may be moved if necessary or if desired, and in that case the smaller of old_size and new_size bytes must be copied to the new location. The return value is a pointer to the resized block, that being the new location if moved or just ptr if not.
  ptr is never NULL, it’s always a previously allocated block. new_size may be bigger or smaller than old_size.

void free_function (void *ptr, size_t size)
  De-allocate the space pointed to by ptr.
  ptr is never NULL, it’s always a previously allocated block of size bytes.
```

A byte here means the unit used by the sizeof operator.

The reallocate_function parameter old_size and the free_function parameter size are passed for convenience, but of course they can be ignored if not needed by an implementation. The default functions using malloc and friends for instance don’t use them.

No error return is allowed from any of these functions, if they return then they must have performed the specified operation. In particular note that allocate_function or reallocate_function mustn’t return NULL.
Getting a different fatal error action is a good use for custom allocation functions, for example giving a graphical dialog rather than the default print to stderr. How much is possible when genuinely out of memory is another question though.

There’s currently no defined way for the allocation functions to recover from an error such as out of memory, they must terminate program execution. A longjmp or throwing a C++ exception will have undefined results. This may change in the future.

GMP may use allocated blocks to hold pointers to other allocated blocks. This will limit the assumptions a conservative garbage collection scheme can make.

Since the default GMP allocation uses malloc and friends, those functions will be linked in even if the first thing a program does is an mp_set_memory_functions. It’s necessary to change the GMP sources if this is a problem.

```c
void mp_get_memory_functions ( [Function]  
  void (**alloc_func_ptr)(size_t),  
  void (**realloc_func_ptr)(void *, size_t, size_t),  
  void (**free_func_ptr)(void *, size_t))  
Get the current allocation functions, storing function pointers to the locations given by the arguments. If an argument is NULL, that function pointer is not stored.

For example, to get just the current free function,

  void (*freefunc)(void *, size_t);

  mp_get_memory_functions (NULL, NULL, &freefunc);
```
14 Language Bindings

The following packages and projects offer access to GMP from languages other than C, though perhaps with varying levels of functionality and efficiency.

C++
- GMP C++ class interface, see Chapter 12 [C++ Class Interface], page 81
  Straightforward interface, expression templates to eliminate temporaries.
- ALP https://www-sop.inria.fr/saga/logiciels/ALP/
  Linear algebra and polynomials using templates.
- CLN https://www.ginac.de/CLN/
  High level classes for arithmetic.
- Linbox http://www.linalg.org/
  Sparse vectors and matrices.
- NTL http://www.shoup.net/ntl/
  A C++ number theory library.

Eiffel
- Eiffelroom http://www.eiffelroom.org/node/442

Haskell
- Glasgow Haskell Compiler https://www.haskell.org/ghc/

Java
- Kaffe https://github.com/kaffe/kaffe

Lisp
- Librep http://librep.sourceforge.net/
- XEmacs (21.5.18 beta and up) https://www.xemacs.org
  Optional big integers, rationals and floats using GMP.

ML
- MLton compiler http://mlton.org/

Objective Caml
- MLGMP https://opam.ocaml.org/packages/mlgmp/
- Numerix http://pauillac.inria.fr/~quercia/
  Optionally using GMP.

Oz
- Mozart https://mozart.github.io/

Pascal
- GNU Pascal Compiler http://www.gnu-pascal.de/
  GMP unit.
- Numerix http://pauillac.inria.fr/~quercia/
  For Free Pascal, optionally using GMP.

Perl
- GMP module, see demos/perl in the GMP sources (see Section 3.10 [Demonstration Programs], page 21).
Math::GMP  https://www.cpan.org/
Compatible with Math::BigInt, but not as many functions as the GMP module above.

Math::BigInt::GMP  https://www.cpan.org/
Plug Math::GMP into normal Math::BigInt operations.

Pike

• pikempz module in the standard distribution, https://pike.lysator.liu.se/

Prolog

• SWI Prolog  http://www.swi-prolog.org/
Arbitrary precision floats.

Python

• GMPY  https://code.google.com/p/gmpy/

Ruby

• https://rubygems.org/gems/gmp

Scheme

• GNU Guile  https://www.gnu.org/software/guile/guile.html
• RScheme  https://www.rscheme.org/
• STklos  http://www.stklos.net/

Smalltalk

• GNU Smalltalk  http://smalltalk.gnu.org/

Other

• Axiom  https://savannah.nongnu.org/projects/axiom
Computer algebra using GCL.
• DrGenius  http://drgenius.seul.org/
Geometry system and mathematical programming language.
• GiNaC  https://www.ginac.de/
C++ computer algebra using CLN.
• GOO  https://www.eecs.berkeley.edu/~jrb/goo/
Dynamic object oriented language.
• Maxima  https://www.ma.utexas.edu/users/wfs/maxima.html
Macsyma computer algebra using GCL.
• Regina  http://regina.sourceforge.net/
Topological calculator.
• Yacas  http://yacas.sourceforge.net
Yet another computer algebra system.
15 Algorithms

This chapter is an introduction to some of the algorithms used for various GMP operations. The code is likely to be hard to understand without knowing something about the algorithms.

Some GMP internals are mentioned, but applications that expect to be compatible with future GMP releases should take care to use only the documented functions.

15.1 Multiplication

$N \times N$ limb multiplications and squares are done using one of seven algorithms, as the size $N$ increases.

<table>
<thead>
<tr>
<th>Algorithm</th>
<th>Threshold</th>
</tr>
</thead>
<tbody>
<tr>
<td>Basecase</td>
<td>(none)</td>
</tr>
<tr>
<td>Karatsuba</td>
<td>MUL_TOOM22_THRESHOLD</td>
</tr>
<tr>
<td>Toom-3</td>
<td>MUL_TOOM33_THRESHOLD</td>
</tr>
<tr>
<td>Toom-4</td>
<td>MUL_TOOM44_THRESHOLD</td>
</tr>
<tr>
<td>Toom-6.5</td>
<td>MUL_TOOM6H_THRESHOLD</td>
</tr>
<tr>
<td>Toom-8.5</td>
<td>MUL_TOOM8H_THRESHOLD</td>
</tr>
<tr>
<td>FFT</td>
<td>MUL_FFT_THRESHOLD</td>
</tr>
</tbody>
</table>

Similarly for squaring, with the $\text{SQR}$ thresholds.

$N \times M$ multiplications of operands with different sizes above MUL_TOOM22_THRESHOLD are currently done by special Toom-inspired algorithms or directly with FFT, depending on operand size (see Section 15.1.8 [Unbalanced Multiplication], page 100).

15.1.1 Basecase Multiplication

Basecase $N \times M$ multiplication is a straightforward rectangular set of cross-products, the same as long multiplication done by hand and for that reason sometimes known as the schoolbook or grammar school method. This is an $O(NM)$ algorithm. See Knuth section 4.3.1 algorithm M (see Appendix B [References], page 128), and the mpn/generic/mul_basecase.c code.

Assembly implementations of mpn_mul_basecase are essentially the same as the generic C code, but have all the usual assembly tricks and obscurities introduced for speed.

A square can be done in roughly half the time of a multiply, by using the fact that the cross products above and below the diagonal are the same. A triangle of products below the diagonal is formed, doubled (left shift by one bit), and then the products on the diagonal added. This can be seen in mpn/generic/sqr_basecase.c. Again the assembly implementations take essentially the same approach.

In practice squaring isn’t a full $2 \times$ faster than multiplying, it’s usually around $1.5 \times$. Less than $1.5 \times$ probably indicates mpn_sqr_basecase wants improving on that CPU.
On some CPUs `mpn_mul_basecase` can be faster than the generic C `mpn_sqr_basecase` on some small sizes. `SQR_BASECASE_THRESHOLD` is the size at which to use `mpn_sqr_basecase`, this will be zero if that routine should be used always.

### 15.1.2 Karatsuba Multiplication

The Karatsuba multiplication algorithm is described in Knuth section 4.3.3 part A, and various other textbooks. A brief description is given here.

The inputs `x` and `y` are treated as each split into two parts of equal length (or the most significant part one limb shorter if `N` is odd).

<table>
<thead>
<tr>
<th>high</th>
<th>low</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>x_1</code></td>
<td><code>x_0</code></td>
</tr>
<tr>
<td><code>y_1</code></td>
<td><code>y_0</code></td>
</tr>
</tbody>
</table>

Let `b` be the power of 2 where the split occurs, i.e. if `x_0` is `k` limbs (`y_0` the same) then `b = 2^{k*mp_bits_per_limb}`. With that `x = x_1b + x_0` and `y = y_1b + y_0`, and the following holds,

\[ xy = (b^2 + b)x_1y_1 - b(x_1 - x_0)(y_1 - y_0) + (b + 1)x_0y_0 \]

This formula means doing only three multiplies of `(N/2)\times(N/2)` limbs, whereas a basecase multiply of `N\times N` limbs is equivalent to four multiplies of `(N/2)\times(N/2)`. The factors `(b^2 + b)` etc represent the positions where the three products must be added.

<table>
<thead>
<tr>
<th>high</th>
<th>low</th>
</tr>
</thead>
<tbody>
<tr>
<td><code>x_1y_1</code></td>
<td><code>x_0y_0</code></td>
</tr>
<tr>
<td><code>x_1y_1</code></td>
<td><code>x_1y_0</code></td>
</tr>
<tr>
<td><code>x_0y_0</code></td>
<td><code>(x_1 - x_0)(y_1 - y_0)</code></td>
</tr>
</tbody>
</table>

The term `(x_1 - x_0)(y_1 - y_0)` is best calculated as an absolute value, and the sign used to choose to add or subtract. Notice the sum `high(x_0y_0) + low(x_1y_1)` occurs twice, so it’s possible to do `5k` limb additions, rather than `6k`, but in GMP extra function call overheads outweigh the saving.

Squaring is similar to multiplying, but with `x = y` the formula reduces to an equivalent with three squares,

\[ x^2 = (b^2 + b)x_1^2 - b(x_1 - x_0)^2 + (b + 1)x_0^2 \]

The final result is accumulated from those three squares the same way as for the three multiplies above. The middle term `(x_1 - x_0)^2` is now always positive.

A similar formula for both multiplying and squaring can be constructed with a middle term `(x_1 + x_0)(y_1 + y_0)`. But those sums can exceed `k` limbs, leading to more carry handling and additions than the form above.

Karatsuba multiplication is asymptotically an \( O(N^{1.585}) \) algorithm, the exponent being \( \log 3/\log 2 \), representing 3 multiplies each 1/2 the size of the inputs. This is a big improvement over the basecase multiply at \( O(N^2) \) and the advantage soon overcomes the extra additions Karatsuba performs. `MUL_TOOM22_THRESHOLD` can be as little as 10 limbs. The `SQR` threshold is usually about twice the `MUL`.

The basecase algorithm will take a time of the form \( M(N) = aN^2 + bN + c \) and the Karatsuba algorithm \( K(N) = 3M(N/2) + dN + e \), which expands to \( K(N) = \frac{3}{4}aN^2 + \frac{3}{2}bN + 3c + dN + e \). The
factor $\frac{3}{4}$ for $a$ means per-crossproduct speedups in the basecase code will increase the threshold since they benefit $M(N)$ more than $K(N)$. And conversely the $\frac{3}{4}$ for $b$ means linear style speedups of $b$ will increase the threshold since they benefit $K(N)$ more than $M(N)$. The latter can be seen for instance when adding an optimized `mpn_sqr_diagonal` to `mpn_sqr_basecase`. Of course all speedups reduce total time, and in that sense the algorithm thresholds are merely of academic interest.

15.1.3 Toom 3-Way Multiplication

The Karatsuba formula is the simplest case of a general approach to splitting inputs that leads to both Toom and FFT algorithms. A description of Toom can be found in Knuth section 4.3.3, with an example 3-way calculation after Theorem A. The 3-way form used in GMP is described here.

The operands are each considered split into 3 pieces of equal length (or the most significant part 1 or 2 limbs shorter than the other two).

<table>
<thead>
<tr>
<th>high</th>
<th>low</th>
</tr>
</thead>
<tbody>
<tr>
<td>$x_2$</td>
<td>$x_1$</td>
</tr>
<tr>
<td>$y_2$</td>
<td>$y_1$</td>
</tr>
</tbody>
</table>

These parts are treated as the coefficients of two polynomials

$X(t) = x_2t^2 + x_1t + x_0$
$Y(t) = y_2t^2 + y_1t + y_0$

Let $b$ equal the power of 2 which is the size of the $x_0$, $x_1$, $y_0$ and $y_1$ pieces, i.e. if they’re $k$ limbs each then $b = 2^{k \cdot \text{mp_bits_per_limb}}$. With this $x = X(b)$ and $y = Y(b)$.

Let a polynomial $W(t) = X(t)Y(t)$ and suppose its coefficients are

$W(t) = w_4t^4 + w_3t^3 + w_2t^2 + w_1t + w_0$

The $w_i$ are going to be determined, and when they are they’ll give the final result using $w = W(b)$, since $xy = X(b)Y(b)$. The coefficients will be roughly $b^2$ each, and the final $W(b)$ will be an addition like,

<table>
<thead>
<tr>
<th>high</th>
<th>low</th>
</tr>
</thead>
<tbody>
<tr>
<td>$w_4$</td>
<td></td>
</tr>
<tr>
<td></td>
<td>$w_3$</td>
</tr>
<tr>
<td></td>
<td>$w_2$</td>
</tr>
<tr>
<td></td>
<td>$w_1$</td>
</tr>
<tr>
<td></td>
<td>$w_0$</td>
</tr>
</tbody>
</table>

The $w_i$ coefficients could be formed by a simple set of cross products, like $w_4 = x_2y_2$, $w_3 = x_2y_1 + x_1y_2$, $w_2 = x_2y_0 + x_1y_1 + x_0y_2$ etc, but this would need all nine $x_iy_j$ for $i, j = 0, 1, 2$, and would be equivalent merely to a basecase multiply. Instead the following approach is used. $X(t)$ and $Y(t)$ are evaluated and multiplied at 5 points, giving values of $W(t)$ at those points. In GMP the following points are used,

<table>
<thead>
<tr>
<th>Point</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>$t = 0$</td>
<td>$x_0y_0$, which gives $w_0$ immediately</td>
</tr>
<tr>
<td>$t = 1$</td>
<td>$(x_2 + x_1 + x_0)(y_2 + y_1 + y_0)$</td>
</tr>
</tbody>
</table>
\[ t = -1 \quad (x_2 - x_1 + x_0)(y_2 - y_1 + y_0) \]
\[ t = 2 \quad (4x_2 + 2x_1 + x_0)(4y_2 + 2y_1 + y_0) \]
\[ t = \infty \quad x_2y_2, \text{ which gives } w_4 \text{ immediately} \]

At \( t = -1 \) the values can be negative and that’s handled using the absolute values and tracking the sign separately. At \( t = \infty \) the value is actually \( \lim_{t \to \infty} \frac{X(t)Y(t)}{t^4} \), but it’s much easier to think of as simply \( x_2y_2 \) giving \( w_4 \) immediately (much like \( x_0y_0 \) at \( t = 0 \) gives \( w_0 \) immediately).

Each of the points substituted into \( W(t) = w_4t^4 + \cdots + w_0 \) gives a linear combination of the \( w_i \) coefficients, and the value of those combinations has just been calculated.

\[
\begin{align*}
W(0) &= w_4 + w_3 + w_2 + w_1 + w_0 \\
W(1) &= w_4 - w_3 + w_2 - w_1 + w_0 \\
W(-1) &= 16w_4 + 8w_3 + 4w_2 + 2w_1 + w_0 \\
W(\infty) &= w_4
\end{align*}
\]

This is a set of five equations in five unknowns, and some elementary linear algebra quickly isolates each \( w_i \). This involves adding or subtracting one \( W(t) \) value from another, and a couple of divisions by powers of 2 and one division by 3, the latter using the special \texttt{mpn\_divexact\_by3} (see Section 15.2.5 [Exact Division], page 102).

The conversion of \( W(t) \) values to the coefficients is interpolation. A polynomial of degree 4 like \( W(t) \) is uniquely determined by values known at 5 different points. The points are arbitrary and can be chosen to make the linear equations come out with a convenient set of steps for quickly isolating the \( w_i \).

Squaring follows the same procedure as multiplication, but there’s only one \( X(t) \) and it’s evaluated at the 5 points, and those values squared to give values of \( W(t) \). The interpolation is then identical, and in fact the same \texttt{toom\_interpolate\_5pts} subroutine is used for both squaring and multiplying.

Toom-3 is asymptotically \( O(N^{1.465}) \), the exponent being \( \log 5 / \log 3 \), representing 5 recursive multiplies of 1/3 the original size each. This is an improvement over Karatsuba at \( O(N^{1.585}) \), though Toom does more work in the evaluation and interpolation and so it only realizes its advantage above a certain size.

Near the crossover between Toom-3 and Karatsuba there’s generally a range of sizes where the difference between the two is small. \texttt{MUL\_TOOM33\_THRESHOLD} is a somewhat arbitrary point in that range and successive runs of the tune program can give different values due to small variations in measuring. A graph of time versus size for the two shows the effect, see \texttt{tune/README}.

At the fairly small sizes where the Toom-3 thresholds occur it’s worth remembering that the asymptotic behaviour for Karatsuba and Toom-3 can’t be expected to make accurate predictions, due of course to the big influence of all sorts of overheads, and the fact that only a few recursions of each are being performed. Even at large sizes there’s a good chance machine dependent effects like cache architecture will mean actual performance deviates from what might be predicted.

The formula given for the Karatsuba algorithm (see Section 15.1.2 [Karatsuba Multiplication], page 95) has an equivalent for Toom-3 involving only five multiplies, but this would be complicated and unenlightening.

An alternate view of Toom-3 can be found in Zuras (see Appendix B [References], page 128), using a vector to represent the \( x \) and \( y \) splits and a matrix multiplication for the evaluation and interpolation stages. The matrix inverses are not meant to be actually used, and they have elements with values much greater than in fact arise in the interpolation steps. The diagram
shown for the 3-way is attractive, but again doesn’t have to be implemented that way and for example with a bit of rearrangement just one division by 6 can be done.

### 15.1.4 Toom 4-Way Multiplication

Karatsuba and Toom-3 split the operands into 2 and 3 coefficients, respectively. Toom-4 analogously splits the operands into 4 coefficients. Using the notation from the section on Toom-3 multiplication, we form two polynomials:

\[ X(t) = x_3t^3 + x_2t^2 + x_1t + x_0 \]
\[ Y(t) = y_3t^3 + y_2t^2 + y_1t + y_0 \]

\(X(t)\) and \(Y(t)\) are evaluated and multiplied at 7 points, giving values of \(W(t)\) at those points. In GMP the following points are used,

<table>
<thead>
<tr>
<th>Point</th>
<th>Value</th>
</tr>
</thead>
<tbody>
<tr>
<td>(t = 0)</td>
<td>(x_0y_0), which gives (w_0) immediately</td>
</tr>
<tr>
<td>(t = 1/2)</td>
<td>((x_3 + 2x_2 + 4x_1 + 8x_0)(y_3 + 2y_2 + 4y_1 + 8y_0))</td>
</tr>
<tr>
<td>(t = -1/2)</td>
<td>((-x_3 + 2x_2 - 4x_1 + 8x_0)(-y_3 + 2y_2 - 4y_1 + 8y_0))</td>
</tr>
<tr>
<td>(t = 1)</td>
<td>((x_3 + x_2 + x_1 + x_0)(y_3 + y_2 + y_1 + y_0))</td>
</tr>
<tr>
<td>(t = -1)</td>
<td>((-x_3 + x_2 - x_1 + x_0)(-y_3 + y_2 - y_1 + y_0))</td>
</tr>
<tr>
<td>(t = 2)</td>
<td>((8x_3 + 4x_2 + 2x_1 + x_0)(8y_3 + 4y_2 + 2y_1 + y_0))</td>
</tr>
<tr>
<td>(t = \infty)</td>
<td>(x_3y_3), which gives (w_6) immediately</td>
</tr>
</tbody>
</table>

The number of additions and subtractions for Toom-4 is much larger than for Toom-3. But several subexpressions occur multiple times, for example \(x_2 + x_0\), occurs for both \(t = 1\) and \(t = -1\).

Toom-4 is asymptotically \(O(N^{1.404})\), the exponent being \(\log 7/\log 4\), representing 7 recursive multiplies of 1/4 the original size each.

### 15.1.5 Higher degree Toom’n’half

The Toom algorithms described above (see Section 15.1.3 [Toom 3-Way Multiplication], page 96, see Section 15.1.4 [Toom 4-Way Multiplication], page 98) generalizes to split into an arbitrary number of pieces. In general a split of two equally long operands into \(r\) pieces leads to evaluations and pointwise multiplications done at \(2r - 1\) points. To fully exploit symmetries it would be better to have a multiple of 4 points, that’s why for higher degree Toom’n’half is used.

Toom’n’half means that the existence of one more piece is considered for a single operand. It can be virtual, i.e. zero, or real, when the two operand are not exactly balanced. By choosing an even \(r\), Toom-\(r\frac{1}{2}\) requires \(2r\) points, a multiple of four.

The quadruplets of points include 0, \(\infty\), +1, -1 and \(\pm 2^i\), \(\pm 2^{-i}\). Each of them giving shortcuts for the evaluation phase and for some steps in the interpolation phase. Further tricks are used to reduce the memory footprint of the whole multiplication algorithm to a memory buffer equal in size to the result of the product.

Current GMP uses both Toom-6’n’half and Toom-8’n’half.

### 15.1.6 FFT Multiplication

At large to very large sizes a Fermat style FFT multiplication is used, following Schönhage and Strassen (see Appendix B [References], page 128). Descriptions of FFTs in various forms can be found in many textbooks, for instance Knuth section 4.3.3 part C or Lipson chapter IX. A brief description of the form used in GMP is given here.
The multiplication done is \( xy \mod 2^N + 1 \), for a given \( N \). A full product \( xy \) is obtained by choosing \( N \geq \text{bits}(x) + \text{bits}(y) \) and padding \( x \) and \( y \) with high zero limbs. The modular product is the native form for the algorithm, so padding to get a full product is unavoidable.

The algorithm follows a split, evaluate, pointwise multiply, interpolate and combine similar to that described above for Karatsuba and Toom-3. A \( k \) parameter controls the split, with an FFT-\( k \) splitting into \( 2^k \) pieces of \( M = N/2^k \) bits each. \( N \) must be a multiple of \( 2^k \times \text{mp_bits_per_limb} \) so the split falls on limb boundaries, avoiding bit shifts in the split and combine stages.

The evaluations, pointwise multiplications, and interpolation, are all done modulo \( 2^{N'} + 1 \) where \( N' \) is \( 2M + k + 3 \) rounded up to a multiple of \( 2^k \) and of \( \text{mp_bits_per_limb} \). The results of interpolation will be the following negacyclic convolution of the input pieces, and the choice of \( N' \) ensures these sums aren’t truncated.

\[
w_n = \sum_{i+j=2^k+n \quad 4 \mid i+1} (-1)^b x_i y_j
\]

The points used for the evaluation are \( g^i \) for \( i = 0 \) to \( 2^k - 1 \) where \( g = 2^{2^{N'}/2^k} \). \( g \) is a \( 2^k \)th root of unity mod \( 2^{N'} + 1 \), which produces necessary cancellations at the interpolation stage, and it’s also a power of 2 so the fast Fourier transforms used for the evaluation and interpolation do only shifts, adds and negations.

The pointwise multiplications are done modulo \( 2^{N'} + 1 \) and either recurse into a further FFT or use a plain multiplication (Toom-3, Karatsuba or basecase), whichever is optimal at the size \( N' \). The interpolation is an inverse fast Fourier transform. The resulting set of sums of \( x_i y_j \) are added at appropriate offsets to give the final result.

Squaring is the same, but \( x \) is the only input so it’s one transform at the evaluate stage and the pointwise multiplies are squares. The interpolation is the same.

For a mod \( 2^N + 1 \) product, an FFT-\( k \) is an \( O(N^{k/(k-1)}) \) algorithm, the exponent representing \( 2^k \) recursed modular multiplies each \( 1/2^{k-1} \) the size of the original. Each successive \( k \) is an asymptotic improvement, but overheads mean each is only faster at bigger and bigger sizes. In the code, \texttt{MUL_FFT_TABLE} and \texttt{SQR_FFT_TABLE} are the thresholds where each \( k \) is used. Each new \( k \) effectively swaps some multiplying for some shifts, adds and overheads.

A mod \( 2^N + 1 \) product can be formed with a normal \( N \times N \to 2N \) bit multiply plus a subtraction, so an FFT and Toom-3 etc can be compared directly. A \( k = 4 \) FFT at \( O(N^{1.33}) \) can be expected to be the first faster than Toom-3 at \( O(N^{1.465}) \). In practice this is what’s found, with \texttt{MUL_FFT_MODF_THRESHOLD} and \texttt{SQR_FFT_MODF_THRESHOLD} being between 300 and 1000 limbs, depending on the CPU. So far it’s been found that only very large FFTs recurse into pointwise multiplies above these sizes.

When an FFT is to give a full product, the change of \( N \) to \( 2N \) doesn’t alter the theoretical complexity for a given \( k \), but for the purposes of considering where an FFT might be first used it can be assumed that the FFT is recursing into a normal multiply and that on that basis it’s doing \( 2^k \) recursed multiplies each \( 1/2^{k-2} \) the size of the inputs, making it \( O(N^{k/(k-2)}) \). This would mean \( k = 7 \) at \( O(N^{1.4}) \) would be the first FFT faster than Toom-3. In practice \texttt{MUL_FFT_THRESHOLD} and \texttt{SQR_FFT_THRESHOLD} have been found to be in the \( k = 8 \) range, somewhere between 3000 and 10000 limbs.

The way \( N \) is split into \( 2^k \) pieces and then \( 2M + k + 3 \) is rounded up to a multiple of \( 2^k \) and \texttt{mp_bits_per_limb} means that when \( 2^k \geq \text{mp_bits_per_limb} \) the effective \( N \) is a multiple of \( 2^{2k-1} \) bits. The \( +k + 3 \) means some values of \( N \) just under such a multiple will be rounded to the next. The complexity calculations above assume that a favourable size is used, meaning one which isn’t padded through rounding, and it’s also assumed that the extra \( +k + 3 \) bits are negligible at typical FFT sizes.
The practical effect of the $2^{2k-1}$ constraint is to introduce a step-effect into measured speeds. For example $k = 8$ will round $N$ up to a multiple of 32768 bits, so for a 32-bit limb there’ll be 512 limb groups of sizes for which mpn_mul_n runs at the same speed. Or for $k = 9$ groups of 2048 limbs, $k = 10$ groups of 8192 limbs, etc. In practice it’s been found each $k$ is used at quite small multiples of its size constraint and so the step effect is quite noticeable in a time versus size graph.

The threshold determinations currently measure at the mid-points of size steps, but this is sub-optimal since at the start of a new step it can happen that it’s better to go back to the previous $k$ for a while. Something more sophisticated for MUL_FFT_TABLE and SQR_FFT_TABLE will be needed.

### 15.1.7 Other Multiplication

The Toom algorithms described above (see Section 15.1.3 [Toom 3-Way Multiplication], page 96, see Section 15.1.4 [Toom 4-Way Multiplication], page 98) generalizes to split into an arbitrary number of pieces, as per Knuth section 4.3.3 algorithm C. This is not currently used. The notes here are merely for interest.

In general a split into $r + 1$ pieces is made, and evaluations and pointwise multiplications done at $2r + 1$ points. A 4-way split does 7 pointwise multiplies, 5-way does 9, etc. Asymptotically an $(r + 1)$-way algorithm is $O(N^{\log(2r+1)/\log(r+1)})$. Only the pointwise multiplications count towards big-$O$ complexity, but the time spent in the evaluate and interpolate stages grows with $r$ and has a significant practical impact, with the asymptotic advantage of each $r$ realized only at bigger and bigger sizes. The overheads grow as $O(Nr)$, whereas in an $r = 2^k$ FFT they grow only as $O(N \log r)$.

Knuth algorithm C evaluates at points $0, 1, 2, \ldots, 2r$, but exercise 4 uses $-r, \ldots, 0, \ldots, r$ and the latter saves some small multiplies in the evaluate stage (or rather trades them for additions), and has a further saving of nearly half the interpolate steps. The idea is to separate odd and even final coefficients and then perform algorithm C steps C7 and C8 on them separately. The divisors at step C7 become $j^2$ and the multipliers at C8 become $2tj - j^2$.

Splitting odd and even parts through positive and negative points can be thought of as using $-1$ as a square root of unity. If a 4th root of unity was available then a further split and speedup would be possible, but no such root exists for plain integers. Going to complex integers with $i = \sqrt{-1}$ doesn’t help, essentially because in Cartesian form it takes three real multiplies to do a complex multiply. The existence of $2^k$th roots of unity in a suitable ring or field lets the fast Fourier transform keep splitting and get to $O(N \log r)$.

Floating point FFTs use complex numbers approximating Nth roots of unity. Some processors have special support for such FFTs. But these are not used in GMP since it’s very difficult to guarantee an exact result (to some number of bits). An occasional difference of 1 in the last bit might not matter to a typical signal processing algorithm, but is of course of vital importance to GMP.

### 15.1.8 Unbalanced Multiplication

Multiplication of operands with different sizes, both below MUL_TOOM22_THRESHOLD are done with plain schoolbook multiplication (see Section 15.1.1 [Basecase Multiplication], page 94).

For really large operands, we invoke FFT directly.

For operands between these sizes, we use Toom inspired algorithms suggested by Alberto Zanoni and Marco Bodrato. The idea is to split the operands into polynomials of different degree. GMP currently splits the smaller operand onto 2 coefficients, i.e., a polynomial of degree 1, but the larger operand can be split into 2, 3, or 4 coefficients, i.e., a polynomial of degree 1 to 3.
15.2 Division Algorithms

15.2.1 Single Limb Division

\( N \times 1 \) division is implemented using repeated \( 2 \times 1 \) divisions from high to low, either with a hardware divide instruction or a multiplication by inverse, whichever is best on a given CPU.

The multiply by inverse follows “Improved division by invariant integers” by Möller and Granlund (see Appendix B [References], page 128) and is implemented as `udiv_qrnnd_preinv` in `gmp-impl.h`. The idea is to have a fixed-point approximation to \( 1/d \) (see `invert_limb`) and then multiply by the high limb (plus one bit) of the dividend to get a quotient \( q \). With \( d \) normalized (high bit set), \( q \) is no more than 1 too small. Subtraction of \( qd \) from the dividend gives a remainder, and reveals whether \( q \) or \( q - 1 \) is correct.

The result is a division done with two multiplications and four or five arithmetic operations. On CPUs with low latency multipliers this can be much faster than a hardware divide, though the cost of calculating the inverse at the start may mean it’s only better on inputs bigger than say 4 or 5 limbs.

When a divisor must be normalized, either for the generic C `__udiv_qrnnd_c` or the multiply by inverse, the division performed is actually \( a2^k \) by \( d2^k \) where \( a \) is the dividend and \( k \) is the power necessary to have the high bit of \( d2^k \) set. The bit shifts for the dividend are usually accomplished “on the fly” meaning by extracting the appropriate bits at each step. Done this way the quotient limbs come out aligned ready to store. When only the remainder is wanted, an alternative is to take the dividend limbs unshifted and calculate \( r = a \mod d2^k \) followed by an extra final step \( r2^k \mod d2^k \). This can help on CPUs with poor bit shifts or few registers.

The multiply by inverse can be done two limbs at a time. The calculation is basically the same, but the inverse is two limbs and the divisor treated as if padded with a low zero limb. This means more work, since the inverse will need a \( 2 \times 2 \) multiply, but the four \( 1 \times 1 \)s to do that are independent and can therefore be done partly or wholly in parallel. Likewise for a \( 2 \times 1 \) calculating \( qd \). The net effect is to process two limbs with roughly the same two multiplies worth of latency that one limb at a time gives. This extends to 3 or 4 limbs at a time, though the extra work to apply the inverse will almost certainly soon reach the limits of multiplier throughput.

A similar approach in reverse can be taken to process just half a limb at a time if the divisor is only a half limb. In this case the \( 1 \times 1 \) multiply for the inverse effectively becomes two \( \frac{1}{2} \times 1 \) for each limb, which can be a saving on CPUs with a fast half limb multiply, or in fact if the only multiply is a half limb, and especially if it’s not pipelined.

15.2.2 Basecase Division

Basecase \( N \times M \) division is like long division done by hand, but in base \( 2^\text{mp\_bits\_per\_limb} \). See Knuth section 4.3.1 algorithm D, and `mpn/generic/sb_divrem_mn.c`.

Briefly stated, while the dividend remains larger than the divisor, a high quotient limb is formed and the \( N \times 1 \) product \( qd \) subtracted at the top end of the dividend. With a normalized divisor (most significant bit set), each quotient limb can be formed with a \( 2 \times 1 \) division and a \( 1 \times 1 \) multiplication plus some subtractions. The \( 2 \times 1 \) division is by the high limb of the divisor and is done either with a hardware divide or a multiply by inverse (the same as in Section 15.2.1 [Single Limb Division], page 101) whichever is faster. Such a quotient is sometimes one too big, requiring an addback of the divisor, but that happens rarely.

With \( Q = N - M \) being the number of quotient limbs, this is an \( O(QM) \) algorithm and will run at a speed similar to a basecase \( Q \times M \) multiplication, differing in fact only in the extra multiply and divide for each of the \( Q \) quotient limbs.
15.2.3 Divide and Conquer Division

For divisors larger than DC_DIV_QR_THRESHOLD, division is done by dividing. Or to be precise by a recursive divide and conquer algorithm based on work by Moenck and Borodin, Jebelean, and Burnikel and Ziegler (see Appendix B [References], page 128).

The algorithm consists essentially of recognising that a $2N \times N$ division can be done with the basecase division algorithm (see Section 15.2.2 [Basecase Division], page 101), but using $N/2$ limbs as a base, not just a single limb. This way the multiplications that arise are $(N/2) \times (N/2)$ and can take advantage of Karatsuba and higher multiplication algorithms (see Section 15.1 [Multiplication Algorithms], page 94). The two “digits” of the quotient are formed by recursive $N \times (N/2)$ divisions.

If the $(N/2) \times (N/2)$ multiplies are done with a basecase multiplication then the work is about the same as a basecase division, but with more function call overheads and with some subtractions separated from the multiplies. These overheads mean that it’s only when $N/2$ is above MUL_TOOM22_THRESHOLD that divide and conquer is of use.

DC_DIV_QR_THRESHOLD is based on the divisor size $N$, so it will be somewhere above twice MUL_TOOM22_THRESHOLD, but how much above depends on the CPU. An optimized mpn_mul_basecase can lower DC_DIV_QR_THRESHOLD a little by offering a ready-made advantage over repeated mpn_submul_1 calls.

Divide and conquer is asymptotically $O(M(N) \log N)$ where $M(N)$ is the time for an $N \times N$ multiplication done with FFTs. The actual time is a sum over multiplications of the recursed sizes, as can be seen near the end of section 2.2 of Burnikel and Ziegler. For example, within the Toom-3 range, divide and conquer is $2.63M(N)$. With higher algorithms the $M(N)$ term improves and the multiplier tends to $\log N$. In practice, at moderate to large sizes, a $2N \times N$ division is about 2 to 4 times slower than an $N \times N$ multiplication.

15.2.4 Block-Wise Barrett Division

For the largest divisions, a block-wise Barrett division algorithm is used. Here, the divisor is inverted to a precision determined by the relative size of the dividend and divisor. Blocks of quotient limbs are then generated by multiplying blocks from the dividend by the inverse.

Our block-wise algorithm computes a smaller inverse than in the plain Barrett algorithm. For a $2n/n$ division, the inverse will be just $[n/2]$ limbs.

15.2.5 Exact Division

A so-called exact division is when the dividend is known to be an exact multiple of the divisor. Jebelean’s exact division algorithm uses this knowledge to make some significant optimizations (see Appendix B [References], page 128).

The idea can be illustrated in decimal for example with 368154 divided by 543. Because the low digit of the dividend is 4, the low digit of the quotient must be 8. This is arrived at from $4 \times 7 \mod 10$, using the fact 7 is the modular inverse of 3 (the low digit of the divisor), since $3 \times 7 \equiv 1 \mod 10$. So $8 \times 543 = 4344$ can be subtracted from the dividend leaving 363810. Notice the low digit has become zero.

The procedure is repeated at the second digit, with the next quotient digit 7 ($1 \times 7 \mod 10$), subtracting $7 \times 543 = 3801$, leaving 325800. And finally at the third digit with quotient digit 6 ($8 \times 7 \mod 10$), subtracting $6 \times 543 = 3258$ leaving 0. So the quotient is 678.

Notice however that the multiplies and subtractions don’t need to extend past the low three digits of the dividend, since that’s enough to determine the three quotient digits. For the last
quotient digit no subtraction is needed at all. On a 2N×N division like this one, only about half the work of a normal basecase division is necessary.

For an N×M exact division producing Q=N−M quotient limbs, the saving over a normal basecase division is in two parts. Firstly, each of the Q quotient limbs needs only one multiply, not a 2×1 divide and multiply. Secondly, the crossproducts are reduced when \( Q > M \) to \( QM - M(M+1)/2 \), or when \( Q \leq M \) to \( Q(Q - 1)/2 \). Notice the savings are complementary. If \( Q \) is big then many divisions are saved, or if \( Q \) is small then the crossproducts reduce to a small number.

The modular inverse used is calculated efficiently by `binvert_limb` in `gmp-impl.h`. This does four multiplies for a 32-bit limb, or six for a 64-bit limb. `tune/modlinv.c` has some alternate implementations that might suit processors better at bit twiddling than multiplying.

The sub-quadratic exact division described by Jebelean in “Exact Division with Karatsuba Complexity” is not currently implemented. It uses a rearrangement similar to the divide and conquer for normal division (see Section 15.2.3 [Divide and Conquer Division], page 102), but operating from low to high. A further possibility not currently implemented is “Bidirectional Exact Integer Division” by Krindick and Jebelean which forms quotient limbs from both the high and low ends of the dividend, and can halve once more the number of crossproducts needed in a 2N×N division.

A special case exact division by 3 exists in `mpn_divexact_by3`, supporting Toom-3 multiplication and `mpq` canonicalizations. It forms quotient digits with a multiply by the modular inverse of 3 (which is 0xAA..AAB) and uses two comparisons to determine a borrow for the next limb. The multiplications don’t need to be on the dependent chain, as long as the effect of the borrows is applied, which can help chips with pipelined multipliers.

### 15.2.6 Exact Remainder

If the exact division algorithm is done with a full subtraction at each stage and the dividend isn’t a multiple of the divisor, then low zero limbs are produced but with a remainder in the high limbs. For dividend \( a \), divisor \( d \), quotient \( q \), and \( b = 2^{\text{mp\_bits\_per\_limb}} \), this remainder \( r \) is of the form

\[
a =qd + rb^n
\]

\( n \) represents the number of zero limbs produced by the subtractions, that being the number of limbs produced for \( q \). \( r \) will be in the range \( 0 \leq r < d \) and can be viewed as a remainder, but one shifted up by a factor of \( b^n \).

Carrying out full subtractions at each stage means the same number of cross products must be done as a normal division, but there’s still some single limb divisions saved. When \( d \) is a single limb some simplifications arise, providing good speedups on a number of processors.

The functions `mpn_divexact_by3`, `mpn_modexact_1_odd` and the internal `mpn_redc_X` functions differ subtly in how they return \( r \), leading to some negations in the above formula, but all are essentially the same.

Clearly \( r \) is zero when \( a \) is a multiple of \( d \), and this leads to divisibility or congruence tests which are potentially more efficient than a normal division.

The factor of \( b^n \) on \( r \) can be ignored in a GCD when \( d \) is odd, hence the use of `mpn_modexact_1_odd` by `mpn_gcd_1` and `mpz_kronecker_ui` etc (see Section 15.3 [Greatest Common Divisor Algorithms], page 104).

Montgomery’s REDC method for modular multiplications uses operands of the form of \( xb^{-n} \) and \( yb^{-n} \) and on calculating \((xb^{-n})(yb^{-n})\) uses the factor of \( b^n \) in the exact remainder to reach a product in the same form \((xy)b^{-n}\) (see Section 15.4.2 [Modular Powering Algorithm], page 107).
Notice that \( r \) generally gives no useful information about the ordinary remainder \( a \mod d \) since \( b^n \mod d \) could be anything. If however \( b^n \equiv 1 \mod d \), then \( r \) is the negative of the ordinary remainder. This occurs whenever \( d \) is a factor of \( b^n - 1 \), as for example with 3 in \texttt{mpn\_divexact\_by3}. For a 32 or 64 bit limb other such factors include 5, 17 and 257, but no particular use has been found for this.

15.2.7 Small Quotient Division

An \( N \times M \) division where the number of quotient limbs \( Q = N - M \) is small can be optimized somewhat.

An ordinary basecase division normalizes the divisor by shifting it to make the high bit set, shifting the dividend accordingly, and shifting the remainder back down at the end of the calculation. This is wasteful if only a few quotient limbs are to be formed. Instead a division of just the top \( 2Q \) limbs of the dividend by the top \( Q \) limbs of the divisor can be used to form a trial quotient. This requires only those limbs normalized, not the whole of the divisor and dividend.

A multiply and subtract then applies the trial quotient to the \( M - Q \) unused limbs of the divisor and \( N - Q \) dividend limbs (which includes \( Q \) limbs remaining from the trial quotient division). The starting trial quotient can be 1 or 2 too big, but all cases of 2 too big and most cases of 1 too big are detected by first comparing the most significant limbs that will arise from the subtraction. An addback is done if the quotient still turns out to be 1 too big.

This whole procedure is essentially the same as one step of the basecase algorithm done in a \( Q \) limb base, though with the trial quotient test done only with the high limbs, not an entire \( Q \) limb “digit” product. The correctness of this weaker test can be established by following the argument of Knuth section 4.3.1 exercise 20 but with the \( v_2 \hat{q} > b \hat{r} + u_2 \) condition appropriately relaxed.

15.3 Greatest Common Divisor

15.3.1 Binary GCD

At small sizes GMP uses an \( O(N^2) \) binary style GCD. This is described in many textbooks, for example Knuth section 4.5.2 algorithm B. It simply consists of successively reducing odd operands \( a \) and \( b \) using

\[
a, b = \text{abs}(a - b), \min(a, b) \\
\text{strip factors of 2 from } a
\]

The Euclidean GCD algorithm, as per Knuth algorithms E and A, repeatedly computes the quotient \( q = \lfloor a/b \rfloor \) and replaces \( a, b \) by \( v, u - qv \). The binary algorithm has so far been found to be faster than the Euclidean algorithm everywhere. One reason the binary method does well is that the implied quotient at each step is usually small, so often only one or two subtractions are needed to get the same effect as a division. Quotients 1, 2 and 3 for example occur 67.7% of the time, see Knuth section 4.5.3 Theorem E.

When the implied quotient is large, meaning \( b \) is much smaller than \( a \), then a division is worthwhile. This is the basis for the initial \( a \mod b \) reductions in \texttt{mpn\_gcd} and \texttt{mpn\_gcd\_1} (the latter for both \( N \times 1 \) and \( 1 \times 1 \) cases). But after that initial reduction, big quotients occur too rarely to make it worth checking for them.

The final \( 1 \times 1 \) GCD in \texttt{mpn\_gcd\_1} is done in the generic C code as described above. For two \( N \)-bit operands, the algorithm takes about 0.68 iterations per bit. For optimum performance some attention needs to be paid to the way the factors of 2 are stripped from \( a \).
Firstly it may be noted that in twos complement the number of low zero bits on \( a - b \) is the same as \( b - a \), so counting or testing can begin on \( a - b \) without waiting for \( \text{abs}(a - b) \) to be determined.

A loop stripping low zero bits tends not to branch predict well, since the condition is data dependent. But on average there’s only a few low zeros, so an option is to strip one or two bits arithmetically then loop for more (as done for AMD K6). Or use a lookup table to get a count for several bits then loop for more (as done for AMD K7). An alternative approach is to keep just one of \( a \) or \( b \) odd and iterate

\[
a, b = \text{abs}(a - b), \min(a, b) \\
a = a / 2 \text{ if even} \\
b = b / 2 \text{ if even}
\]

This requires about 1.25 iterations per bit, but stripping of a single bit at each step avoids any branching. Repeating the bit strip reduces to about 0.9 iterations per bit, which may be a worthwhile tradeoff.

Generally with the above approaches a speed of perhaps 6 cycles per bit can be achieved, which is still not terribly fast with for instance a 64-bit GCD taking nearly 400 cycles. It’s this sort of time which means it’s not usually advantageous to combine a set of divisibility tests into a GCD.

Currently, the binary algorithm is used for GCD only when \( N < 3 \).

### 15.3.2 Lehmer’s algorithm

Lehmer’s improvement of the Euclidean algorithms is based on the observation that the initial part of the quotient sequence depends only on the most significant parts of the inputs. The variant of Lehmer’s algorithm used in GMP splits off the most significant two limbs, as suggested, e.g., in “A Double-Digit Lehmer-Euclid Algorithm” by Jebelean (see Appendix B [References], page 128). The quotients of two double-limb inputs are collected as a 2 by 2 matrix with single-limb elements. This is done by the function \( \text{mpn\_hgcd2} \). The resulting matrix is applied to the inputs using \( \text{mpn\_mul\_1} \) and \( \text{mpn\_submul\_1} \). Each iteration usually reduces the inputs by almost one limb. In the rare case of a large quotient, no progress can be made by examining just the most significant two limbs, and the quotient is computed using plain division.

The resulting algorithm is asymptotically \( O(N^2) \), just as the Euclidean algorithm and the binary algorithm. The quadratic part of the work are the calls to \( \text{mpn\_mul\_1} \) and \( \text{mpn\_submul\_1} \). For small sizes, the linear work is also significant. There are roughly \( N \) calls to the \( \text{mpn\_hgcd2} \) function. This function uses a couple of important optimizations:

- It uses the same relaxed notion of correctness as \( \text{mpn\_gcd} \) (see next section). This means that when called with the most significant two limbs of two large numbers, the returned matrix does not always correspond exactly to the initial quotient sequence for the two large numbers; the final quotient may sometimes be one off.
- It takes advantage of the fact the quotients are usually small. The division operator is not used, since the corresponding assembler instruction is very slow on most architectures. (This code could probably be improved further, it uses many branches that are unfriendly to prediction).
- It switches from double-limb calculations to single-limb calculations half-way through, when the input numbers have been reduced in size from two limbs to one and a half.

### 15.3.3 Subquadratic GCD

For inputs larger than \( \text{GCD\_DC\_THRESHOLD} \), GCD is computed via the \( \text{HGCD} \) (Half GCD) function, as a generalization to Lehmer’s algorithm.
Let the inputs $a, b$ be of size $N$ limbs each. Put $S = \lceil N/2 \rceil + 1$. Then HGCD(a,b) returns a transformation matrix $T$ with non-negative elements, and reduced numbers $(c; d) = T^{-1}(a; b)$. The reduced numbers $c, d$ must be larger than $S$ limbs, while their difference $\abs{c - d}$ must fit in $S$ limbs. The matrix elements will also be of size roughly $N/2$.

The HGCD base case uses Lehmer’s algorithm, but with the above stop condition that returns reduced numbers and the corresponding transformation matrix half-way through. For inputs larger than $\text{HGCD\_THRESHOLD}$, HGCD is computed recursively, using the divide and conquer algorithm in “On Schönhage’s algorithm and subquadratic integer GCD computation” by Möller (see Appendix B [References], page 128). The recursive algorithm consists of these main steps.

- Call HGCD recursively, on the most significant $N/2$ limbs. Apply the resulting matrix $T_1$ to the full numbers, reducing them to a size just above $3N/2$.
- Perform a small number of division or subtraction steps to reduce the numbers to size below $3N/2$. This is essential mainly for the unlikely case of large quotients.
- Call HGCD recursively, on the most significant $N/2$ limbs of the reduced numbers. Apply the resulting matrix $T_2$ to the full numbers, reducing them to a size just above $N/2$.
- Compute $T = T_1T_2$.
- Perform a small number of division and subtraction steps to satisfy the requirements, and return.

GCD is then implemented as a loop around HGCD, similarly to Lehmer’s algorithm. Where Lehmer repeatedly chops off the top two limbs, calls mpn_hgcd2, and applies the resulting matrix to the full numbers, the sub-quadratic GCD chops off the most significant third of the limbs (the proportion is a tuning parameter, and $1/3$ seems to be more efficient than, e.g, $1/2$), calls mpn_hgcd, and applies the resulting matrix. Once the input numbers are reduced to size below $\text{GCD\_DC\_THRESHOLD}$, Lehmer’s algorithm is used for the rest of the work.

The asymptotic running time of both HGCD and GCD is $O(M(N) \log N)$, where $M(N)$ is the time for multiplying two $N$-limb numbers.

### 15.3.4 Extended GCD

The extended GCD function, or GCDEXT, calculates gcd $(a, b)$ and also cofactors $x$ and $y$ satisfying $ax + by = \gcd(a,b)$. All the algorithms used for plain GCD are extended to handle this case. The binary algorithm is used only for single-limb GCDEXT. Lehmer’s algorithm is used for sizes up to $\text{GCDEXT\_DC\_THRESHOLD}$. Above this threshold, GCDEXT is implemented as a loop around HGCD, but with more book-keeping to keep track of the cofactors. This gives the same asymptotic running time as for GCD and HGCD, $O(M(N) \log N)$.

One difference to plain GCD is that while the inputs $a$ and $b$ are reduced as the algorithm proceeds, the cofactors $x$ and $y$ grow in size. This makes the tuning of the chopping-point more difficult. The current code chops off the most significant half of the inputs for the call to HGCD in the first iteration, and the most significant two thirds for the remaining calls. This strategy could surely be improved. Also the stop condition for the loop, where Lehmer’s algorithm is invoked once the inputs are reduced below $\text{GCDEXT\_DC\_THRESHOLD}$, could maybe be improved by taking into account the current size of the cofactors.

### 15.3.5 Jacobi Symbol

Jacobi symbol $(\frac{a}{b})$

Initially if either operand fits in a single limb, a reduction is done with either mpn_mod_1 or mpn_modexact_1_odd, followed by the binary algorithm on a single limb. The binary algorithm is well suited to a single limb, and the whole calculation in this case is quite efficient.
For inputs larger than GCD_DC_THRESHOLD, mpz_jacobi, mpz_legendre and mpz_kronecker are computed via the HGCD (Half GCD) function, as a generalization to Lehmer’s algorithm.

Most GCD algorithms reduce $a$ and $b$ by repeatedly computing the quotient $q = \lfloor a/b \rfloor$ and iteratively replacing

$$a, b = b, a - q \times b$$

Different algorithms use different methods for calculating $q$, but the core algorithm is the same if we use Section 15.3.2 [Lehmer’s Algorithm], page 105 or Section 15.3.3 [Subquadratic GCD], page 105.

At each step it is possible to compute if the reduction inverts the Jacobi symbol based on the two least significant bits of $a$ and $b$. For more details see “Efficient computation of the Jacobi symbol” by Möller (see Appendix B [References], page 128).

A small set of bits is thus used to track state

- current sign of result (1 bit)
- two least significant bits of $a$ and $b$ (4 bits)
- a pointer to which input is currently the denominator (1 bit)

In all the routines sign changes for the result are accumulated using fast bit twiddling which avoids conditional jumps.

The final result is calculated after verifying the inputs are coprime ($\text{GCD} = 1$) by raising $(-1)^e$

Much of the HGCD code is shared directly with the HGCD implementations, such as the $2 \times 2$ matrix calculation, See Section 15.3.2 [Lehmer’s Algorithm], page 105 basecase and GCD_DC_THRESHOLD.

The asymptotic running time is $O(M(N) \log N)$, where $M(N)$ is the time for multiplying two $N$-limb numbers.

15.4 Powering Algorithms

15.4.1 Normal Powering

Normal mpz or mpf powering uses a simple binary algorithm, successively squaring and then multiplying by the base when a 1 bit is seen in the exponent, as per Knuth section 4.6.3. The “left to right” variant described there is used rather than algorithm A, since it’s just as easy and can be done with somewhat less temporary memory.

15.4.2 Modular Powering

Modular powering is implemented using a $2^k$-ary sliding window algorithm, as per “Handbook of Applied Cryptography” algorithm 14.85 (see Appendix B [References], page 128). $k$ is chosen according to the size of the exponent. Larger exponents use larger values of $k$, the choice being made to minimize the average number of multiplications that must supplement the squaring.

The modular multiplies and squarings use either a simple division or the REDC method by Montgomery (see Appendix B [References], page 128). REDC is a little faster, essentially saving $N$ single limb divisions in a fashion similar to an exact remainder (see Section 15.2.6 [Exact Remainder], page 103).

15.5 Root Extraction Algorithms
15.5.1 Square Root

Square roots are taken using the “Karatsuba Square Root” algorithm by Paul Zimmermann (see Appendix B [References], page 128).

An input $n$ is split into four parts of $k$ bits each, so with $b = 2^k$ we have $n = a_3b^3 + a_2b^2 + a_1b + a_0$. Part $a_3$ must be “normalized” so that either the high or second highest bit is set. In GMP, $k$ is kept on a limb boundary and the input is left shifted (by an even number of bits) to normalize.

The square root of the high two parts is taken, by recursive application of the algorithm (bottoming out in a one-limb Newton’s method),

$$s', r' = \text{sqrem} (a_3b + a_2)$$

This is an approximation to the desired root and is extended by a division to give $s,r$,

$$q, u = \text{divrem} (r'b + a_1, 2s')$$

$$s = s'b + q$$

$$r = ub + a_0 - q^2$$

The normalization requirement on $a_3$ means at this point $s$ is either correct or $1$ too big. $r$ is negative in the latter case, so

if $r < 0$ then

$$r \leftarrow r + 2s - 1$$

$$s \leftarrow s - 1$$

The algorithm is expressed in a divide and conquer form, but as noted in the paper it can also be viewed as a discrete variant of Newton’s method, or as a variation on the schoolboy method (no longer taught) for square roots two digits at a time.

If the remainder $r$ is not required then usually only a few high limbs of $r$ and $u$ need to be calculated to determine whether an adjustment to $s$ is required. This optimization is not currently implemented.

In the Karatsuba multiplication range this algorithm is $O\left(3^2 M(N/2)\right)$, where $M(n)$ is the time to multiply two numbers of $n$ limbs. In the FFT multiplication range this grows to a bound of $O(6M(N/2))$. In practice a factor of about 1.5 to 1.8 is found in the Karatsuba and Toom-3 ranges, growing to 2 or 3 in the FFT range.

The algorithm does all its calculations in integers and the resulting mpn_sqrtrem is used for both mpz_sqrt and mpf_sqrt. The extended precision given by mpf_sqrt_ui is obtained by padding with zero limbs.

15.5.2 Nth Root

Integer Nth roots are taken using Newton’s method with the following iteration, where $A$ is the input and $n$ is the root to be taken.

$$a_{i+1} = \frac{1}{n} \left( \frac{A}{a_i^n} + (n - 1)a_i \right)$$

The initial approximation $a_1$ is generated bitwise by successively powering a trial root with or without new 1 bits, aiming to be just above the true root. The iteration converges quadratically when started from a good approximation. When $n$ is large more initial bits are needed to get good convergence. The current implementation is not particularly well optimized.
15.5.3 Perfect Square

A significant fraction of non-squares can be quickly identified by checking whether the input is a quadratic residue modulo small integers.

\texttt{mpz\_perfect\_square\_p} first tests the input mod 256, which means just examining the low byte. Only 44 different values occur for squares mod 256, so 82.8\% of inputs can be immediately identified as non-squares.

On a 32-bit system similar tests are done mod 9, 5, 7, 13 and 17, for a total 99.25\% of inputs identified as non-squares. On a 64-bit system 97 is tested too, for a total 99.62\%.

These moduli are chosen because they’re factors of \(2^{24} - 1\) (or \(2^{48} - 1\) for 64-bits), and such a remainder can be quickly taken just using additions (see \texttt{mpn\_mod\_34lsub1}).

When nails are in use moduli are instead selected by the \texttt{gen-psqr.c} program and applied with an \texttt{mpn\_mod\_1}. The same \(2^{24} - 1\) or \(2^{48} - 1\) could be done with nails using some extra bit shifts, but this is not currently implemented.

In any case each modulus is applied to the \texttt{mpn\_mod\_34lsub1} or \texttt{mpn\_mod\_1} remainder and a table lookup identifies non-squares. By using a “modexact” style calculation, and suitably permuted tables, just one multiply each is required, see the code for details. Moduli are also combined to save operations, so long as the lookup tables don’t become too big. \texttt{gen-psqr.c} does all the pre-calculations.

A square root must still be taken for any value that passes these tests, to verify it’s really a square and not one of the small fraction of non-squares that get through (i.e. a pseudo-square to all the tested bases).

Clearly more residue tests could be done, \texttt{mpz\_perfect\_square\_p} only uses a compact and efficient set. Big inputs would probably benefit from more residue testing, small inputs might be better off with less. The assumed distribution of squares versus non-squares in the input would affect such considerations.

15.5.4 Perfect Power

Detecting perfect powers is required by some factorization algorithms. Currently \texttt{mpz\_perfect\_power\_p} is implemented using repeated Nth root extractions, though naturally only prime roots need to be considered. (See Section 15.5.2 [Nth Root Algorithm], page 108.)

If a prime divisor \(p\) with multiplicity \(e\) can be found, then only roots which are divisors of \(e\) need to be considered, much reducing the work necessary. To this end divisibility by a set of small primes is checked.

15.6 Radix Conversion

Radix conversions are less important than other algorithms. A program dominated by conversions should probably use a different data representation.

15.6.1 Binary to Radix

Conversions from binary to a power-of-2 radix use a simple and fast \(O(N)\) bit extraction algorithm.

Conversions from binary to other radices use one of two algorithms. Sizes below \texttt{GET\_STR\_PRECOMPUTE\_THRESHOLD} use a basic \(O(N^2)\) method. Repeated divisions by \(b^n\) are made, where \(b\) is the radix and \(n\) is the biggest power that fits in a limb. But instead of simply using the remainder \(r\) from such divisions, an extra divide step is done to give a fractional limb representing \(r/b^n\). The digits of \(r\) can then be extracted using multiplications by \(b\) rather than divisions.
Special case code is provided for decimal, allowing multiplications by 10 to optimize to shifts and adds.

Above GET_STR_PRECOMPUTE_THRESHOLD a sub-quadratic algorithm is used. For an input $t$, powers $b^{n2^i}$ of the radix are calculated, until a power between $t$ and $\sqrt{t}$ is reached. $t$ is then divided by that largest power, giving a quotient which is the digits above that power, and a remainder which is those below. These two parts are in turn divided by the second highest power, and so on recursively. When a piece has been divided down to less than GET_STR_DC_THRESHOLD limbs, the basecase algorithm described above is used.

The advantage of this algorithm is that big divisions can make use of the sub-quadratic divide and conquer division (see Section 15.2.3 [Divide and Conquer Division], page 102), and big divisions tend to have less overheads than lots of separate single limb divisions anyway. But in any case the cost of calculating the powers $b^{n2^i}$ must first be overcome.

GET_STR_PRECOMPUTE_THRESHOLD and GET_STR_DC_THRESHOLD represent the same basic thing, the point where it becomes worth doing a big division to cut the input in half. GET_STR_PRECOMPUTE_THRESHOLD includes the cost of calculating the radix power required, whereas GET_STR_DC_THRESHOLD assumes that’s already available, which is the case when recursing.

Since the base case produces digits from least to most significant but they want to be stored from most to least, it’s necessary to calculate in advance how many digits there will be, or at least be sure not to underestimate that. For GMP the number of input bits is multiplied by $\text{chars\_per\_bit\_exactly}$ from $\text{mp\_bases}$, rounding up. The result is either correct or one too big.

Examining some of the high bits of the input could increase the chance of getting the exact number of digits, but an exact result every time would not be practical, since in general the difference between numbers 100... and 99... is only in the last few bits and the work to identify 99... might well be almost as much as a full conversion.

The $r/b^n$ scheme described above for using multiplications to bring out digits might be useful for more than a single limb. Some brief experiments with it on the base case when recursing didn’t give a noticeable improvement, but perhaps that was only due to the implementation. Something similar would work for the sub-quadratic divisions too, though there would be the cost of calculating a bigger radix power.

Another possible improvement for the sub-quadratic part would be to arrange for radix powers that balanced the sizes of quotient and remainder produced, i.e. the highest power would be an $b^{nk}$ approximately equal to $\sqrt{t}$, not restricted to a $2^i$ factor. That ought to smooth out a graph of times against sizes, but may or may not be a net speedup.

15.6.2 Radix to Binary

This section needs to be rewritten, it currently describes the algorithms used before GMP 4.3.

Conversions from a power-of-2 radix into binary use a simple and fast $O(N)$ bitwise concatenation algorithm.

Conversions from other radices use one of two algorithms. Sizes below SET_STR_PRECOMPUTE_THRESHOLD use a basic $O(N^2)$ method. Groups of $n$ digits are converted to limbs, where $n$ is the biggest power of the base $b$ which will fit in a limb, then those groups are accumulated into the result by multiplying by $b^n$ and adding. This saves multi-precision operations, as per Knuth section 4.4 part E (see Appendix B [References], page 128). Some special case code is provided for decimal, giving the compiler a chance to optimize multiplications by 10.
Above `SET_STR_PRECOMPUTE_THRESHOLD` a sub-quadratic algorithm is used. First groups of \( n \) digits are converted into limbs. Then adjacent limbs are combined into limb pairs with \( xb^n + y \), where \( x \) and \( y \) are the limbs. Adjacent limb pairs are combined into quads similarly with \( xb^{2n} + y \). This continues until a single block remains, that being the result.

The advantage of this method is that the multiplications for each \( x \) are big blocks, allowing Karatsuba and higher algorithms to be used. But the cost of calculating the powers \( b^{n2^i} \) must be overcome. `SET_STR_PRECOMPUTE_THRESHOLD` usually ends up quite big, around 5000 digits, and on some processors much bigger still.

`SET_STR_PRECOMPUTE_THRESHOLD` is based on the input digits (and tuned for decimal), though it might be better based on a limb count, so as to be independent of the base. But that sort of count isn’t used by the base case and so would need some sort of initial calculation or estimate.

The main reason `SET_STR_PRECOMPUTE_THRESHOLD` is so much bigger than the corresponding `GET_STR_PRECOMPUTE_THRESHOLD` is that `mpn_mul_1` is much faster than `mpn_divrem_1` (often by a factor of 5, or more).

### 15.7 Other Algorithms

#### 15.7.1 Prime Testing

The primality testing in `mpz_probab_prime_p` (see Section 5.9 [Number Theoretic Functions], page 37) first does some trial division by small factors and then uses the Miller-Rabin probabilistic primality testing algorithm, as described in Knuth section 4.5.4 algorithm P (see Appendix B [References], page 128).

For an odd input \( n \), and with \( n = q2^k + 1 \) where \( q \) is odd, this algorithm selects a random base \( x \) and tests whether \( x^q \mod n = 1 \) or \(-1\), or an \( x^{2^j} \mod n = 1 \), for \( 1 \leq j \leq k \). If so then \( n \) is probably prime, if not then \( n \) is definitely composite.

Any prime \( n \) will pass the test, but some composites do too. Such composites are known as strong pseudoprimes to base \( x \). No \( n \) is a strong pseudoprime to more than \( 1/4 \) of all bases (see Knuth exercise 22), hence with \( x \) chosen at random there’s no more than a \( 1/4 \) chance a “probable prime” will in fact be composite.

In fact strong pseudoprimes are quite rare, making the test much more powerful than this analysis would suggest, but \( 1/4 \) is all that’s proven for an arbitrary \( n \).

#### 15.7.2 Factorial

Factorials are calculated by a combination of two algorithms. An idea is shared among them: to compute the odd part of the factorial; a final step takes account of the power of 2 term, by shifting.

For small \( n \), the odd factor of \( n! \) is computed with the simple observation that it is equal to the product of all positive odd numbers smaller than \( n \) times the odd factor of \( \lfloor n/2 \rfloor! \), where \( \lfloor x \rfloor \) is the integer part of \( x \), and so on recursively. The procedure can be best illustrated with an example,

\[
23! = (23·21·19·17·15·13·11·9·7·5·3)(11·9·7·5·3)(5·3)2^{19}
\]

Current code collects all the factors in a single list, with a loop and no recursion, and compute the product, with no special care for repeated chunks.
When \( n \) is larger, computation pass through prime sieving. An helper function is used, as suggested by Peter Luschny:

\[
\text{msf}(n) = \frac{n!}{\lfloor n/2 \rfloor! \cdot 2^k} = \prod_{p=3}^{n} p^{L(p,n)}
\]

Where \( p \) ranges on odd prime numbers. The exponent \( k \) is chosen to obtain an odd integer number: \( k \) is the number of 1 bits in the binary representation of \( \lfloor n/2 \rfloor \). The function \( L(p,n) \) can be defined as zero when \( p \) is composite, and, for any prime \( p \), it is computed with:

\[
L(p,n) = \sum_{i>0} \left\lfloor \frac{n}{p^i} \right\rfloor \mod 2 \leq \log_p(n)
\]

With this helper function, we are able to compute the odd part of \( n! \) using the recursion implied by \( n! = \lfloor n/2 \rfloor! \cdot \text{msf}(n) \cdot 2^k \). The recursion stops using the small-\( n \) algorithm on some \( \lfloor n/2 \rfloor \).

Both the above algorithms use binary splitting to compute the product of many small factors. At first as many products as possible are accumulated in a single register, generating a list of factors that fit in a machine word. This list is then split into halves, and the product is computed recursively.

Such splitting is more efficient than repeated \( \times 1 \) multiplies since it forms big multiplies, allowing Karatsuba and higher algorithms to be used. And even below the Karatsuba threshold a big block of work can be more efficient for the basecase algorithm.

### 15.7.3 Binomial Coefficients

Binomial coefficients \( \binom{n}{k} \) are calculated by first arranging \( k \leq n/2 \) using \( \binom{n}{k} = \binom{n}{n-k} \) if necessary, and then evaluating the following product simply from \( i = 2 \) to \( i = k \).

\[
\binom{n}{k} = \frac{(n-k+1) \prod_{i=2}^{k} \frac{n-k+i}{i}}
\]

It’s easy to show that each denominator \( i \) will divide the product so far, so the exact division algorithm is used (see Section 15.2.5 [Exact Division], page 102).

The numerators \( n-k+i \) and denominators \( i \) are first accumulated into as many fit a limb, to save multi-precision operations, though for \( \text{mpz_bin_ui} \) this applies only to the divisors, since \( n \) is an \( \text{mpz_t} \) and \( n-k+i \) in general won’t fit in a limb at all.

### 15.7.4 Fibonacci Numbers

The Fibonacci functions \( \text{mpz_fib_ui} \) and \( \text{mpz_fib2_ui} \) are designed for calculating isolated \( F_n \) or \( F_n, F_{n-1} \) values efficiently.

For small \( n \), a table of single limb values in \( \_\_gmp\_\_\text{fib\_table} \) is used. On a 32-bit limb this goes up to \( F_{17} \), or on a 64-bit limb up to \( F_{93} \). For convenience the table starts at \( F_{-1} \).

Beyond the table, values are generated with a binary powering algorithm, calculating a pair \( F_n \) and \( F_{n-1} \) working from high to low across the bits of \( n \). The formulas used are

\[
F_{2k+1} = 4F_k^2 - F_{k-1}^2 + 2(-1)^k \\
F_{2k-1} = F_k^2 + F_{k-1}^2 \\
F_{2k} = F_{2k+1} - F_{2k-1}
\]

At each step, \( k \) is the high \( b \) bits of \( n \). If the next bit of \( n \) is 0 then \( F_{2k}, F_{2k-1} \) is used, or if it’s a 1 then \( F_{2k+1}, F_{2k} \) is used, and the process repeated until all bits of \( n \) are incorporated. Notice these formulas require just two squares per bit of \( n \).
It’d be possible to handle the first few \( n \) above the single limb table with simple additions, using the defining Fibonacci recurrence \( F_{k+1} = F_k + F_{k-1} \), but this is not done since it usually turns out to be faster for only about 10 or 20 values of \( n \), and including a block of code for just those doesn’t seem worthwhile. If they really mattered it’d be better to extend the data table.

Using a table avoids lots of calculations on small numbers, and makes small \( n \) go fast. A bigger table would make more small \( n \) go fast, it’s just a question of balancing size against desired speed. For GMP the code is kept compact, with the emphasis primarily on a good powering algorithm.

`mpz_fib2_ui` returns both \( F_n \) and \( F_{n-1} \), but `mpz_fib_ui` is only interested in \( F_n \). In this case the last step of the algorithm can become one multiply instead of two squares. One of the following two formulas is used, according as \( n \) is odd or even.

\[
F_{2k} = F_k (F_k + 2F_{k-1}) \\
F_{2k+1} = (2F_k + F_{k-1})(2F_k - F_{k-1}) + 2(-1)^k
\]

\( F_{2k+1} \) here is the same as above, just rearranged to be a multiply. For interest, the \( 2(-1)^k \) term both here and above can be applied just to the low limb of the calculation, without a carry or borrow into further limbs, which saves some code size. See comments with `mpz_fib_ui` and the internal `mpn_fib2_ui` for how this is done.

### 15.7.5 Lucas Numbers

`mpz_lucnum2_ui` derives a pair of Lucas numbers from a pair of Fibonacci numbers with the following simple formulas.

\[
L_k = F_k + 2F_{k-1} \\
L_{k-1} = 2F_k - F_{k-1}
\]

`mpz_lucnum_ui` is only interested in \( L_n \), and some work can be saved. Trailing zero bits on \( n \) can be handled with a single square each.

\[
L_{2k} = L_k^2 - 2(-1)^k
\]

And the lowest 1 bit can be handled with one multiply of a pair of Fibonacci numbers, similar to what `mpz_fib_ui` does.

\[
L_{2k+1} = 5F_{k-1}(2F_k + F_{k-1}) - 4(-1)^k
\]

### 15.7.6 Random Numbers

For the `urandomb` functions, random numbers are generated simply by concatenating bits produced by the generator. As long as the generator has good randomness properties this will produce well-distributed \( N \) bit numbers.

For the `urandomm` functions, random numbers in a range \( 0 \leq R < N \) are generated by taking values \( R \) of \( \lceil \log_2 N \rceil \) bits each until one satisfies \( R < N \). This will normally require only one or two attempts, but the attempts are limited in case the generator is somehow degenerate and produces only 1 bits or similar.

The Mersenne Twister generator is by Matsumoto and Nishimura (see Appendix B [References], page 128). It has a non-repeating period of \( 2^{19937} - 1 \), which is a Mersenne prime, hence the name of the generator. The state is 624 words of 32-bits each, which is iterated with one XOR and shift for each 32-bit word generated, making the algorithm very fast. Randomness properties are also very good and this is the default algorithm used by GMP.

Linear congruential generators are described in many text books, for instance Knuth volume 2 (see Appendix B [References], page 128). With a modulus \( M \) and parameters \( A \) and \( C \), an
integer state $S$ is iterated by the formula $S \leftarrow AS + C \mod M$. At each step the new state is a linear function of the previous, mod $M$, hence the name of the generator.

In GMP only moduli of the form $2^N$ are supported, and the current implementation is not as well optimized as it could be. Overheads are significant when $N$ is small, and when $N$ is large clearly the multiply at each step will become slow. This is not a big concern, since the Mersenne Twister generator is better in every respect and is therefore recommended for all normal applications.

For both generators the current state can be deduced by observing enough output and applying some linear algebra (over GF(2) in the case of the Mersenne Twister). This generally means raw output is unsuitable for cryptographic applications without further hashing or the like.

15.8 Assembly Coding

The assembly subroutines in GMP are the most significant source of speed at small to moderate sizes. At larger sizes algorithm selection becomes more important, but of course speedups in low level routines will still speed up everything proportionally.

Carry handling and widening multiplies that are important for GMP can’t be easily expressed in C. GCC `asm` blocks help a lot and are provided in `longlong.h`, but hand coding low level routines invariably offers a speedup over generic C by a factor of anything from 2 to 10.

15.8.1 Code Organisation

The various `mpn` subdirectories contain machine-dependent code, written in C or assembly. The `mpn/generic` subdirectory contains default code, used when there’s no machine-specific version of a particular file.

Each `mpn` subdirectory is for an ISA family. Generally 32-bit and 64-bit variants in a family cannot share code and have separate directories. Within a family further subdirectories may exist for CPU variants.

In each directory a `nails` subdirectory may exist, holding code with nails support for that CPU variant. A `NAILS_SUPPORT` directive in each file indicates the nails values the code handles. Nails code only exists where it’s faster, or promises to be faster, than plain code. There’s no effort put into nails if they’re not going to enhance a given CPU.

15.8.2 Assembly Basics

`mpn_addmul_1` and `mpn_submul_1` are the most important routines for overall GMP performance. All multiplications and divisions come down to repeated calls to these. `mpn_add_n`, `mpn_sub_n`, `mpn_lshift` and `mpn_rshift` are next most important.

On some CPUs assembly versions of the internal functions `mpn_mul_basecase` and `mpn_sqr_basecase` give significant speedups, mainly through avoiding function call overheads. They can also potentially make better use of a wide superscalar processor, as can bigger primitives like `mpn_addmul_2` or `mpn_addmul_4`.

The restrictions on overlaps between sources and destinations (see Chapter 8 [Low-level Functions], page 58) are designed to facilitate a variety of implementations. For example, knowing `mpn_add_n` won’t have partly overlapping sources and destination means reading can be done far ahead of writing on superscalar processors, and loops can be vectorized on a vector processor, depending on the carry handling.
15.8.3 Carry Propagation

The problem that presents most challenges in GMP is propagating carries from one limb to the next. In functions like \texttt{mpn\_addmul\_1} and \texttt{mpn\_add\_n}, carries are the only dependencies between limb operations.

On processors with carry flags, a straightforward CISC style \texttt{adc} is generally best. AMD K6 \texttt{mpn\_addmul\_1} however is an example of an unusual set of circumstances where a branch works out better.

On RISC processors generally an add and compare for overflow is used. This sort of thing can be seen in \texttt{mpn/generic/aors\_n.c}. Some carry propagation schemes require 4 instructions, meaning at least 4 cycles per limb, but other schemes may use just 1 or 2. On wide superscalar processors performance may be completely determined by the number of dependent instructions between carry-in and carry-out for each limb.

On vector processors good use can be made of the fact that a carry bit only very rarely propagates more than one limb. When adding a single bit to a limb, there’s only a carry out if that limb was \texttt{0xFF...FF} which on random data will be only 1 in \texttt{2^{mp\_bits\_per\_limb}}. \texttt{mpn/cray/add\_n.c} is an example of this, it adds all limbs in parallel, adds one set of carry bits in parallel and then only rarely needs to fall through to a loop propagating further carries.

On the x86s, GCC (as of version 2.95.2) doesn’t generate particularly good code for the RISC style idioms that are necessary to handle carry bits in C. Often conditional jumps are generated where \texttt{adc} or \texttt{sbb} forms would be better. And so unfortunately almost any loop involving carry bits needs to be coded in assembly for best results.

15.8.4 Cache Handling

GMP aims to perform well both on operands that fit entirely in L1 cache and those which don’t.

Basic routines like \texttt{mpn\_add\_n} or \texttt{mpn\_lshift} are often used on large operands, so L2 and main memory performance is important for them. \texttt{mpn\_mul\_1} and \texttt{mpn\_addmul\_1} are mostly used for multiply and square basecases, so L1 performance matters most for them, unless assembly versions of \texttt{mpn\_mul\_basecase} and \texttt{mpn\_sqr\_basecase} exist, in which case the remaining uses are mostly for larger operands.

For L2 or main memory operands, memory access times will almost certainly be more than the calculation time. The aim therefore is to maximize memory throughput, by starting a load of the next cache line while processing the contents of the previous one. Clearly this is only possible if the chip has a lock-up free cache or some sort of prefetch instruction. Most current chips have both these features.

Prefetching sources combines well with loop unrolling, since a prefetch can be initiated once per unrolled loop (or more than once if the loop covers more than one cache line).

On CPUs without write-allocate caches, prefetching destinations will ensure individual stores don’t go further down the cache hierarchy, limiting bandwidth. Of course for calculations which are slow anyway, like \texttt{mpn\_divrem\_1}, write-throughs might be fine.

The distance ahead to prefetch will be determined by memory latency versus throughput. The aim of course is to have data arriving continuously, at peak throughput. Some CPUs have limits on the number of fetches or prefetches in progress.

If a special prefetch instruction doesn’t exist then a plain load can be used, but in that case care must be taken not to attempt to read past the end of an operand, since that might produce a segmentation violation.
Some CPUs or systems have hardware that detects sequential memory accesses and initiates suitable cache movements automatically, making life easy.

### 15.8.5 Functional Units

When choosing an approach for an assembly loop, consideration is given to what operations can execute simultaneously and what throughput can thereby be achieved. In some cases an algorithm can be tweaked to accommodate available resources.

Loop control will generally require a counter and pointer updates, costing as much as 5 instructions, plus any delays a branch introduces. CPU addressing modes might reduce pointer updates, perhaps by allowing just one updating pointer and others expressed as offsets from it, or on CISC chips with all addressing done with the loop counter as a scaled index.

The final loop control cost can be amortised by processing several limbs in each iteration (see Section 15.8.9 [Assembly Loop Unrolling], page 118). This at least ensures loop control isn’t a big fraction the work done.

Memory throughput is always a limit. If perhaps only one load or one store can be done per cycle then 3 cycles/limb will the top speed for “binary” operations like `mpn_add_n`, and any code achieving that is optimal.

Integer resources can be freed up by having the loop counter in a float register, or by pressing the float units into use for some multiplying, perhaps doing every second limb on the float side (see Section 15.8.6 [Assembly Floating Point], page 116).

Float resources can be freed up by doing carry propagation on the integer side, or even by doing integer to float conversions in integers using bit twiddling.

### 15.8.6 Floating Point

Floating point arithmetic is used in GMP for multiplications on CPUs with poor integer multipliers. It’s mostly useful for `mpn_mul_1`, `mpn_addmul_1` and `mpn_submul_1` on 64-bit machines, and `mpn_mul_basecase` on both 32-bit and 64-bit machines.

With IEEE 53-bit double precision floats, integer multiplications producing up to 53 bits will give exact results. Breaking a $64 \times 64$ multiplication into eight $16 \times 32 \rightarrow 48$ bit pieces is convenient. With some care though six $21 \times 32 \rightarrow 53$ bit products can be used, if one of the lower two 21-bit pieces also uses the sign bit.

For the `mpn_mul_1` family of functions on a 64-bit machine, the invariant single limb is split at the start, into 3 or 4 pieces. Inside the loop, the bignum operand is split into 32-bit pieces. Fast conversion of these unsigned 32-bit pieces to floating point is highly machine-dependent. In some cases, reading the data into the integer unit, zero-extending to 64-bits, then transferring to the floating point unit back via memory is the only option.

Converting partial products back to 64-bit limbs is usually best done as a signed conversion. Since all values are smaller than $2^{53}$, signed and unsigned are the same, but most processors lack unsigned conversions.

Here is a diagram showing $16 \times 32$ bit products for an `mpn_mul_1` or `mpn_addmul_1` with a 64-bit limb. The single limb operand V is split into four 16-bit parts. The multi-limb operand U is split in the loop into two 32-bit parts.
p32 and r32 can be summed using floating-point addition, and likewise p48 and r48. p00 and
p16 can be summed with r64 and r80 from the previous iteration.

For each loop then, four 49-bit quantities are transferred to the integer unit, aligned as follows,

\[
\begin{array}{c}
\text{p00} + r64' \\
\text{p16} + r80' \\
\text{p32} + r32 \\
\text{p48} + r48
\end{array}
\]

The challenge then is to sum these efficiently and add in a carry limb, generating a low 64-bit
result limb and a high 33-bit carry limb (i48 extends 33 bits into the high half).

15.8.7 SIMD Instructions

The single-instruction multiple-data support in current microprocessors is aimed at signal pro-
cessing algorithms where each data point can be treated more or less independently. There’s
generally not much support for propagating the sort of carries that arise in GMP.

SIMD multiplications of say four 16×16 bit multiplies only do as much work as one 32×32 from
GMP’s point of view, and need some shifts and adds besides. But of course if say the SIMD
form is fully pipelined and uses less instruction decoding then it may still be worthwhile.

On the x86 chips, MMX has so far found a use in mpn_rshift and mpn_lshift, and is used in a
special case for 16-bit multipliers in the P55 mpn_mul_1. SSE2 is used for Pentium 4 mpn_mul_1,
mpn_addmul_1, and mpn_submul_1.

15.8.8 Software Pipelining

Software pipelining consists of scheduling instructions around the branch point in a loop. For
example a loop might issue a load not for use in the present iteration but the next, thereby
allowing extra cycles for the data to arrive from memory.

Naturally this is wanted only when doing things like loads or multiplies that take several cycles
to complete, and only where a CPU has multiple functional units so that other work can be
done in the meantime.

A pipeline with several stages will have a data value in progress at each stage and each loop
iteration moves them along one stage. This is like juggling.
If the latency of some instruction is greater than the loop time then it will be necessary to unroll, so one register has a result ready to use while another (or multiple others) are still in progress. (see Section 15.8.9 [Assembly Loop Unrolling], page 118).

15.8.9 Loop Unrolling

Loop unrolling consists of replicating code so that several limbs are processed in each loop. At a minimum this reduces loop overheads by a corresponding factor, but it can also allow better register usage, for example alternately using one register combination and then another. Judicious use of m4 macros can help avoid lots of duplication in the source code.

Any amount of unrolling can be handled with a loop counter that’s decremented by N each time, stopping when the remaining count is less than the further N the loop will process. Or by subtracting N at the start, the termination condition becomes when the counter C is less than 0 (and the count of remaining limbs is C + N).

Alternately for a power of 2 unroll the loop count and remainder can be established with a shift and mask. This is convenient if also making a computed jump into the middle of a large loop.

The limbs not a multiple of the unrolling can be handled in various ways, for example

- A simple loop at the end (or the start) to process the excess. Care will be wanted that it isn’t too much slower than the unrolled part.
- A set of binary tests, for example after an 8-limb unrolling, test for 4 more limbs to process, then a further 2 more or not, and finally 1 more or not. This will probably take more code space than a simple loop.
- A switch statement, providing separate code for each possible excess, for example an 8-limb unrolling would have separate code for 0 remaining, 1 remaining, etc, up to 7 remaining. This might take a lot of code, but may be the best way to optimize all cases in combination with a deep pipelined loop.
- A computed jump into the middle of the loop, thus making the first iteration handle the excess. This should make times smoothly increase with size, which is attractive, but setups for the jump and adjustments for pointers can be tricky and could become quite difficult in combination with deep pipelining.

15.8.10 Writing Guide

This is a guide to writing software pipelined loops for processing limb vectors in assembly.

First determine the algorithm and which instructions are needed. Code it without unrolling or scheduling, to make sure it works. On a 3-operand CPU try to write each new value to a new register, this will greatly simplify later steps.

Then note for each instruction the functional unit and/or issue port requirements. If an instruction can use either of two units, like U0 or U1 then make a category “U0/U1”. Count the total using each unit (or combined unit), and count all instructions.

Figure out from those counts the best possible loop time. The goal will be to find a perfect schedule where instruction latencies are completely hidden. The total instruction count might be the limiting factor, or perhaps a particular functional unit. It might be possible to tweak the instructions to help the limiting factor.

Suppose the loop time is N, then make N issue buckets, with the final loop branch at the end of the last. Now fill the buckets with dummy instructions using the functional units desired. Run this to make sure the intended speed is reached.
Now replace the dummy instructions with the real instructions from the slow but correct loop you started with. The first will typically be a load instruction. Then the instruction using that value is placed in a bucket an appropriate distance down. Run the loop again, to check it still runs at target speed.

Keep placing instructions, frequently measuring the loop. After a few you will need to wrap around from the last bucket back to the top of the loop. If you used the new-register for new-value strategy above then there will be no register conflicts. If not then take care not to clobber something already in use. Changing registers at this time is very error prone.

The loop will overlap two or more of the original loop iterations, and the computation of one vector element result will be started in one iteration of the new loop, and completed one or several iterations later.

The final step is to create feed-in and wind-down code for the loop. A good way to do this is to make a copy (or copies) of the loop at the start and delete those instructions which don’t have valid antecedents, and at the end replicate and delete those whose results are unwanted (including any further loads).

The loop will have a minimum number of limbs loaded and processed, so the feed-in code must test if the request size is smaller and skip either to a suitable part of the wind-down or to special code for small sizes.
16 Internals

This chapter is provided only for informational purposes and the various internals described here may change in future GMP releases. Applications expecting to be compatible with future releases should use only the documented interfaces described in previous chapters.

16.1 Integer Internals

mpz_t variables represent integers using sign and magnitude, in space dynamically allocated and reallocated. The fields are as follows.

_mp_size The number of limbs, or the negative of that when representing a negative integer. Zero is represented by _mp_size set to zero, in which case the _mp_d data is undefined.

_mp_d A pointer to an array of limbs which is the magnitude. These are stored “little endian” as per the mpn functions, so _mp_d[0] is the least significant limb and _mp_d[ABS(_mp_size)-1] is the most significant. Whenever _mp_size is non-zero, the most significant limb is non-zero.

Currently there’s always at least one readable limb, so for instance mpz_get_ui can fetch _mp_d[0] unconditionally (though its value is undefined if _mp_size is zero).

_mp_alloc _mp_alloc is the number of limbs currently allocated at _mp_d, and normally _mp_alloc >= ABS(_mp_size). When an mpz routine is about to (or might be about to) increase _mp_size, it checks _mp_alloc to see whether there’s enough space, and reallocates if not. MPZ_REALLOC is generally used for this.

mpz_t variables initialised with the mpz_roinit_n function or the MPZ_ROINIT_N macro have _mp_alloc = 0 but can have a non-zero _mp_size. They can only be used as read-only constants. See Section 5.16 [Integer Special Functions], page 44 for details.

The various bitwise logical functions like mpz_and behave as if negative values were twos complement. But sign and magnitude is always used internally, and necessary adjustments are made during the calculations. Sometimes this isn’t pretty, but sign and magnitude are best for other routines.

Some internal temporary variables are setup with MPZ_TMP_INIT and these have _mp_d space obtained from TMP_ALLOC rather than the memory allocation functions. Care is taken to ensure that these are big enough that no reallocation is necessary (since it would have unpredictable consequences).

_mp_size and _mp_alloc are int, although mp_size_t is usually a long. This is done to make the fields just 32 bits on some 64 bits systems, thereby saving a few bytes of data space but still providing plenty of range.

16.2 Rational Internals

mpq_t variables represent rationals using an mpz_t numerator and denominator (see Section 16.1 [Integer Internals], page 120).

The canonical form adopted is denominator positive (and non-zero), no common factors between numerator and denominator, and zero uniquely represented as 0/1.

It’s believed that casting out common factors at each stage of a calculation is best in general. A GCD is an $O(N^2)$ operation so it’s better to do a few small ones immediately than to delay and
have to do a big one later. Knowing the numerator and denominator have no common factors can be used for example in \texttt{mpq\_mul} to make only two cross GCDs necessary, not four.

This general approach to common factors is badly sub-optimal in the presence of simple factorizations or little prospect for cancellation, but GMP has no way to know when this will occur. As per Section 3.11 [Efficiency], page 22, that’s left to applications. The \texttt{mpq\_t} framework might still suit, with \texttt{mpq\_numref} and \texttt{mpq\_denref} for direct access to the numerator and denominator, or of course \texttt{mpz\_t} variables can be used directly.

### 16.3 Float Internals

Efficient calculation is the primary aim of GMP floats and the use of whole limbs and simple rounding facilitates this. \texttt{mpf\_t} floats have a variable precision mantissa and a single machine word signed exponent. The mantissa is represented using sign and magnitude.

\[
\begin{array}{c}
\text{most significant limb} \quad \text{least significant limb} \\
\hline
\_mp\_exp \quad \_mp\_d \\
\end{array}
\]

\[
\text{\_mp\_size} \quad \text{\_mp\_exp} \quad \text{\_mp\_d} \quad \text{\_mp\_size} \quad \text{\_mp\_exp} \quad \text{\_mp\_d}
\]

\[
\_mp\_size \quad \_mp\_exp \quad \_mp\_d \\
\rightarrow \quad \text{\_mp\_size} \quad \text{\_mp\_exp} \quad \text{\_mp\_d}
\]

The fields are as follows.

- **\_mp\_size**: The number of limbs currently in use, or the negative of that when representing a negative value. Zero is represented by \_mp\_size and \_mp\_exp both set to zero, and in that case the \_mp\_d data is unused. (In the future \_mp\_exp might be undefined when representing zero.)

- **\_mp\_prec**: The precision of the mantissa, in limbs. In any calculation the aim is to produce \_mp\_prec limbs of result (the most significant being non-zero).

- **\_mp\_d**: A pointer to the array of limbs which is the absolute value of the mantissa. These are stored “little endian” as per the \texttt{mpn} functions, so \_mp\_d[0] is the least significant limb and \_mp\_d[\text{ABS(\_mp\_size)}-1] the most significant.

The most significant limb is always non-zero, but there are no other restrictions on its value, in particular the highest 1 bit can be anywhere within the limb. \_mp\_prec+1 limbs are allocated to \_mp\_d, the extra limb being for convenience (see below). There are no reallocations during a calculation, only in a change of precision with \texttt{mpf\_set\_prec}.

- **\_mp\_exp**: The exponent, in limbs, determining the location of the implied radix point. Zero means the radix point is just above the most significant limb. Positive values mean a radix point offset towards the lower limbs and hence a value \( \geq 1 \), as for example in the diagram above. Negative exponents mean a radix point further above the highest limb.

Naturally the exponent can be any value, it doesn’t have to fall within the limbs as the diagram shows, it can be a long way above or a long way below. Limbs other than those included in the \{\_mp\_d, \_mp\_size\} data are treated as zero.

The \_mp\_size and \_mp\_prec fields are \texttt{int}, although the \texttt{mp\_size\_t} type is usually a \texttt{long}. The \_mp\_exp field is usually \texttt{long}. This is done to make some fields just 32 bits on some 64 bits systems, thereby saving a few bytes of data space but still providing plenty of precision and a very large range.
The following various points should be noted.

Low Zeros The least significant limbs \_mp_d[0] etc can be zero, though such low zeros can always be ignored. Routines likely to produce low zeros check and avoid them to save time in subsequent calculations, but for most routines they’re quite unlikely and aren’t checked.

Mantissa Size Range
The \_mp_size count of limbs in use can be less than \_mp_prec if the value can be represented in less. This means low precision values or small integers stored in a high precision mpf_t can still be operated on efficiently.
\_mp_size can also be greater than \_mp_prec. Firstly a value is allowed to use all of the \_mp_prec+1 limbs available at \_mp_d, and secondly when mpf_set_prec_raw lowers \_mp_prec it leaves \_mp_size unchanged and so the size can be arbitrarily bigger than \_mp_prec.

Rounding All rounding is done on limb boundaries. Calculating \_mp_prec limbs with the high non-zero will ensure the application requested minimum precision is obtained. The use of simple “trunc” rounding towards zero is efficient, since there’s no need to examine extra limbs and increment or decrement.

Bit Shifts Since the exponent is in limbs, there are no bit shifts in basic operations like mpf_add and mpf_mul. When differing exponents are encountered all that’s needed is to adjust pointers to line up the relevant limbs.
Of course mpf_mul_2exp and mpf_div_2exp will require bit shifts, but the choice is between an exponent in limbs which requires shifts there, or one in bits which requires them almost everywhere else.

Use of \_mp_prec+1 Limbs
The extra limb on \_mp_d (\_mp_prec+1 rather than just \_mp_prec) helps when an mpf routine might get a carry from its operation. mpf_add for instance will do an mpn_add of \_mp_prec limbs. If there’s no carry then that’s the result, but if there is a carry then it’s stored in the extra limb of space and \_mp_size becomes \_mp_prec+1.
Whenever \_mp_prec+1 limbs are held in a variable, the low limb is not needed for the intended precision, only the \_mp_prec high limbs. But zeroing it out or moving the rest down is unnecessary. Subsequent routines reading the value will simply take the high limbs they need, and this will be \_mp_prec if their target has that same precision. This is no more than a pointer adjustment, and must be checked anyway since the destination precision can be different from the sources.
Copy functions like mpf_set will retain a full \_mp_prec+1 limbs if available. This ensures that a variable which has \_mp_size equal to \_mp_prec+1 will get its full exact value copied. Strictly speaking this is unnecessary since only \_mp_prec limbs are needed for the application’s requested precision, but it’s considered that an mpf_set from one variable into another of the same precision ought to produce an exact copy.

Application Precisions
\_GMPF_BITS_TO_PREC converts an application requested precision to an \_mp_prec. The value in bits is rounded up to a whole limb then an extra limb is added since the most significant limb of \_mp_d is only non-zero and therefore might contain only one bit.
\_GMPF_PREC_TO_BITS does the reverse conversion, and removes the extra limb from \_mp_prec before converting to bits. The net effect of reading back with mpf_get_prec is simply the precision rounded up to a multiple of mp_bits_per_limb.
Note that the extra limb added here for the high only being non-zero is in addition to the extra limb allocated to _mp_d. For example with a 32-bit limb, an application request for 250 bits will be rounded up to 8 limbs, then an extra added for the high being only non-zero, giving an _mp_prec of 9. _mp_d then gets 10 limbs allocated. Reading back with mpf_get_prec will take _mp_prec subtract 1 limb and multiply by 32, giving 256 bits.

Strictly speaking, the fact the high limb has at least one bit means that a float with, say, 3 limbs of 32-bits each will be holding at least 65 bits, but for the purposes of mpf_t it’s considered simply to be 64 bits, a nice multiple of the limb size.

16.4 Raw Output Internals

mpz_out_raw uses the following format.

<table>
<thead>
<tr>
<th>size</th>
<th>data bytes</th>
</tr>
</thead>
</table>

The size is 4 bytes written most significant byte first, being the number of subsequent data bytes, or the twos complement negative of that when a negative integer is represented. The data bytes are the absolute value of the integer, written most significant byte first.

The most significant data byte is always non-zero, so the output is the same on all systems, irrespective of limb size.

In GMP 1, leading zero bytes were written to pad the data bytes to a multiple of the limb size. mpz_inp_raw will still accept this, for compatibility.

The use of “big endian” for both the size and data fields is deliberate, it makes the data easy to read in a hex dump of a file. Unfortunately it also means that the limb data must be reversed when reading or writing, so neither a big endian nor little endian system can just read and write _mp_d.

16.5 C++ Interface Internals

A system of expression templates is used to ensure something like a=b+c turns into a simple call to mpz_add etc. For mpf_class the scheme also ensures the precision of the final destination is used for any temporaries within a statement like f=w*x+y*z. These are important features which a naive implementation cannot provide.

A simplified description of the scheme follows. The true scheme is complicated by the fact that expressions have different return types. For detailed information, refer to the source code.

To perform an operation, say, addition, we first define a “function object” evaluating it,

```c
struct __gmp_binary_plus
{
    static void eval(mpf_t f, const mpf_t g, const mpf_t h)
    {
        mpf_add(f, g, h);
    }
};
```

And an “additive expression” object,

```c
__gmp_expr<__gmp_binary_expr<mpf_class, mpf_class, __gmp_binary_plus> > operator+(const mpf_class &f, const mpf_class &g)
{```
return __gmp_expr
  <__gmp_binary_expr<mpf_class, mpf_class, __gmp_binary_plus> >(f, g);
}

The seemingly redundant __gmp_expr<__gmp_binary_expr<...>> is used to encapsulate any possible kind of expression into a single template type. In fact even mpf_class etc are typedef specializations of __gmp_expr.

Next we define assignment of __gmp_expr to mpf_class.

template <class T>
mpf_class & mpf_class::operator=(const __gmp_expr<T> &expr)
{
  expr.eval(this->get_mpf_t(), this->precision());
  return *this;
}

template <class Op>
void __gmp_expr<__gmp_binary_expr<mpf_class, mpf_class, Op> >::eval
(mpf_t f, mp_bitcnt_t precision)
{
  Op::eval(f, expr.val1.get_mpf_t(), expr.val2.get_mpf_t());
}

where expr.val1 and expr.val2 are references to the expression's operands (here expr is the __gmp_binary_expr stored within the __gmp_expr).

This way, the expression is actually evaluated only at the time of assignment, when the required precision (that of f) is known. Furthermore the target mpf_t is now available, thus we can call mpf_add directly with f as the output argument.

Compound expressions are handled by defining operators taking subexpressions as their arguments, like this:

template <class T, class U>
__gmp_expr
  <__gmp_binary_expr<__gmp_expr<T>, __gmp_expr<U>, __gmp_binary_plus> >
operator+(const __gmp_expr<T> &expr1, const __gmp_expr<U> &expr2)
{
  return __gmp_expr
    <__gmp_binary_expr<__gmp_expr<T>, __gmp_expr<U>, __gmp_binary_plus> >
      (expr1, expr2);
}

And the corresponding specializations of __gmp_expr::eval:

template <class T, class U, class Op>
void __gmp_expr
  <__gmp_binary_expr<__gmp_expr<T>, __gmp_expr<U>, Op> >::eval
(mpf_t f, mp_bitcnt_t precision)
{
  // declare two temporaries
  mpf_class temp1(expr.val1, precision), temp2(expr.val2, precision);
  Op::eval(f, temp1.get_mpf_t(), temp2.get_mpf_t());
}
The expression is thus recursively evaluated to any level of complexity and all subexpressions are evaluated to the precision of f.
Appendix A Contributors

Torbjörn Granlund wrote the original GMP library and is still the main developer. Code not explicitly attributed to others, was contributed by Torbjörn. Several other individuals and organizations have contributed GMP. Here is a list in chronological order on first contribution:

Gunnar Sjödin and Hans Riesel helped with mathematical problems in early versions of the library.

Richard Stallman helped with the interface design and revised the first version of this manual.

Brian Beuning and Doug Lea helped with testing of early versions of the library and made creative suggestions.

John Amanatides of York University in Canada contributed the function `mpz_probab_prime_p`.

Paul Zimmermann wrote the REDC-based `mpz_powm` code, the Schönhage-Strassen FFT multiply code, and the Karatsuba square root code. He also improved the Toom3 code for GMP 4.2. Paul sparked the development of GMP 2, with his comparisons between bignum packages. The ECMNET project Paul is organizing was a driving force behind many of the optimizations in GMP 3. Paul also wrote the new GMP 4.3 nth root code (with Torbjörn).

Ken Weber (Kent State University, Universidade Federal do Rio Grande do Sul) contributed now defunct versions of `mpz_gcd`, `mpz_divexact`, `mpn_gcd`, and `mpn_bdivmod`, partially supported by CNPq (Brazil) grant 301314194-2.

Per Bothner of Cygnus Support helped to set up GMP to use Cygnus’ configure. He has also made valuable suggestions and tested numerous intermediary releases.

Joachim Hollman was involved in the design of the `mpf` interface, and in the `mpz` design revisions for version 2.

Bennet Yee contributed the initial versions of `mpz_jacobi` and `mpz_legendre`.

Andreas Schwab contributed the files `mpn/m68k/lshift.S` and `mpn/m68k/rshift.S` (now in `.asm` form).

Robert Harley of Inria, France and David Seal of ARM, England, suggested clever improvements for population count. Robert also wrote highly optimized Karatsuba and 3-way Toom multiplication functions for GMP 3, and contributed the ARM assembly code.

Torsten Ekedahl of the Mathematical department of Stockholm University provided significant inspiration during several phases of the GMP development. His mathematical expertise helped improve several algorithms.

Linus Nordberg wrote the new configure system based on autoconf and implemented the new random functions.

Kevin Ryde worked on a large number of things: optimized x86 code, `m4`asm macros, parameter tuning, speed measuring, the configure system, function inlining, divisibility tests, bit scanning, Jacobi symbols, Fibonacci and Lucas number functions, printf and scanf functions, perl interface, demo expression parser, the algorithms chapter in the manual, `gmpasm-mode.el`, and various miscellaneous improvements elsewhere.

Kent Boortz made the Mac OS 9 port.

Steve Root helped write the optimized alpha 21264 assembly code.

Gerardo Ballabio wrote the `gmpxx.h` C++ class interface and the C++ `istream` input routines.
Appendix A: Contributors

Jason Moxham rewrote `mpz_fac_ui`.

Pedro Gimeno implemented the Mersenne Twister and made other random number improvements.

Niels Möller wrote the sub-quadratic GCD, extended GCD and jacobi code, the quadratic Hensel division code, and (with Torbjörn) the new divide and conquer division code for GMP 4.3. Niels also helped implement the new Toom multiply code for GMP 4.3 and implemented helper functions to simplify Toom evaluations for GMP 5.0. He wrote the original version of `mpn_mulmod_bnm1`, and he is the main author of the mini-gmp package used for gmp bootstrapping.

Alberto Zanoni and Marco Bodrato suggested the unbalanced multiply strategy, and found the optimal strategies for evaluation and interpolation in Toom multiplication.

Marco Bodrato helped implement the new Toom multiply code for GMP 4.3 and implemented most of the new Toom multiply and squaring code for 5.0. He is the main author of the current `mpn_mulmod_bnm1`, `mpn_mullo_n`, and `mpn_sqrlo`. Marco also wrote the functions `mpn_invert` and `mpn_invertappr`, and improved the speed of integer root extraction. He is the author of mini-mpq, an additional layer to mini-gmp: of most of the combinatorial functions and the BPSW primality testing implementation, for both the main library and the mini-gmp package.

David Harvey suggested the internal function `mpn_bdiv_dbm1`, implementing division relevant to Toom multiplication. He also worked on fast assembly sequences, in particular on a fast AMD64 `mpn_mul_basecase`. He wrote the internal middle product functions `mpn_mulmid_basecase`, `mpn_toom42_mulmid`, `mpn_mulmid_n` and related helper routines.

Martin Boij wrote `mpn_perfect_power_p`.

Marc Glisse improved `gmpxx.h`: use fewer temporaries (faster), specializations of `numeric_limits` and `common_type`, C++11 features (move constructors, explicit bool conversion, UDL), make the conversion from `mpq_class` to `mpz_class` explicit, optimize operations where one argument is a small compile-time constant, replace some heap allocations by stack allocations. He also fixed the eofbit handling of C++ streams, and removed one division from `mpq/aors.c`.

David S Miller wrote assembly code for SPARC T3 and T4.

Mark Sofroniou cleaned up the types of `mul_fft.c`, letting it work for huge operands.

Ulrich Weigand ported GMP to the powerpc64le ABI.

(This list is chronological, not ordered after significance. If you have contributed to GMP but are not listed above, please tell gmp-devel@gmplib.org about the omission!)

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The development of GMP 2, 3, and 4.0 was supported in part by the IDA Center for Computing Sciences.

The development of GMP 4.3, 5.0, and 5.1 was supported in part by the Swedish Foundation for Strategic Research.

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Appendix B References

B.1 Books

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